



Probabilistic Logic Programming with Fusemate: Main Ideas and Recent Developments

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CSIRO/Data61 (StatML)

ANU CECC

About

- PhD in 1996 in Germany, on Automated Reasoning
- NICTA 2005, CSIRO since 2014

Research Interest

Knowledge representation and reasoning

Designing inference systems

Applications

Recently

Probabilistic Logic Programming (PLP)

Combination with LLM (with Lachlan McGinness)

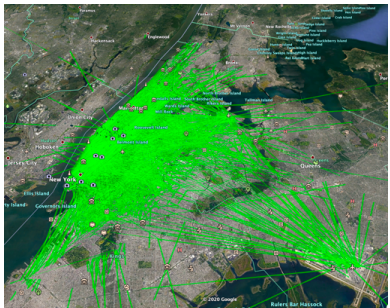
D61 Applications



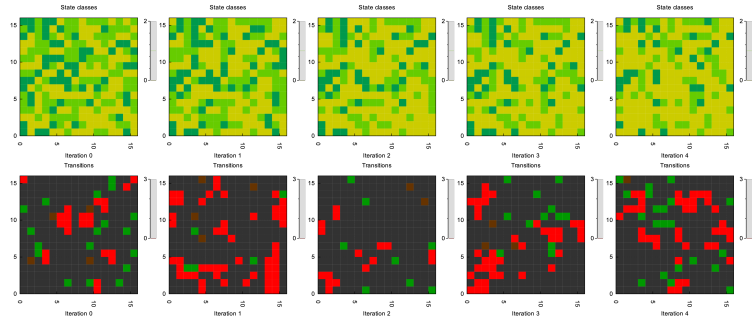
Computer Factory



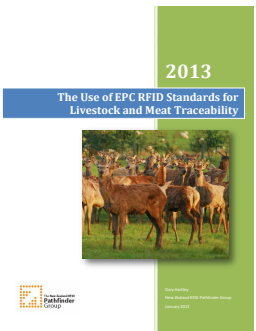
Factory floor



Taxi rides in NYC



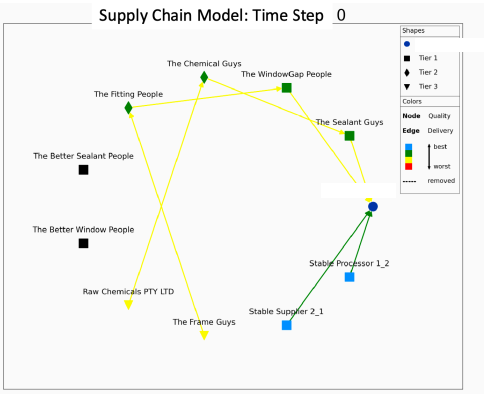
Valuing Sustainability - Future states



Food supply chain



Beef supply chain



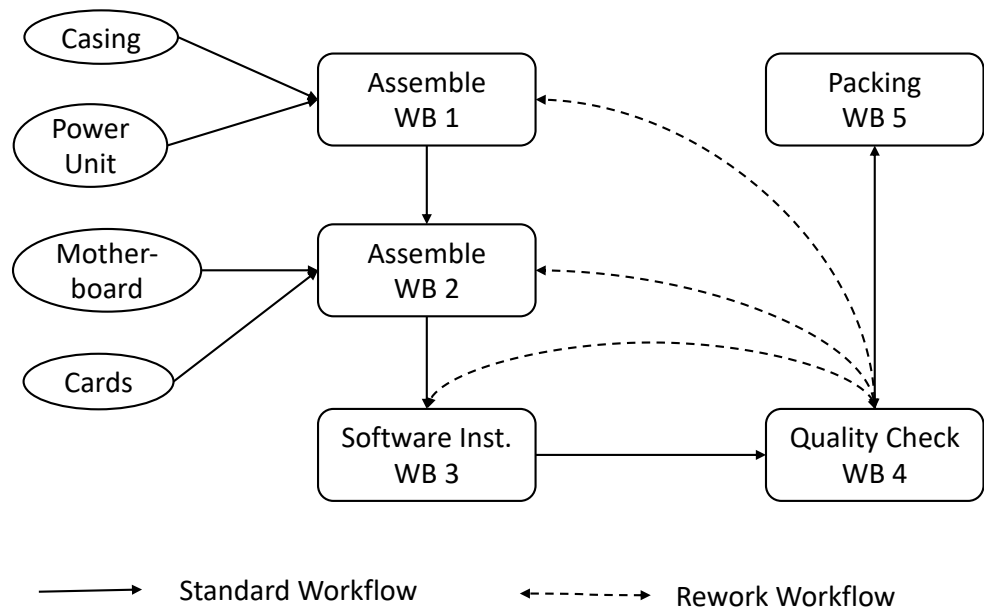
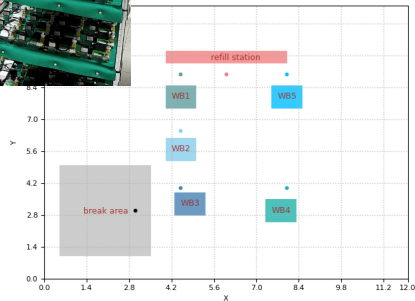
Factory supply chain

States - Transitions - Uncertainty

TLDR; Computer Factory Example (FDMF)



Computer
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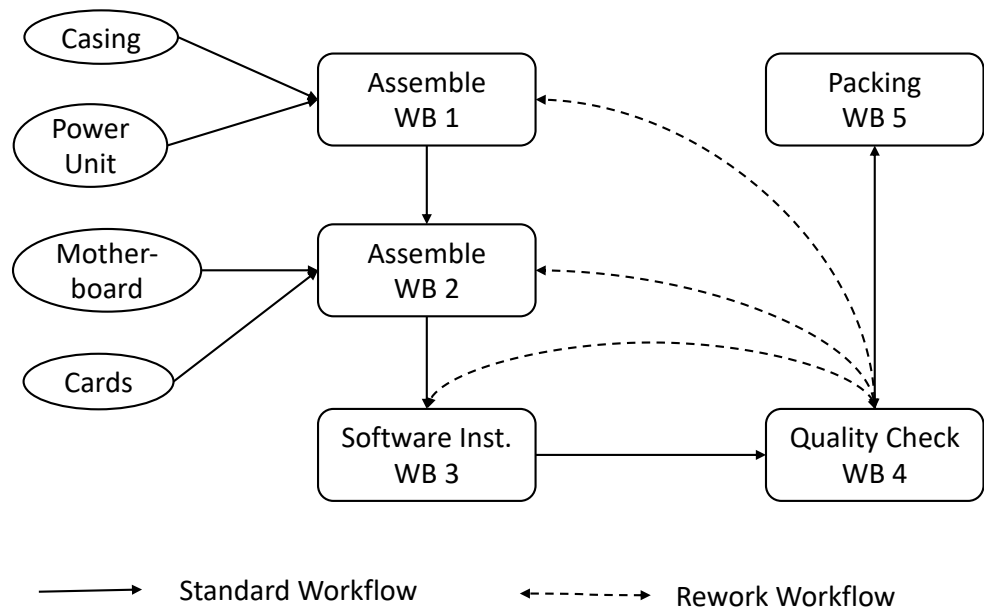
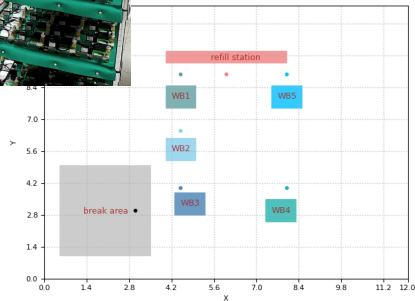
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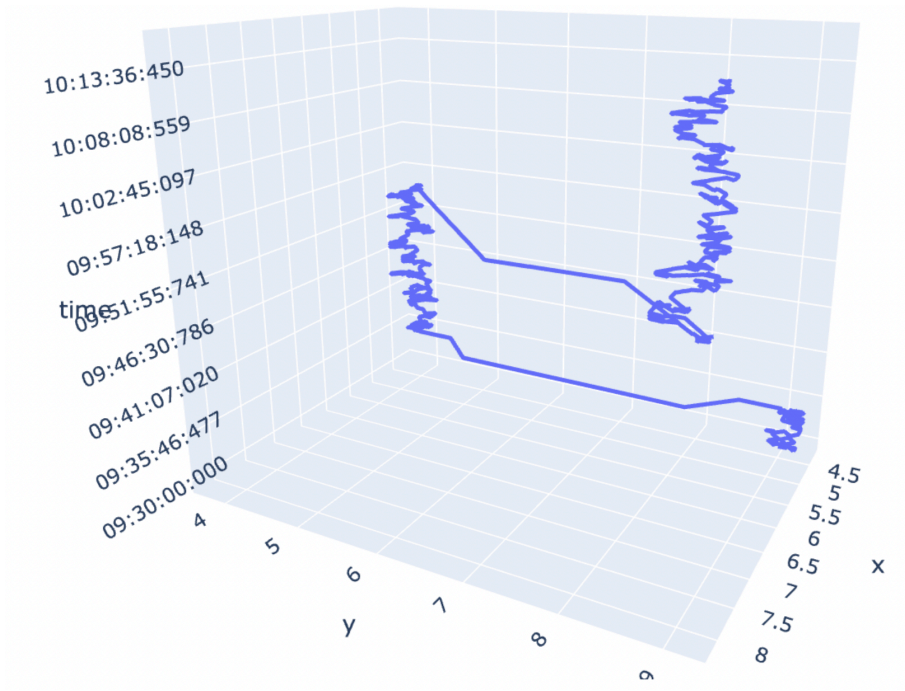
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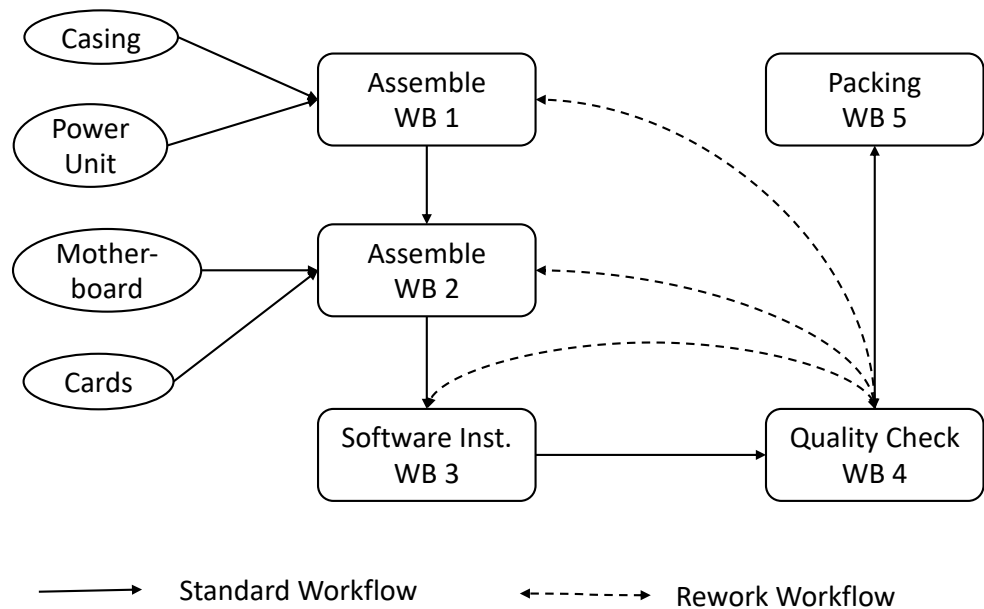
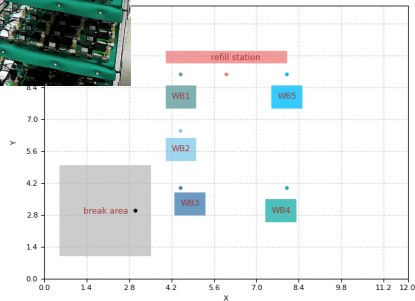
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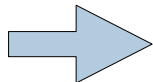
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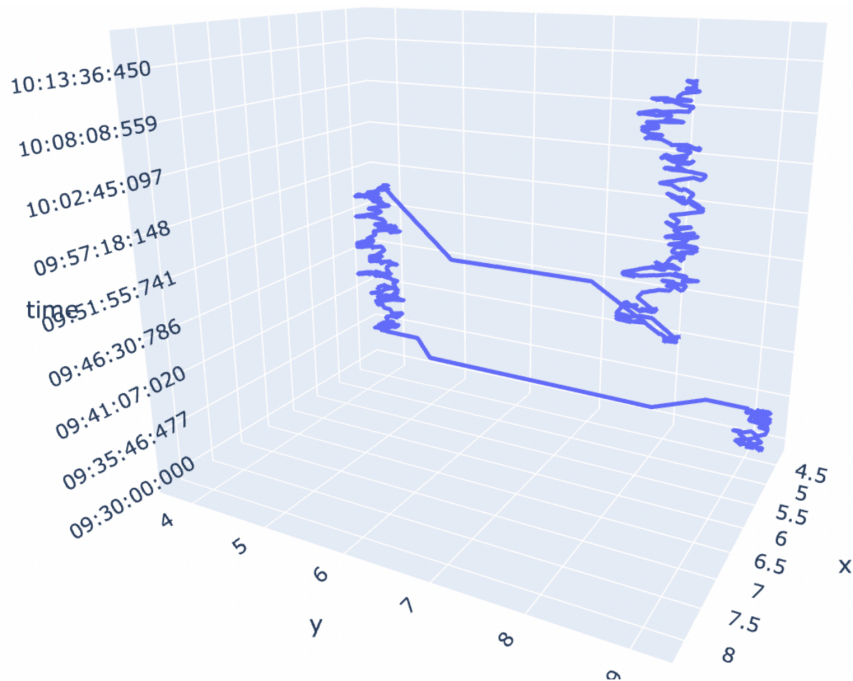
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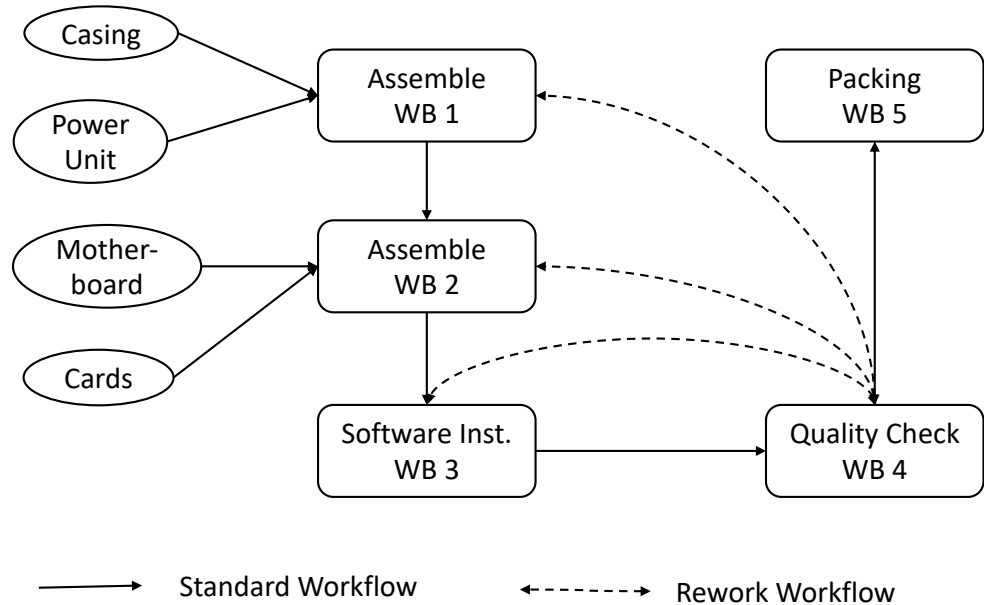
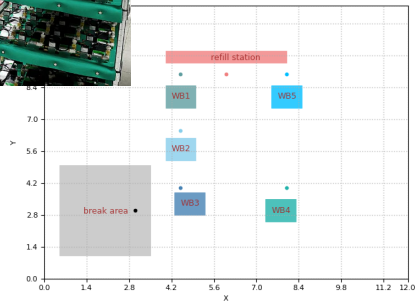
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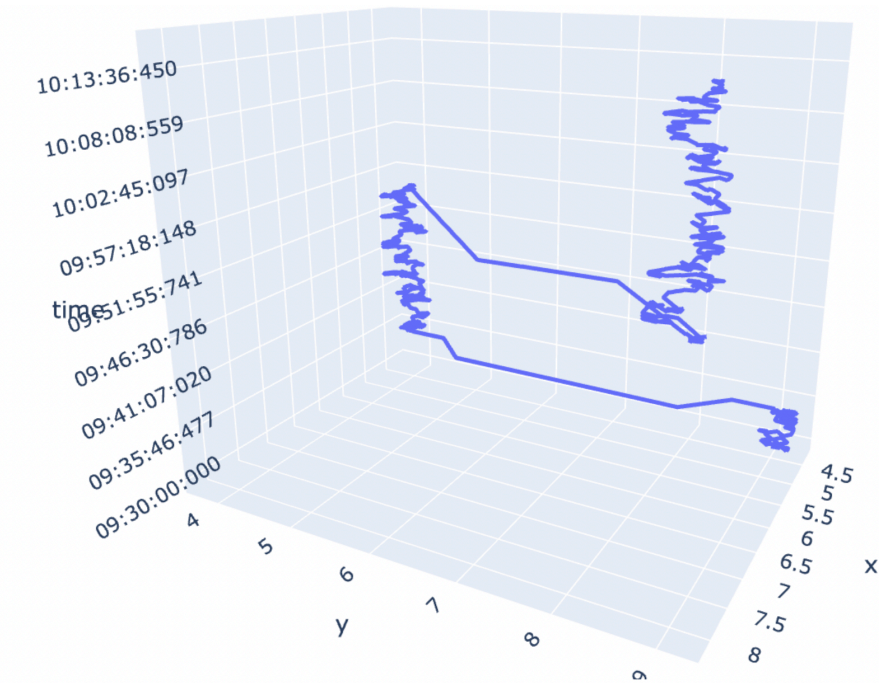
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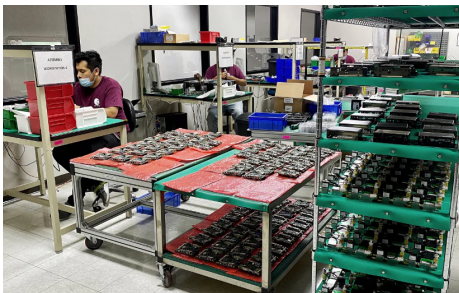
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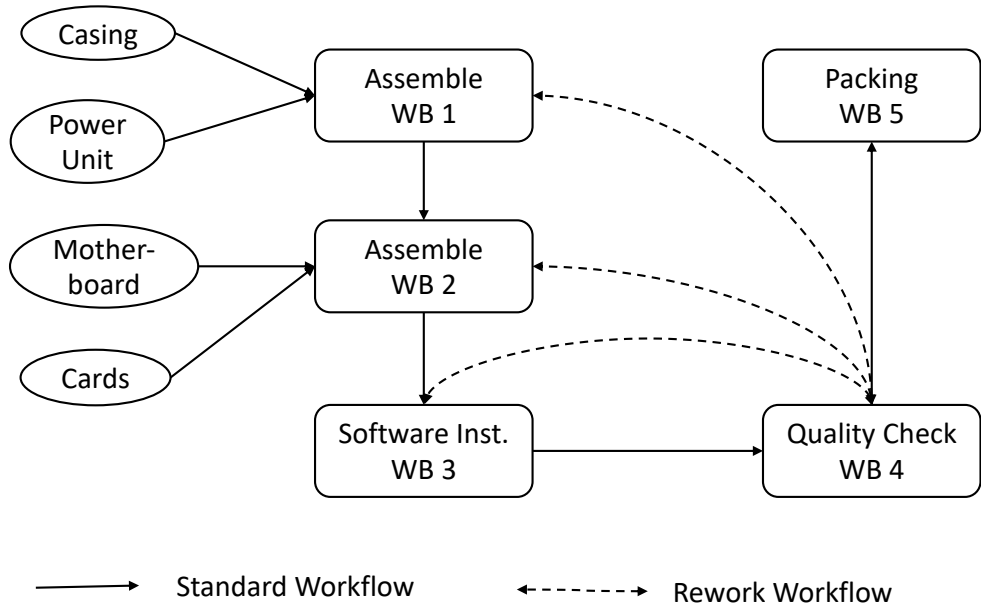
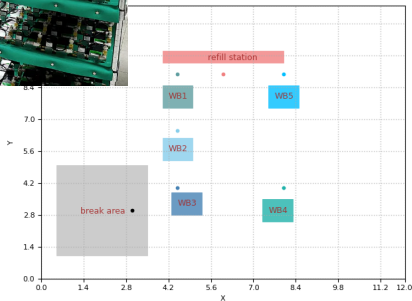
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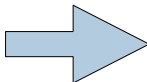
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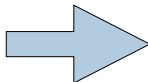
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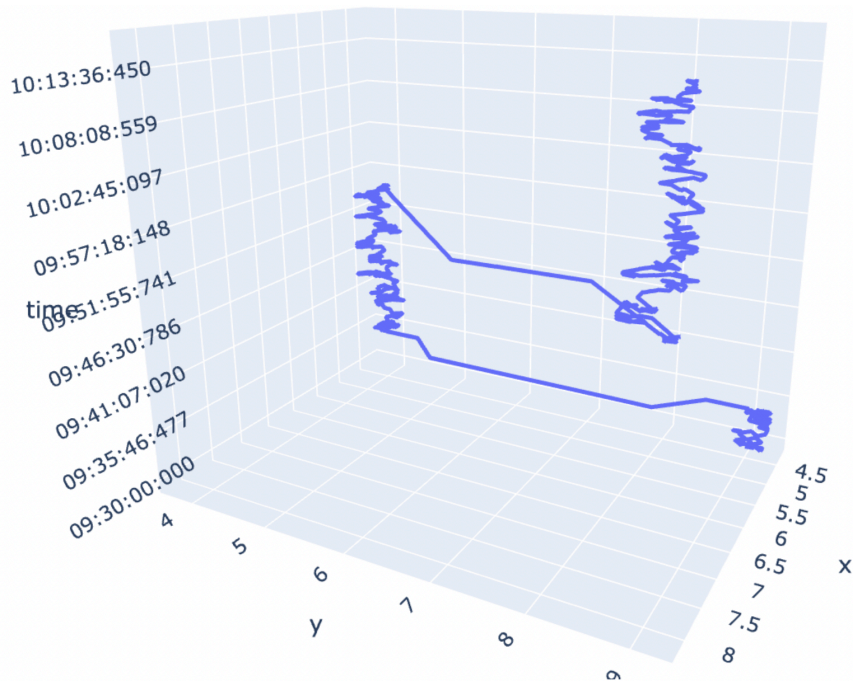
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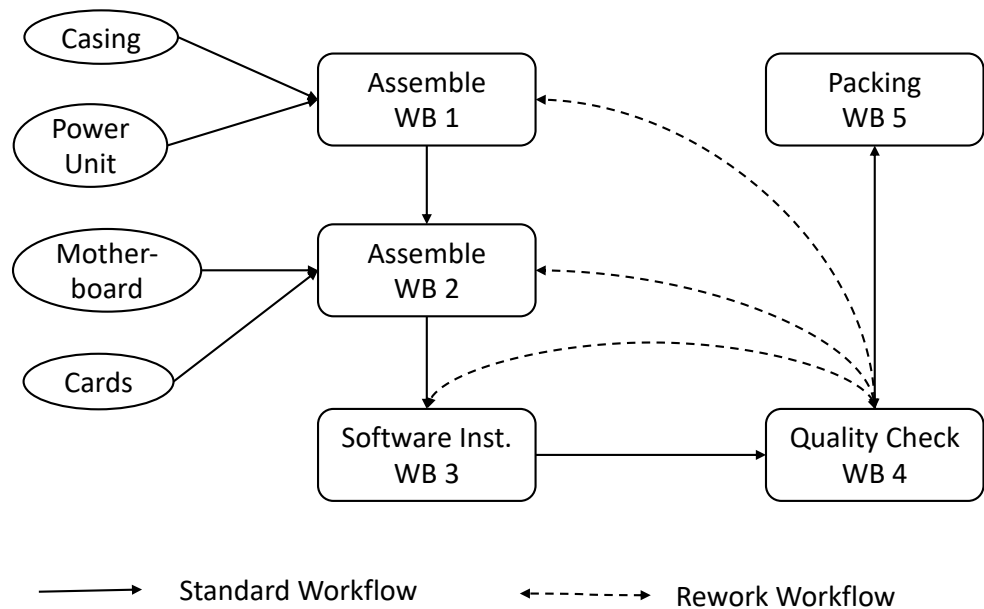
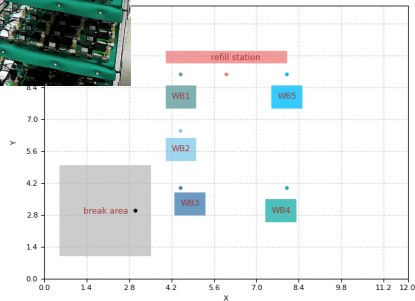
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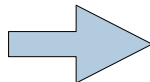
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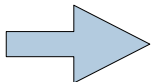
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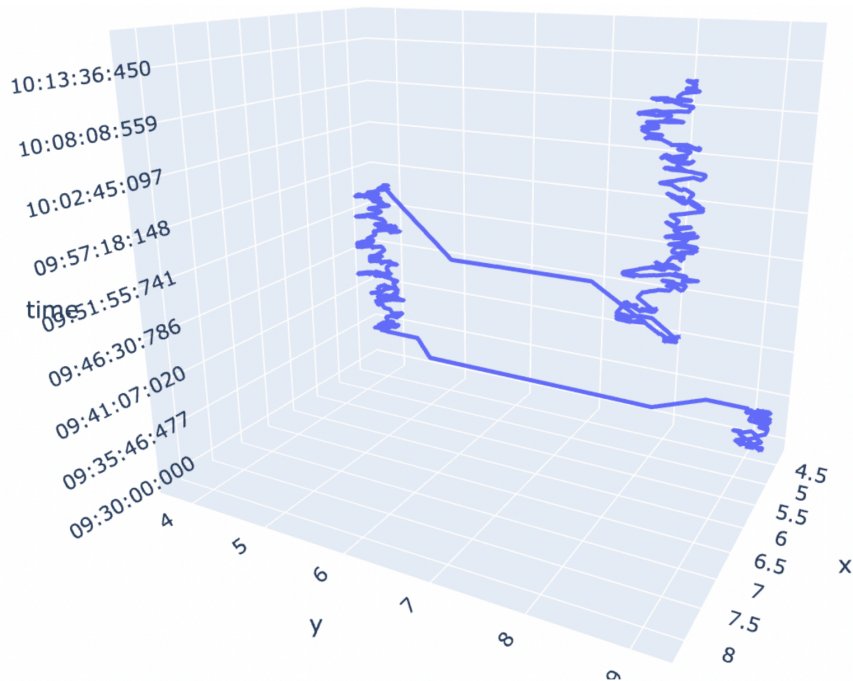
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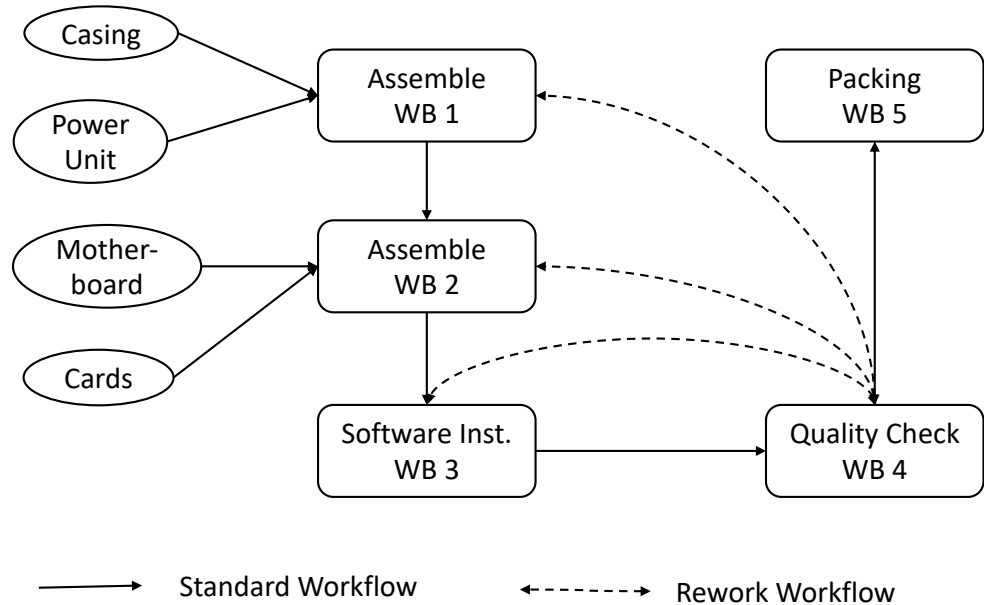
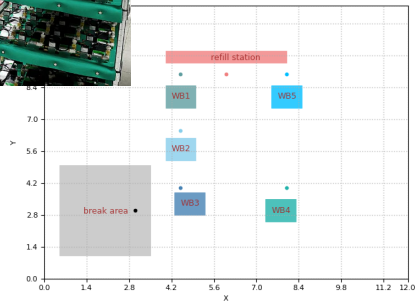
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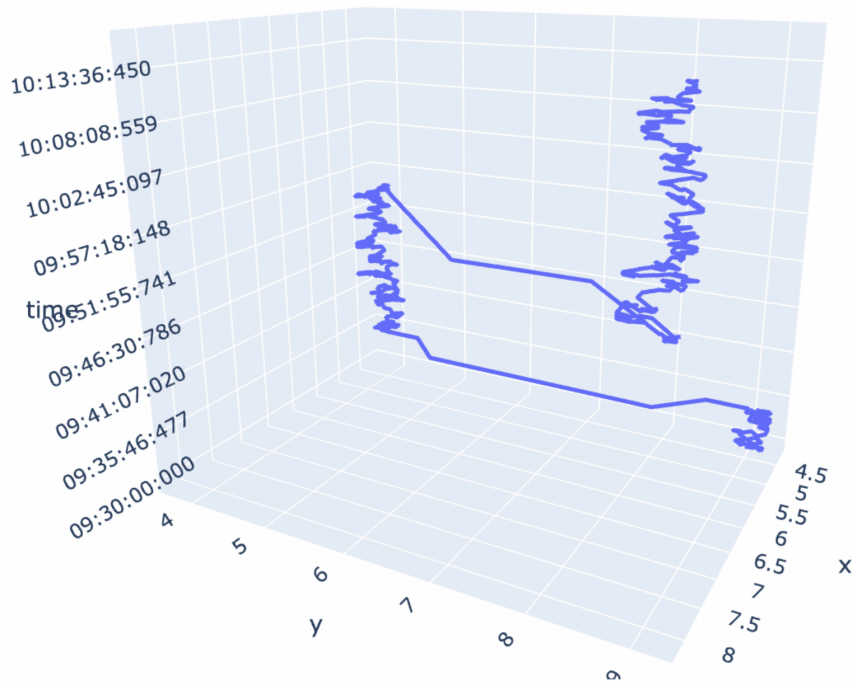
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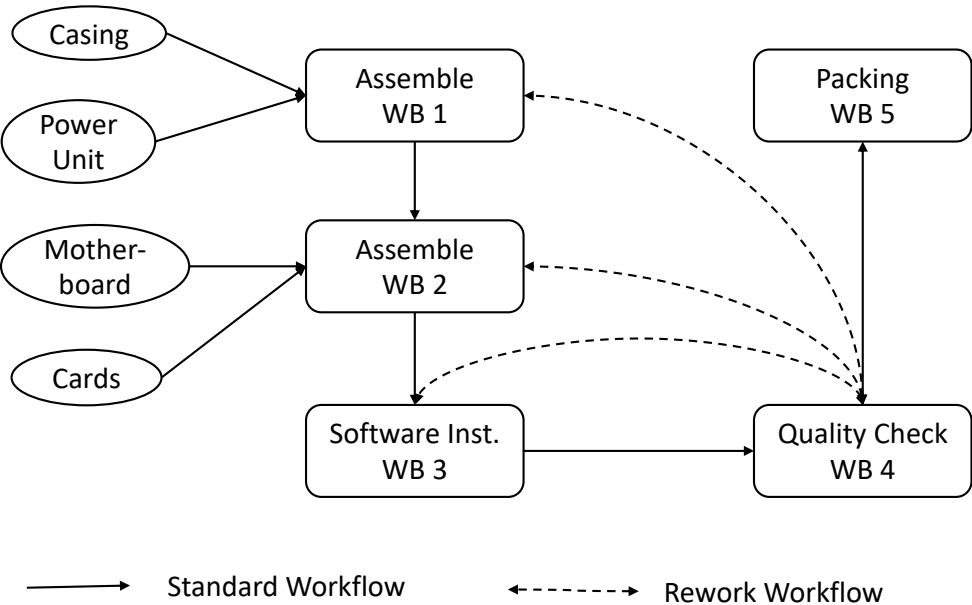
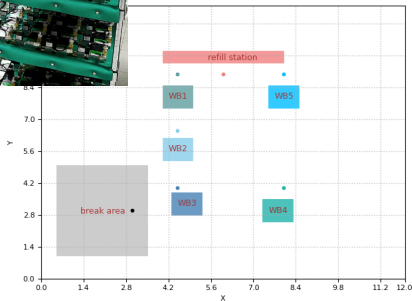
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Factory



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Actions

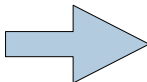
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Trajectory

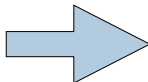
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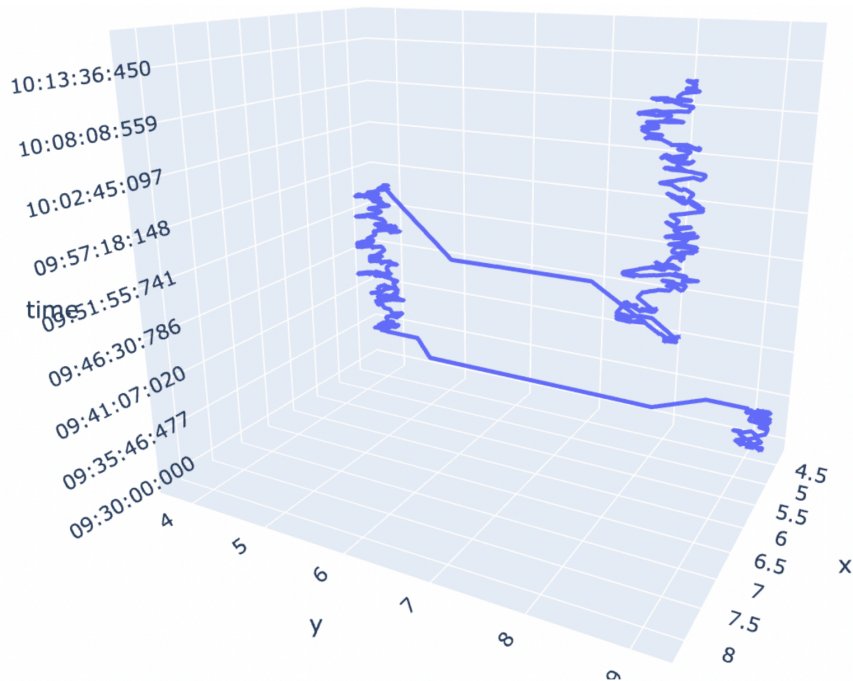
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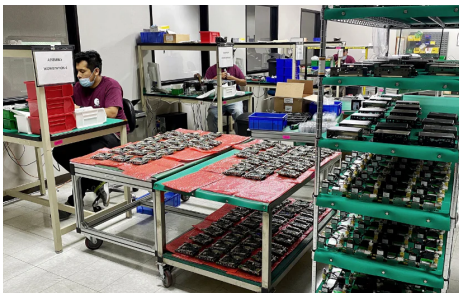
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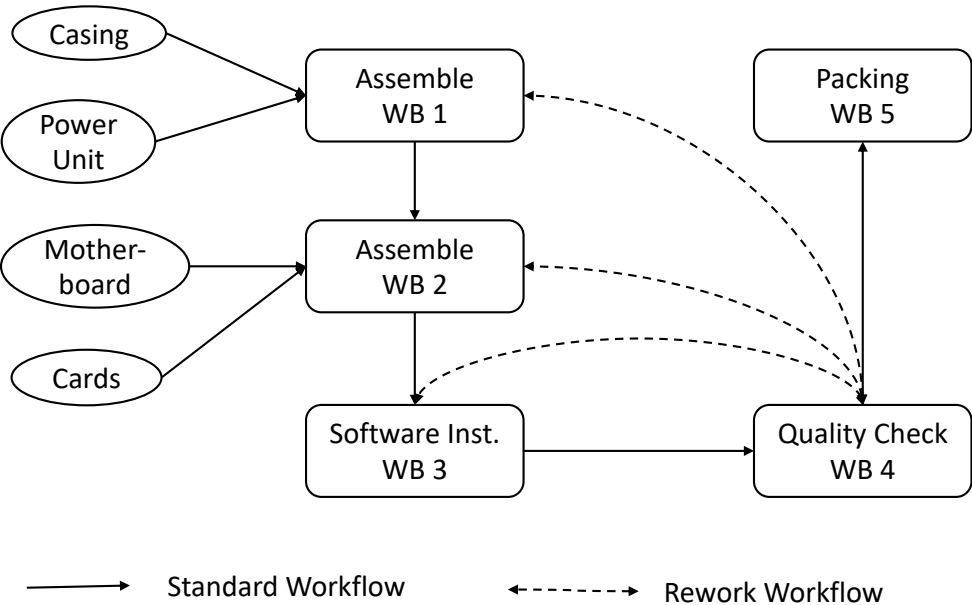
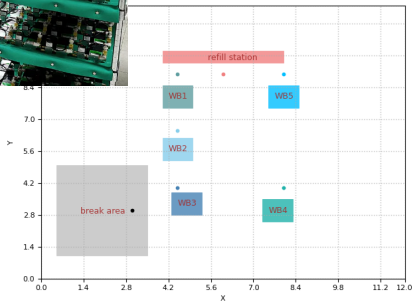
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Hidden Markov Model

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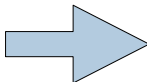
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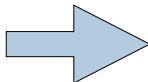
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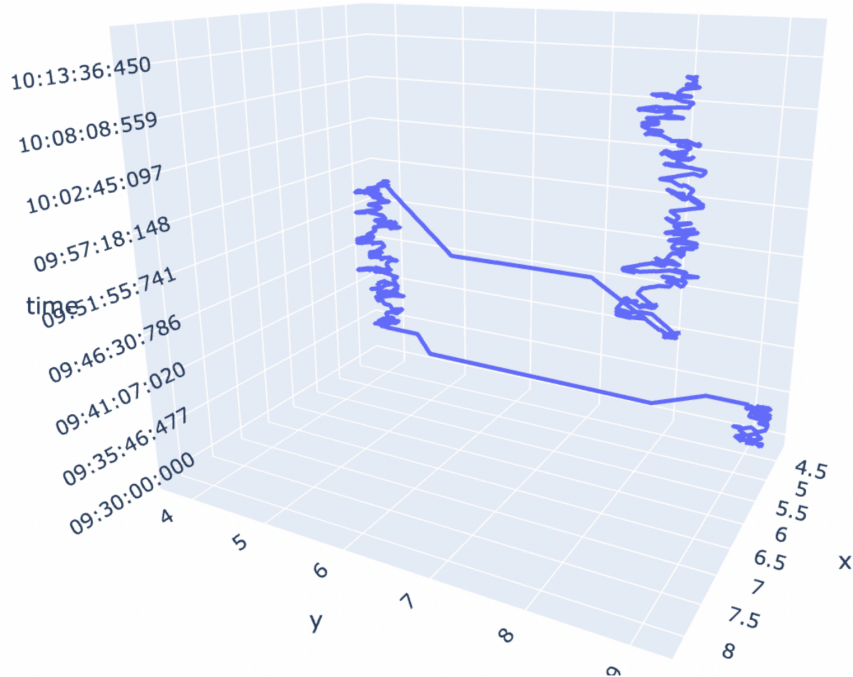
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Hidden Markov Model
PLP can do much more!

Part 1

- Probabilistic
- Logic
- Programming
- Fusemate Implementation

Part 2

- LLMs + Logic (Programming)
- Neural Networks + Logic (Programming)

Logic

“Algorithm = Logic + Control”

- Model the problem at hand with “logic”
- Feed into automated reasoning system
- Push button and get solution

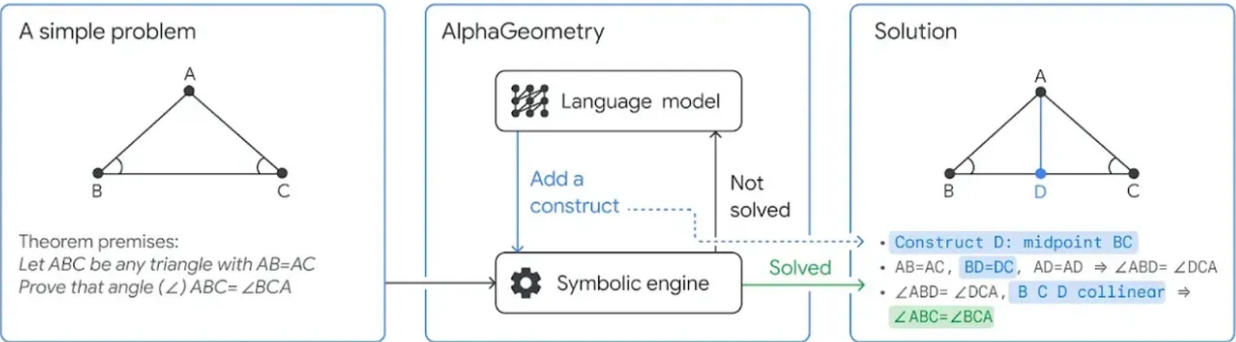
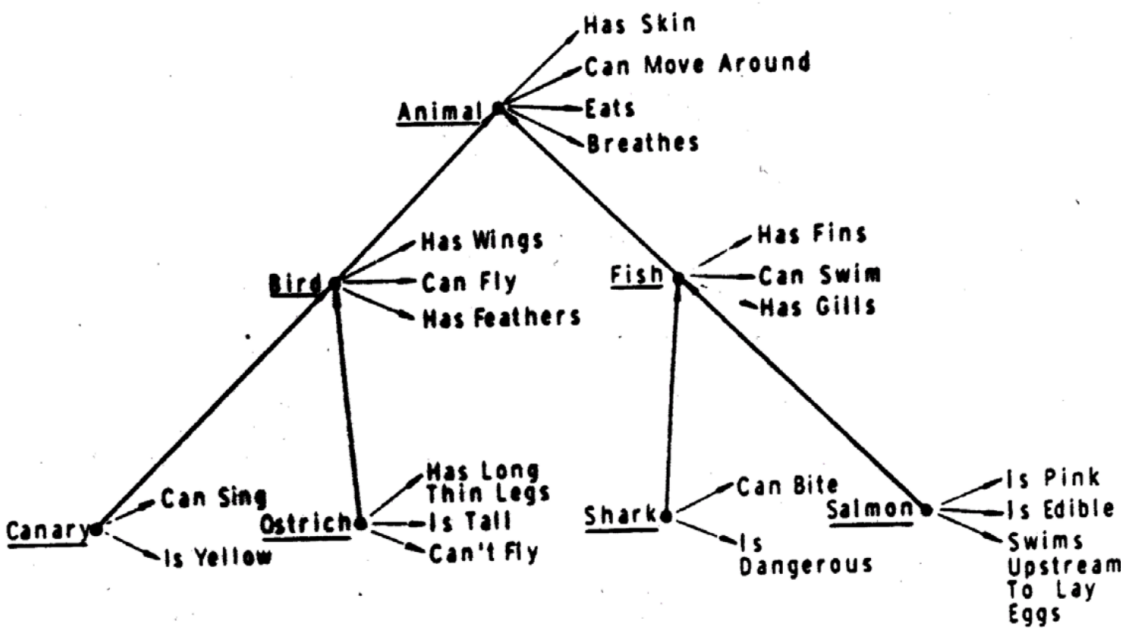
Logic

- Classical
- Non-monotonic
- Modal
- Probabilistic
- Temporal
- Graphs (Ontologies)
- Relational (Tables)
- Built-in Theories

Reasoning Tasks

- Proving
- Disproving
- Query answering
- Model computation
- Knowledge Completion
- Diagnosis

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flight(toronto, london).
flight(london, rome).
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AlphaGeometry, AlphaProof, LLM-modulo, ...

Relational

Ontology

Neuro-Symbolic

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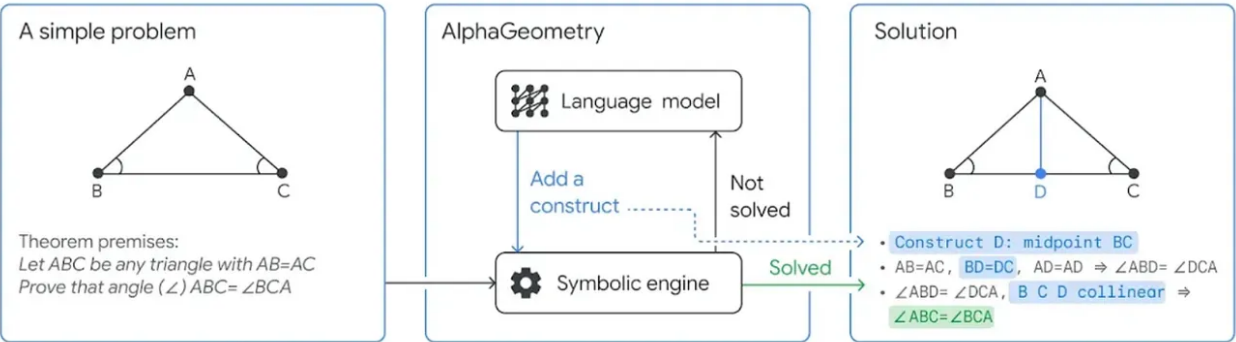
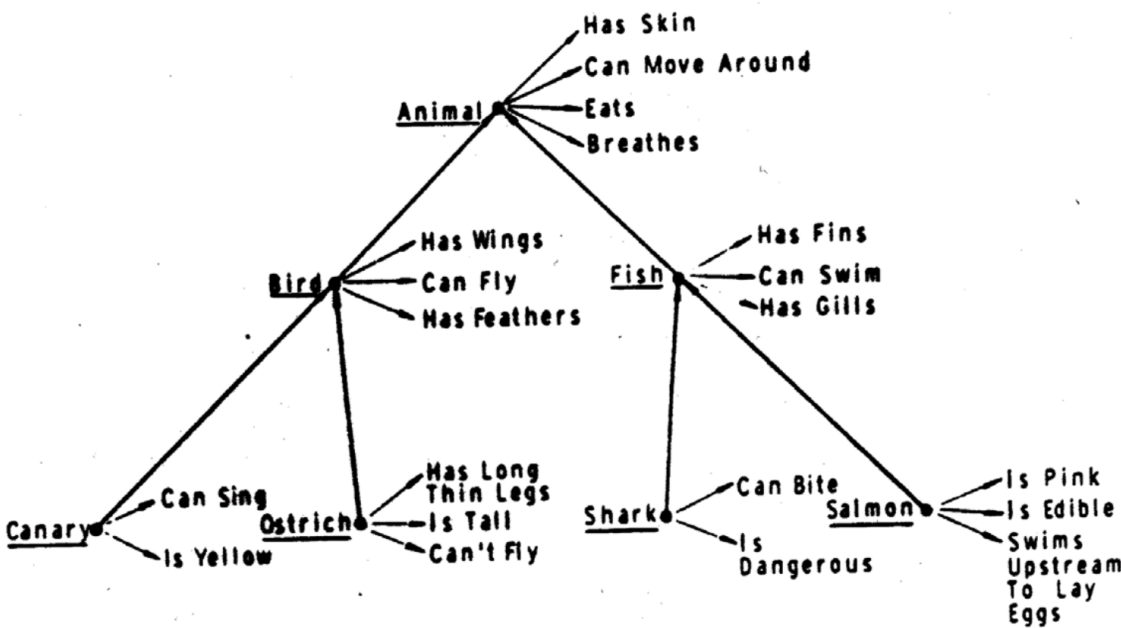
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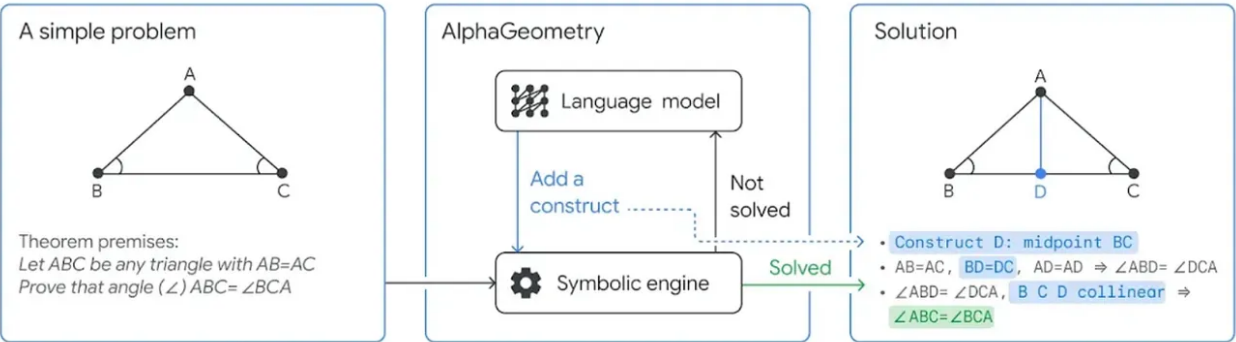
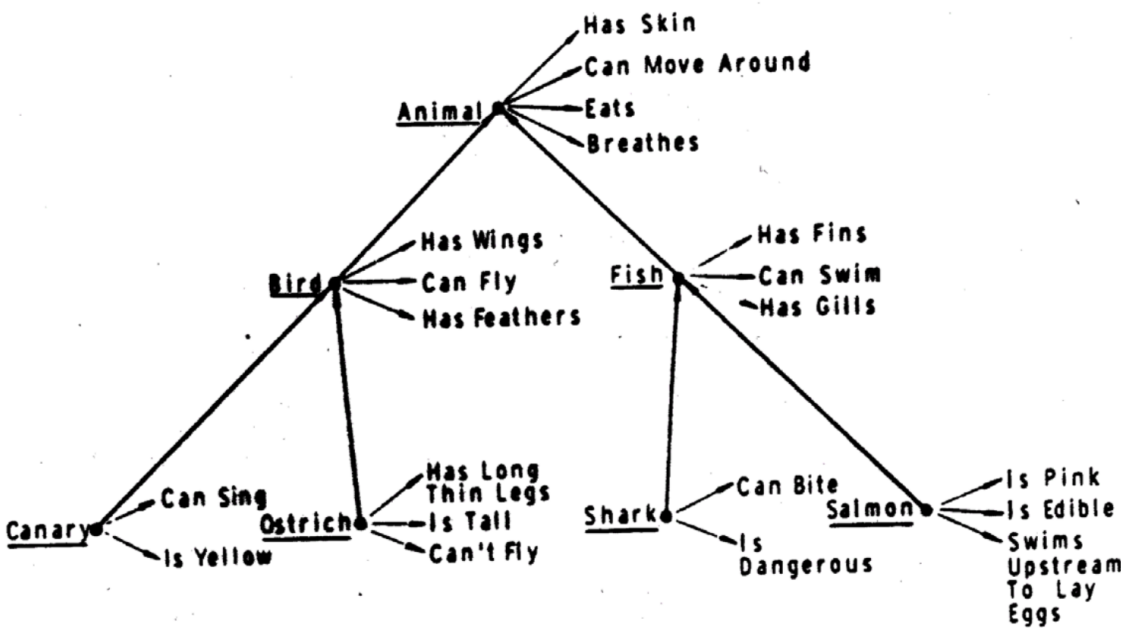
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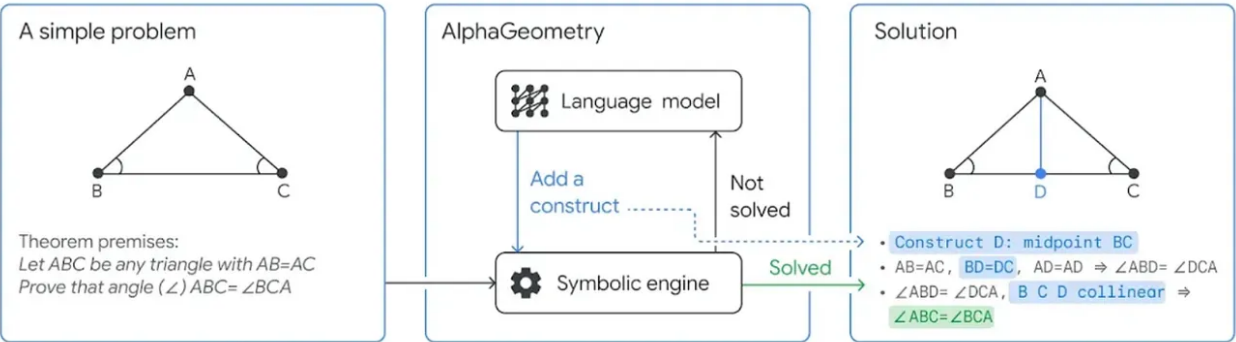
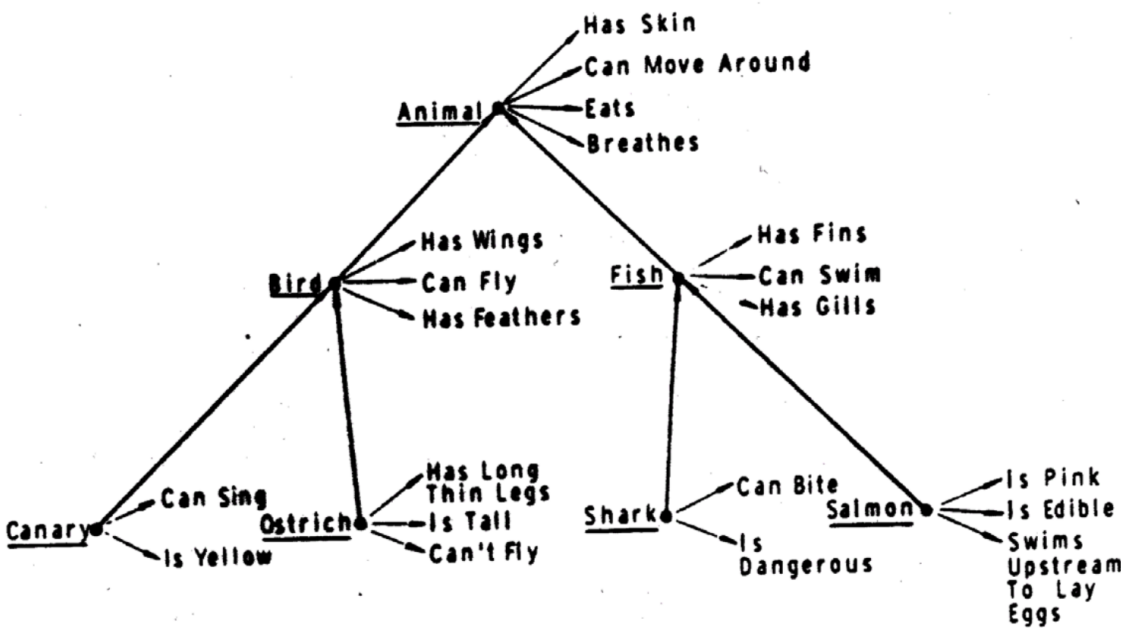
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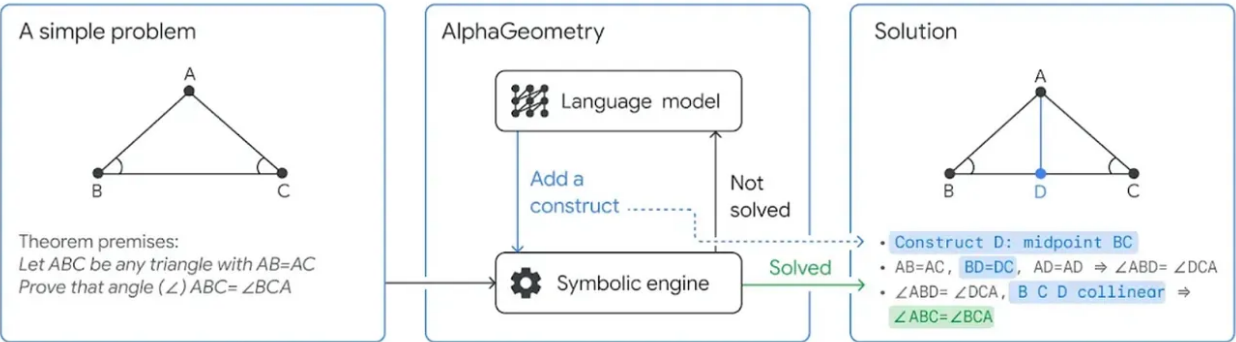
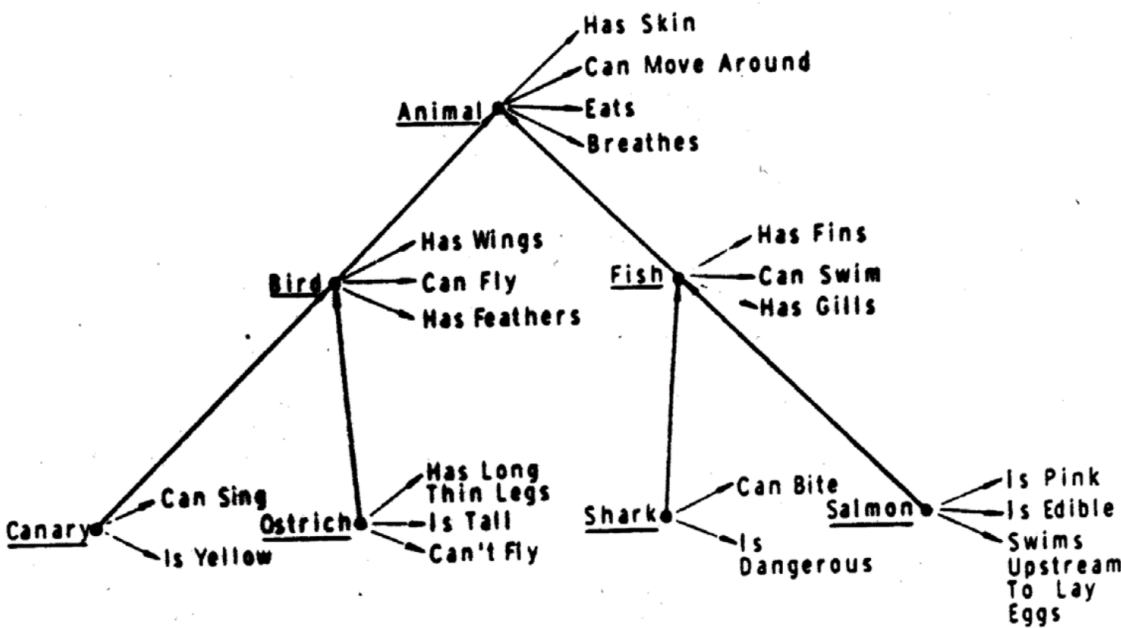
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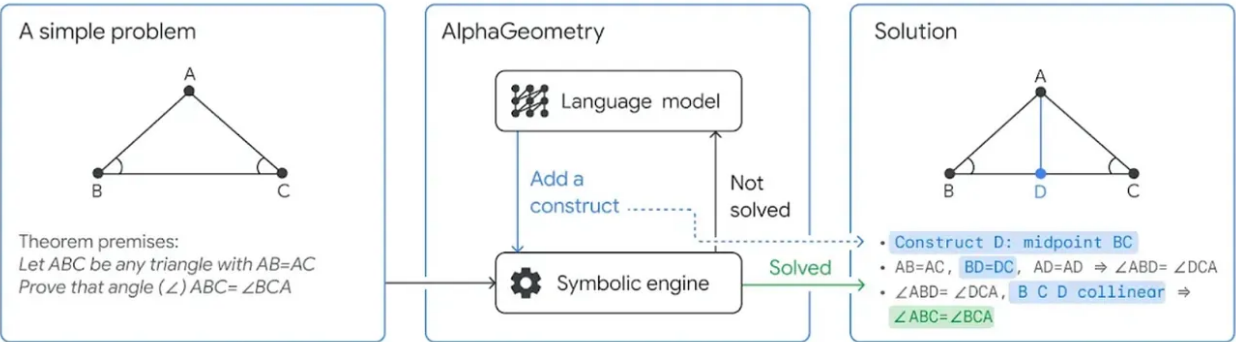
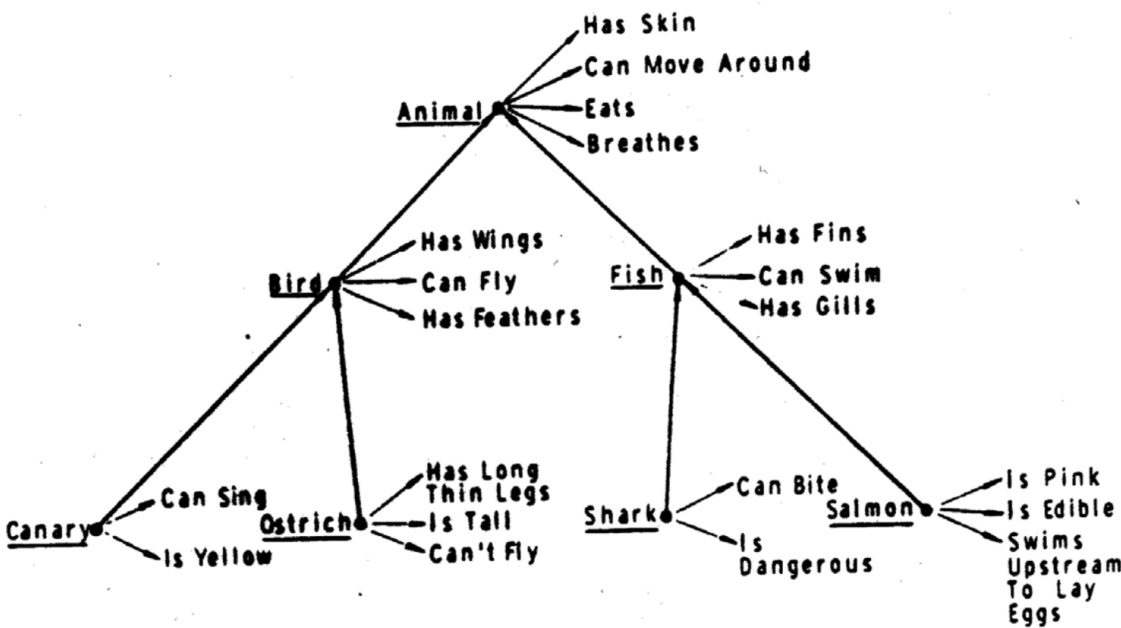
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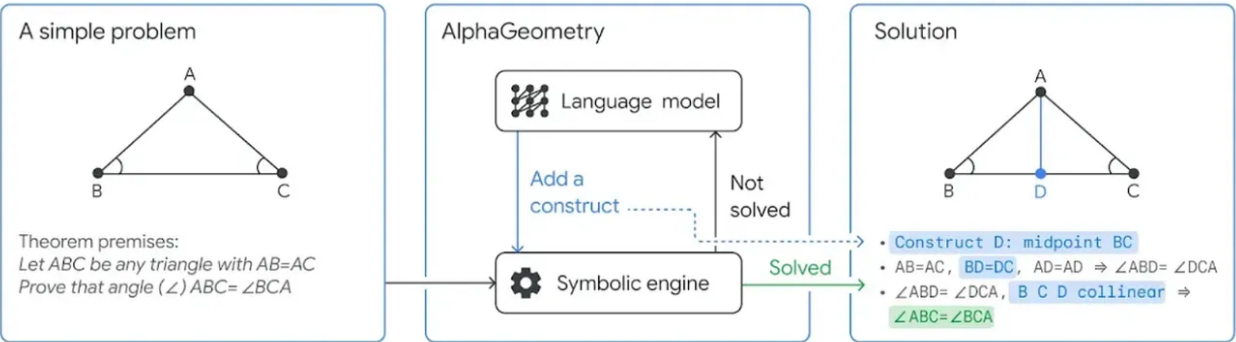
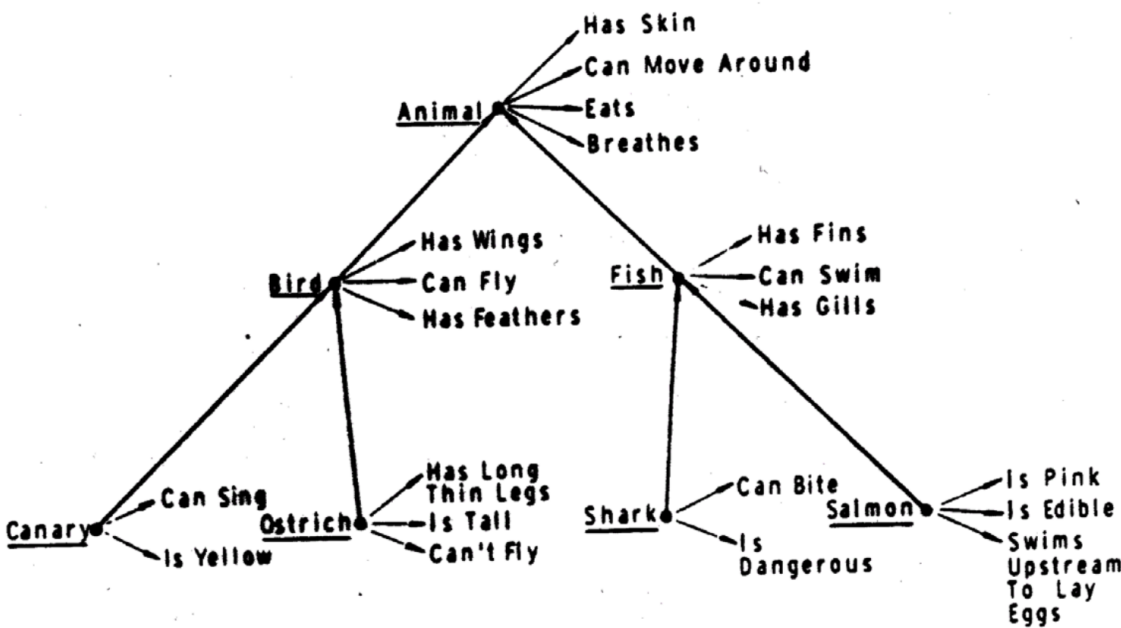
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Neuro-Symbolic

Logic

“Algorithm = Logic + Control”

- Model the problem at hand with “logic”
- Feed into automated reasoning system
- Push button and get solution



Logic

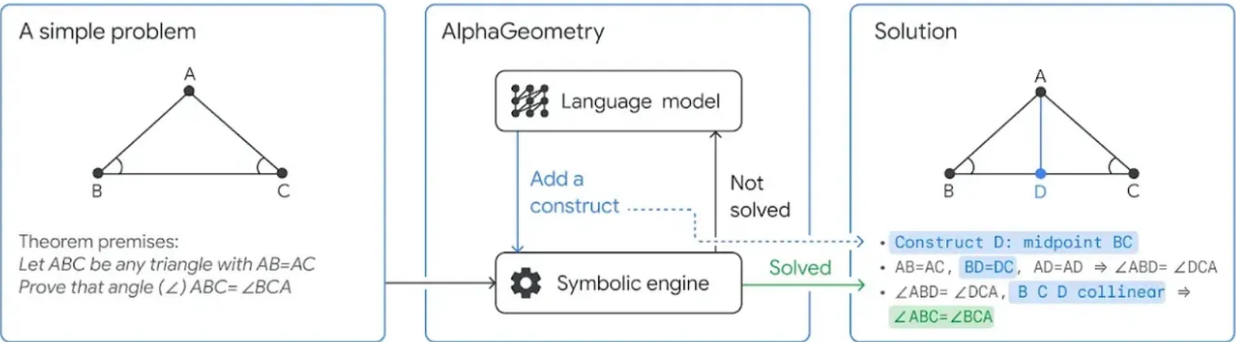
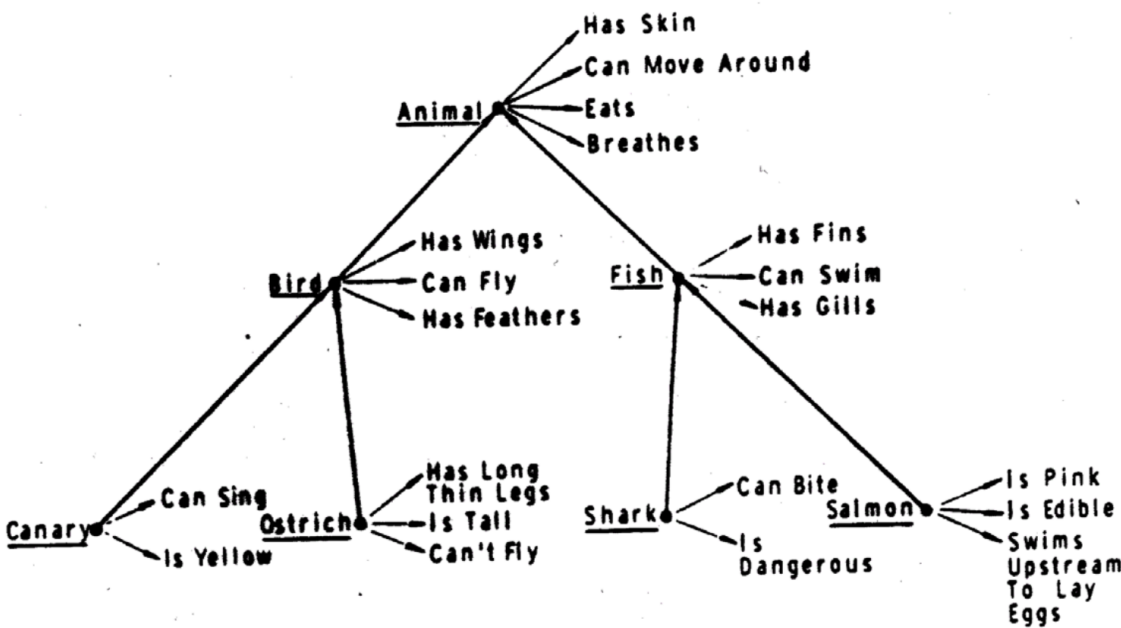
- Classical
- Non-monotonic
- Modal
- Probabilistic
- Temporal
- Graphs (Ontologies)
- Relational (Tables)
- Built-in Theories

Reasoning Tasks

- Proving
- Disproving
- Query answering
- Model computation
- Knowledge Completion
- Diagnosis

“Logic” vs “Logic Programming”?

```
flight(toronto, london).
flight(london, rome).
flight(chicago, london).
flight(X, Y) :- flight(X, Z) , flight(Z, Y).
```



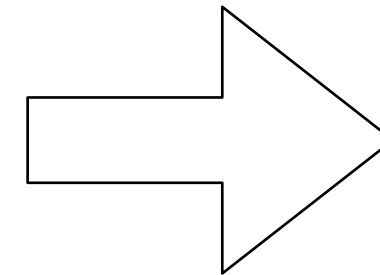
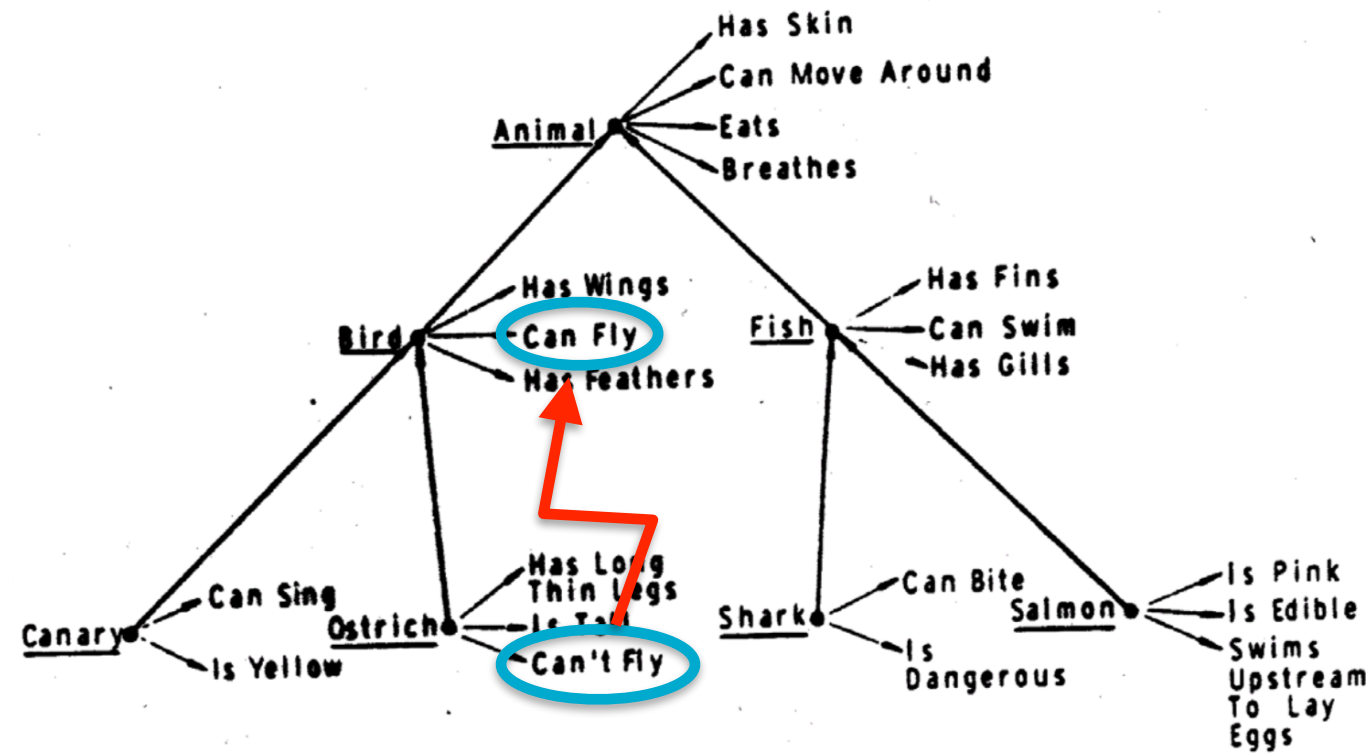
AlphaGeometry, AlphaProof, LLM-modulo, ...

Relational

Ontology

Neuro-Symbolic

Classical Logic and Logic Programming Semantics

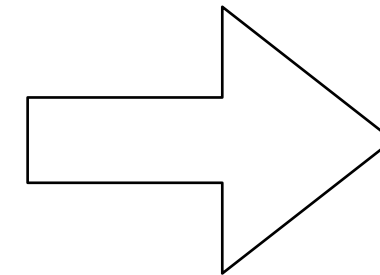
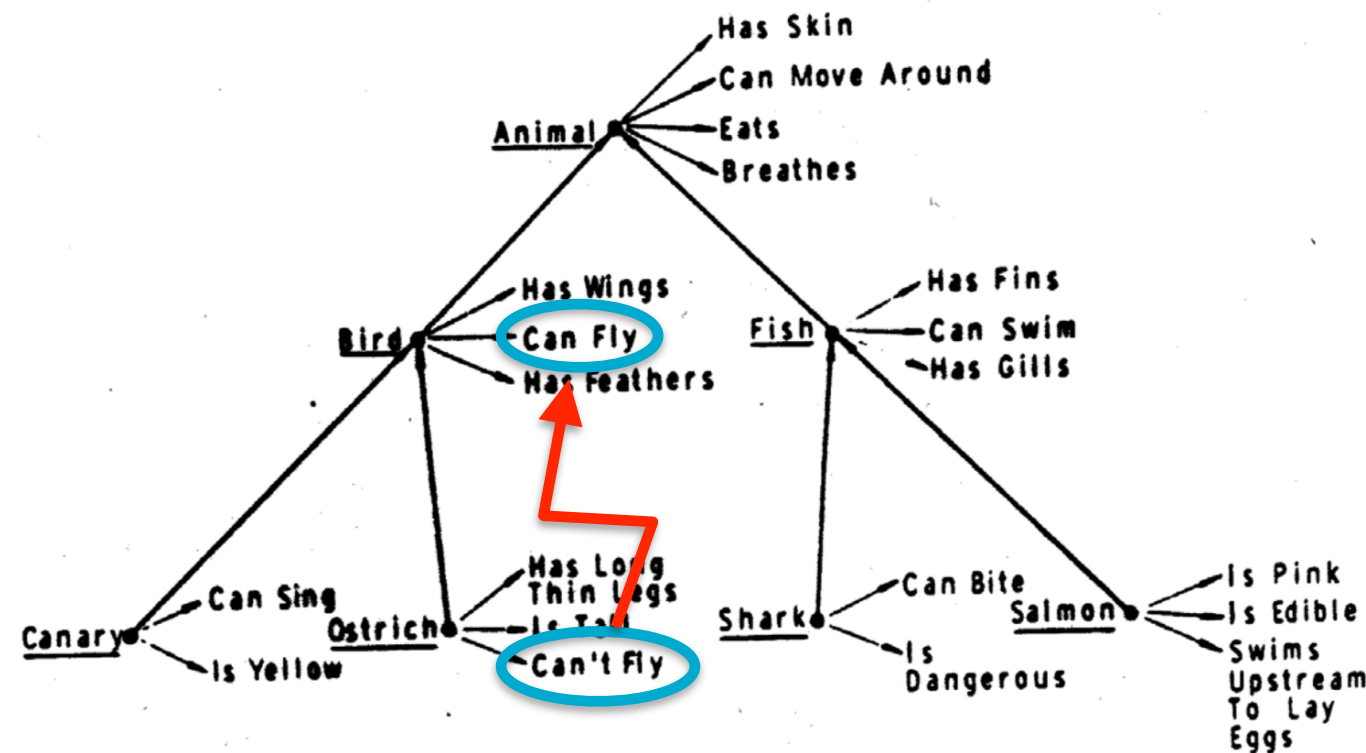


*If X is a bird
then X is an animal*

*If X is a bird and
X is **not** an ostrich
then X can fly*

*Tweety is a bird
(Tweety is an ostrich)*

Classical Logic and Logic Programming Semantics



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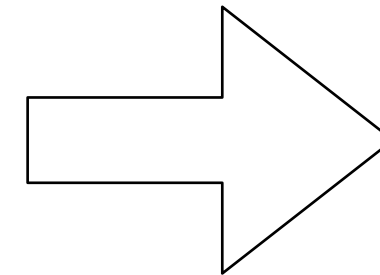
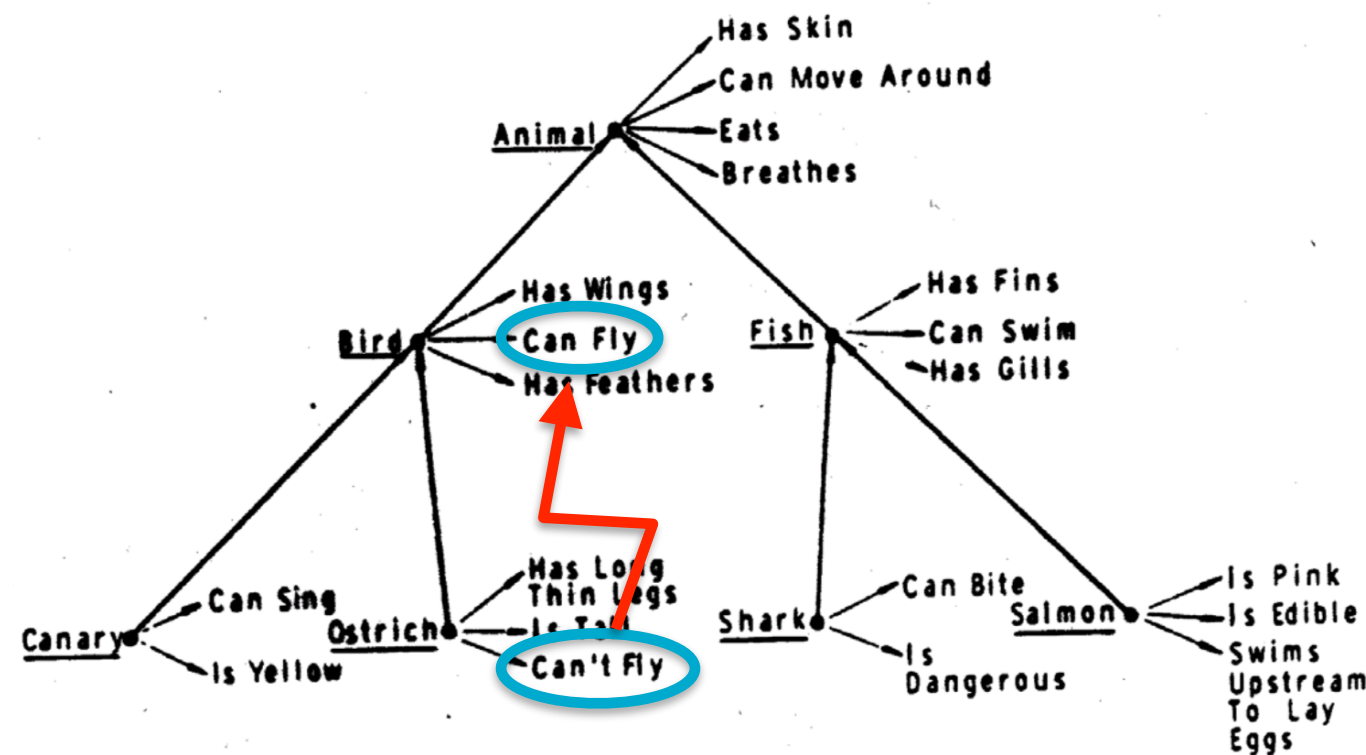
Classical (Open-World) Entailment

Non-Monotonic (Closed-World)

“Constraint” view

“Provability” view
Logic Programming

Classical Logic and Logic Programming Semantics



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✓ *Tweety is an animal*

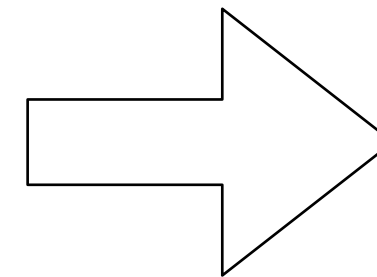
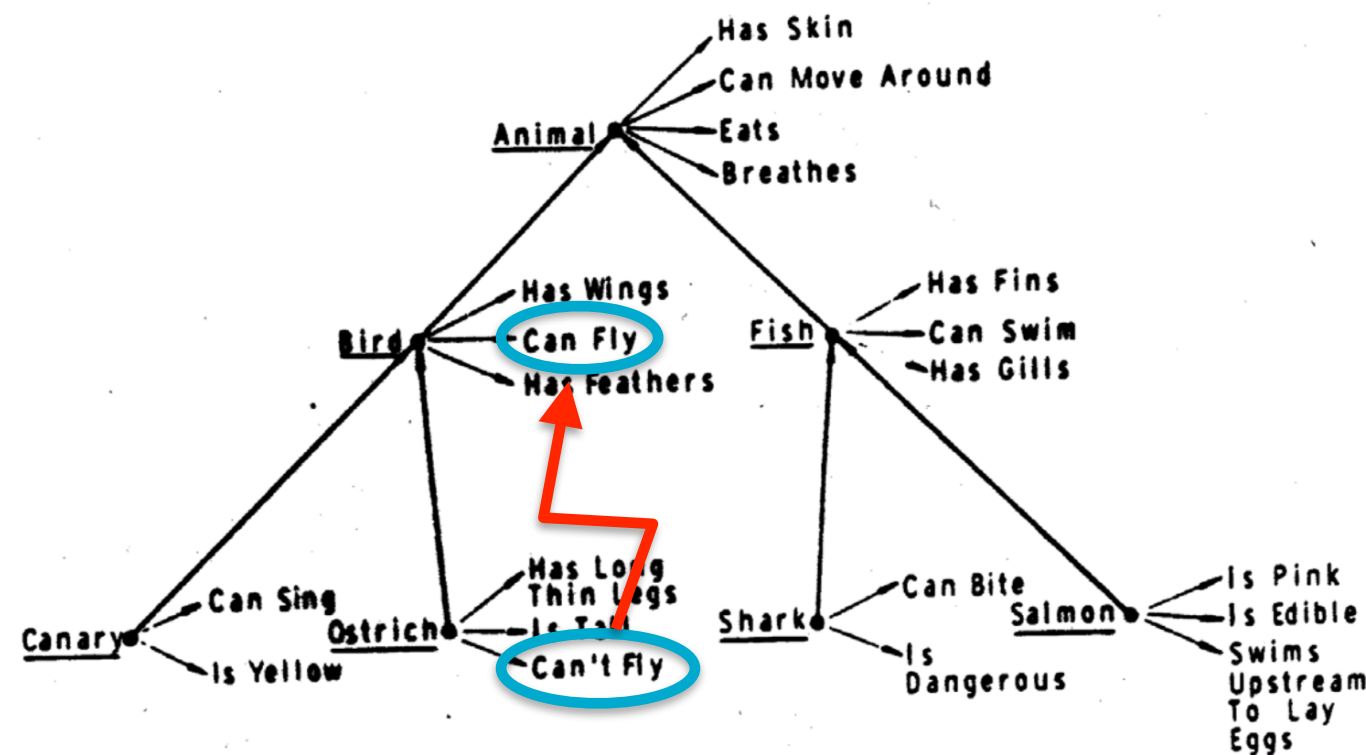
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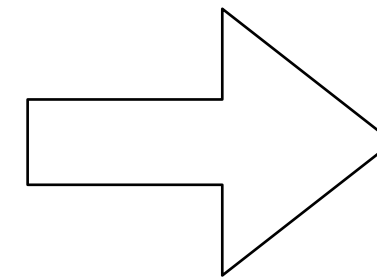
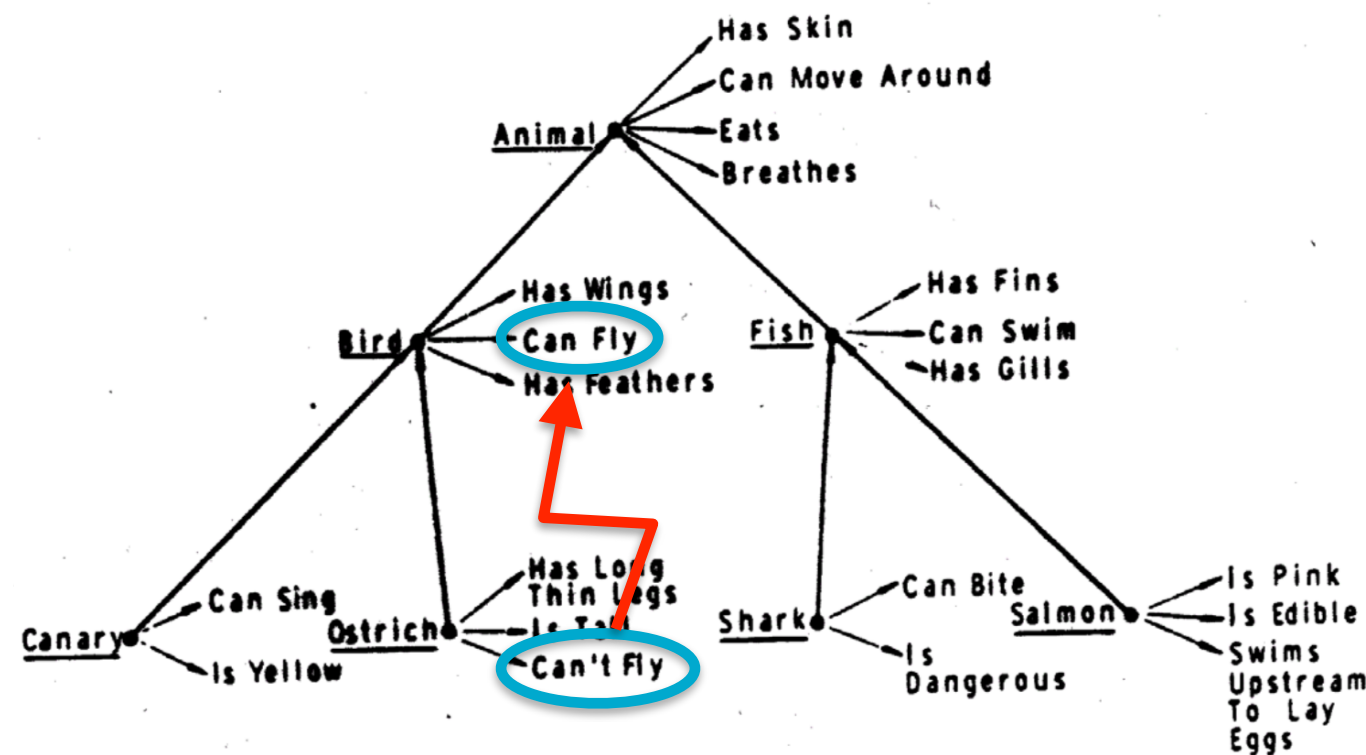
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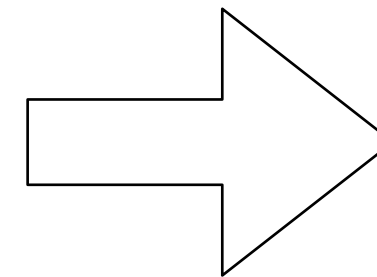
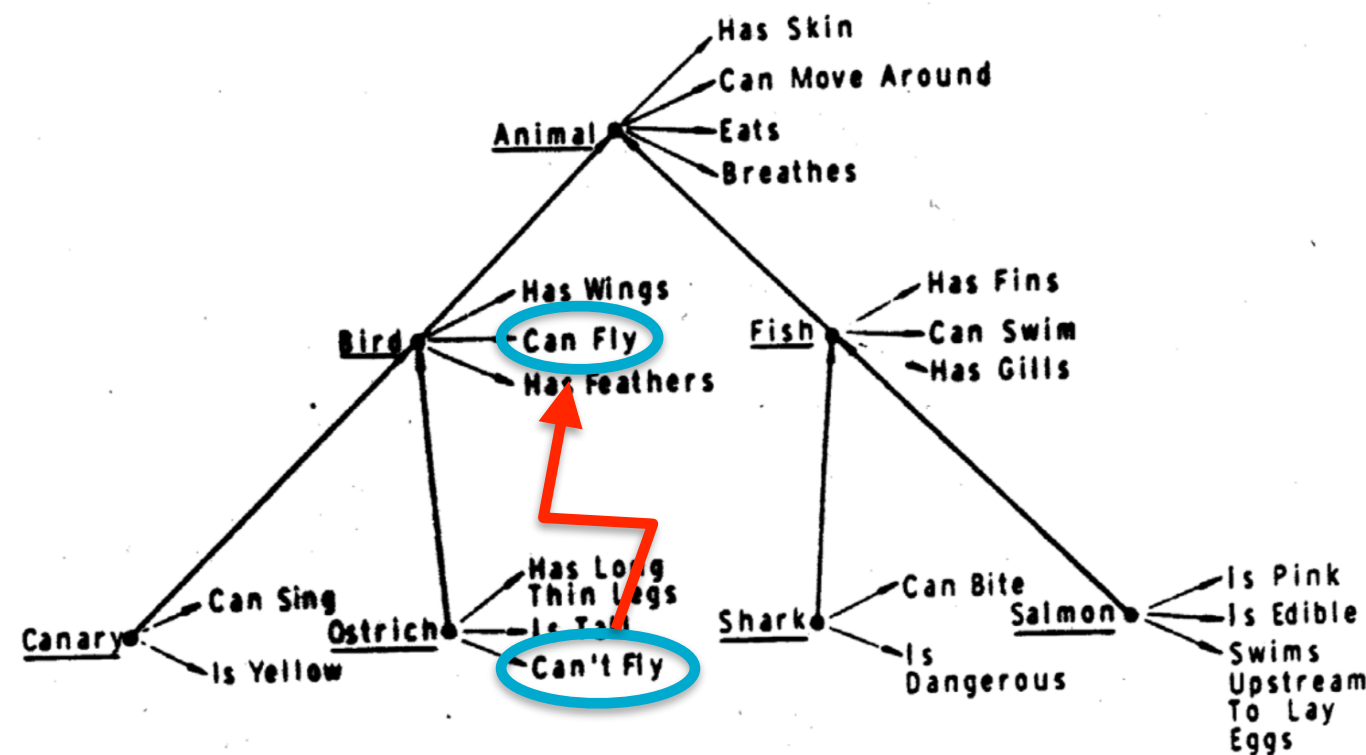
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“Provability” view
Logic Programming



Probabilistic Logic Programs



Facts	cat(tom).	<i>Tom is a cat</i>
Rules	drinks(X, milk) :- cat(X).	<i>If X is a cat then X drinks milk</i>
Default Negation	innocent(X) :- cat(X), not guilty(X). flies(X) :- bird(X), not abnormal(X).	<i>If X is a cat and X is not guilty then X is innocent</i>
... @ Time (Fusemate)	thirsty(X) @ T+1 :- thirsty(X) @ T, not drink(X, _) @ T.	<i>If X is thirsty at time T and X does not drink at time T then X is thirsty at time T+1</i>
Probabilities	0.8 :: cat(tom). 0.5 :: drinks(X, milk) :- cat(X).	
Distributions (Fusemate)	nr_siblings(X) ~ [[0, 0.05], [1, 0.10], ... [5, 0.10]] :- cat(X).	
Queries	?- thirsty(tom) @ T thirsty(tom) @ 2, drink(tom, milk) @ 5.	

Operational
Top-Down Inference
Bottom-Up Inference
Exact inference/sampling
Parameter Learning
Structure Learning

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Dynamic Data Structures and Distributions

Drawing without replacement

```
urn([r(1), r(2), g(1)]) @ 0.           %% Initially two red and one green distinguishable balls
draw ~ Balls @ T :-                     %% Draw a ball uniformly if urn is not empty
    urn(Balls) @ T,
    Balls \= [].
urn(Balls -- [B]) @ T+1 :-              %% Drawing a ball removes it from urn
    urn(Balls) @ T,
    draw = B @ T.
some(red) @ T :- draw=r(_) @ T.          %% Abstract from ball id, color only
some(green) @ T :- draw=g(_) @ T.
```

Queries

```
?- some(green) @ 0.
% 0.333333
```

```
?- some(green) @ 1 | some(red) @ 0.
% 0.5 conditional query
```

```
?- some(C1) @ 1, some(C2) @ 2 | some(red) @ 0. % Non-ground conditional query, two solutions:
% 0.5 :: [C1 = red, C2 = green]
% 0.5 :: [C1 = green, C2 = red]
```

Dynamic Data Structures and Distributions

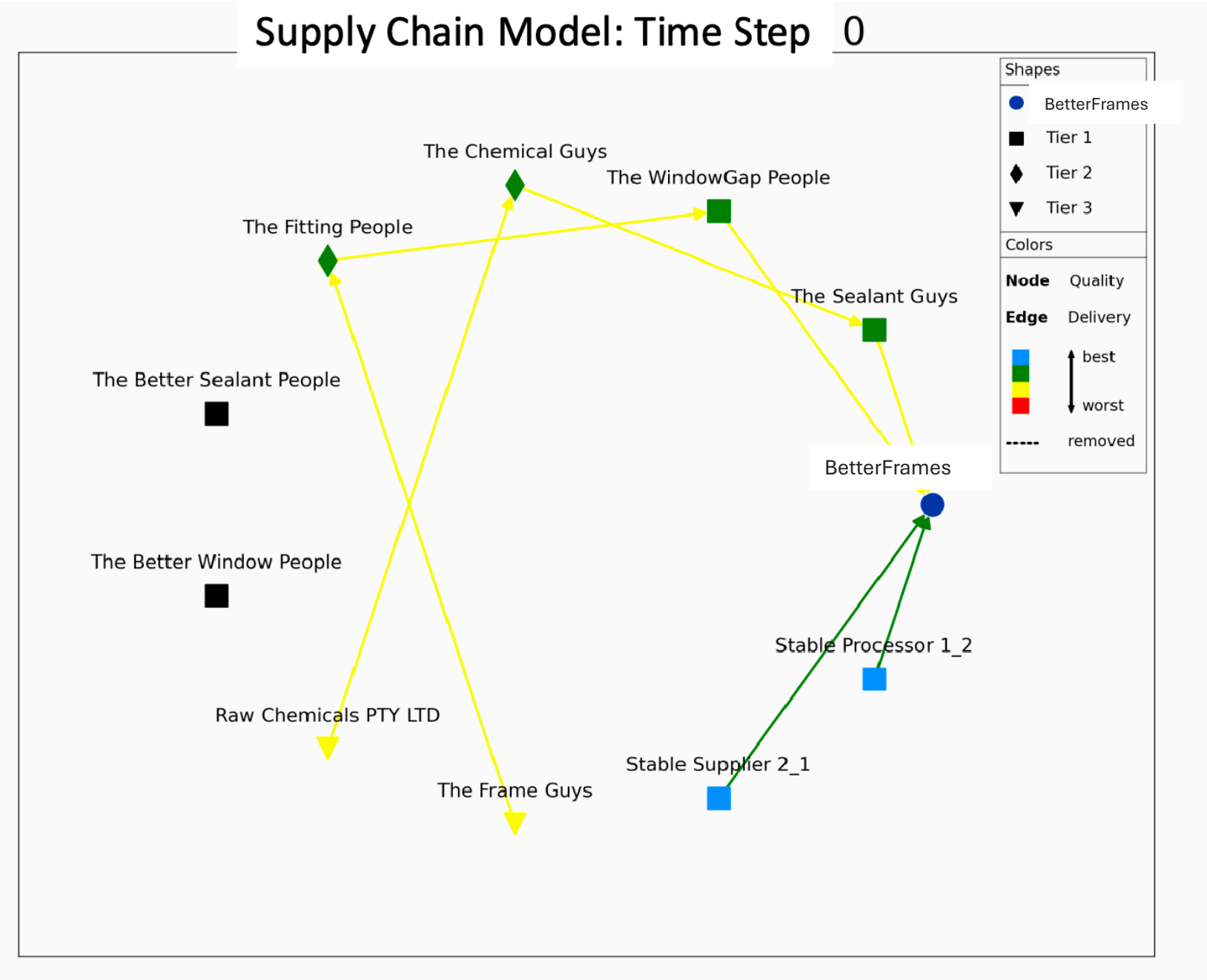
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```

D61 Supply Chain Risk Assessment Application

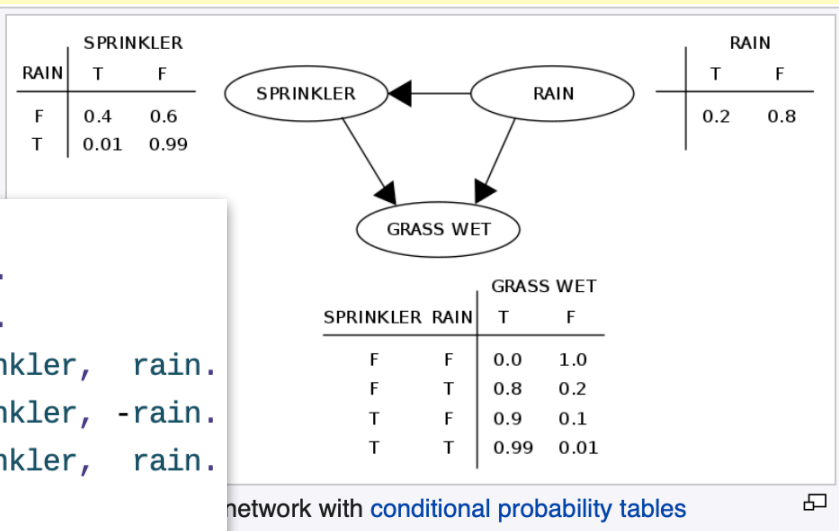


Probabilistic Logic Programming (Fusemate)

Probabilistic Logic Programming (Fusemate)

Bayes Network

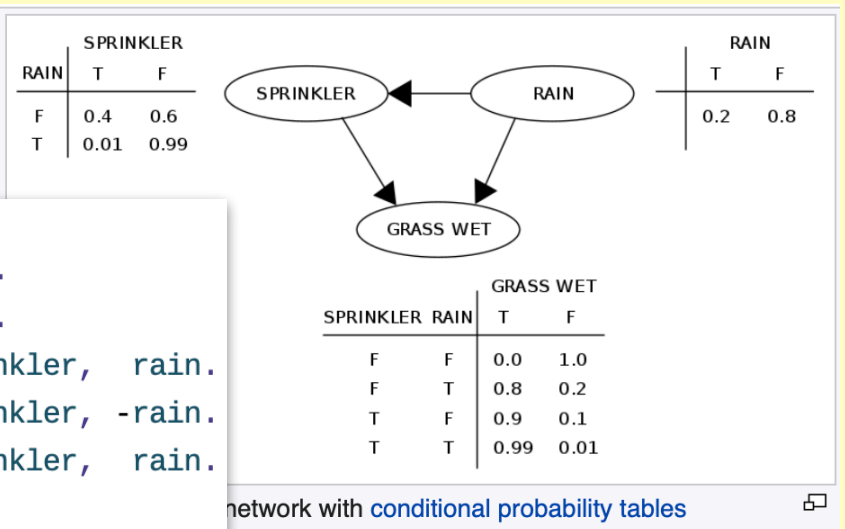
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?- rain | grasswet.
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Probabilistic Logic Programming (Fusemate)

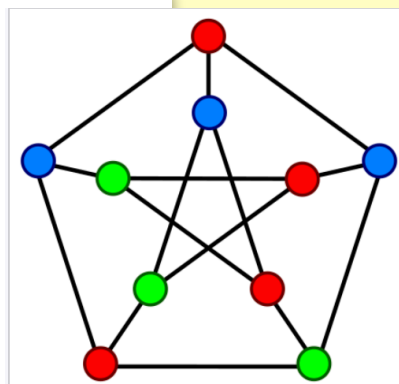
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NP-Complete Search Problems

```
color(X) in [r, g, b] :- node(X).  
node(1). node(2). node(3). node(4).  
noncol :- color(X)=r, color(Y)=r, edge(X,Y).  
noncol :- color(X)=g, color(Y)=g, edge(X,Y).  
noncol :- color(X)=b, color(Y)=b, edge(X,Y).  
edge(1,2). edge(2,3). edge(3,1).  
  
edge(4,1).  
edge(4,2).  
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%% \+ noncol is true iff there is a coloring  
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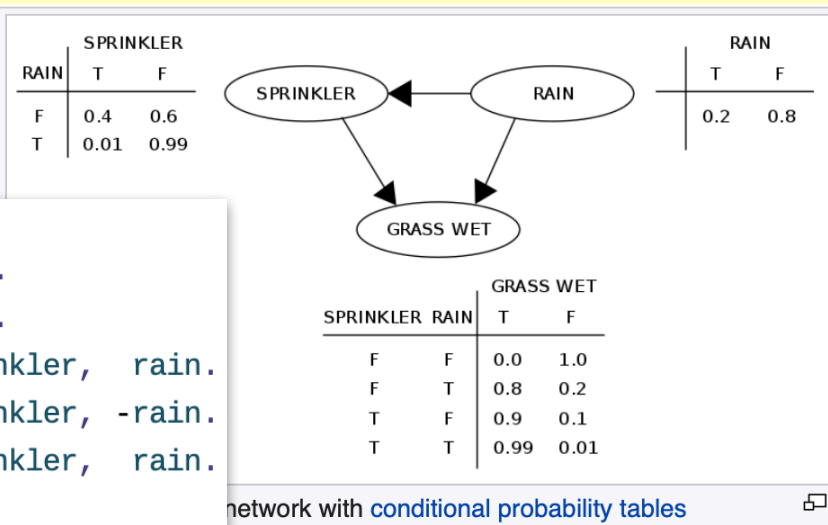
Logical variables **X** for domain objects

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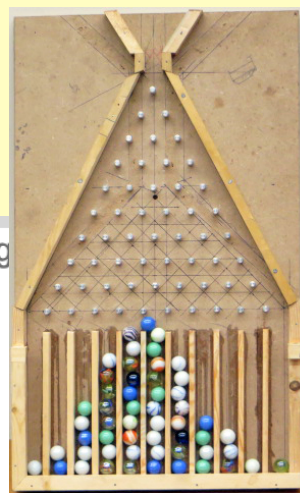
?- rain | grasswet.
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Time

```
%% Some "random" blockage
block(1) @ 2.
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prob(0).
(0.5 :: prob(K+1) + prob(K)) @ N+1 :-
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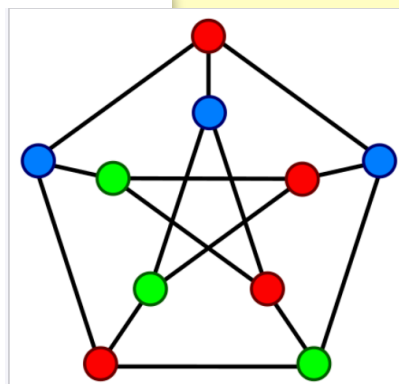
```
%% ?- prob(K) @ 4.
0.0625 :: prob(0) @ 4
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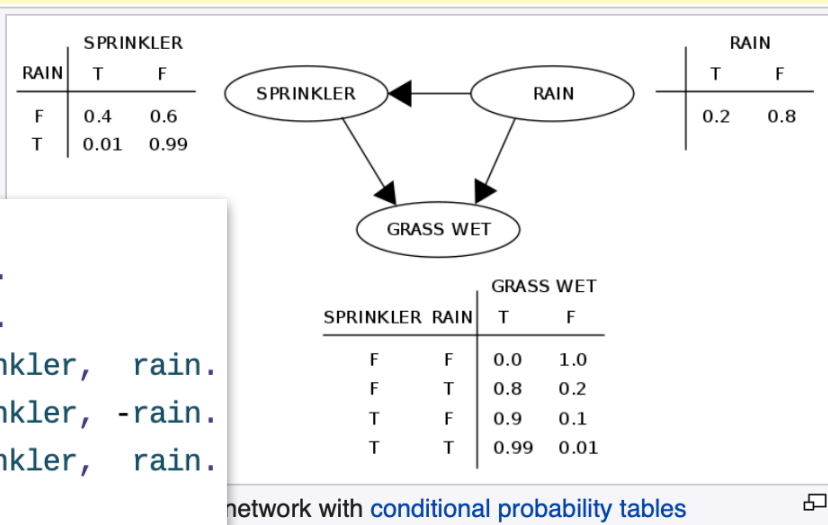
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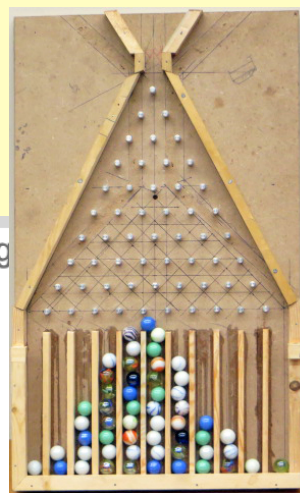
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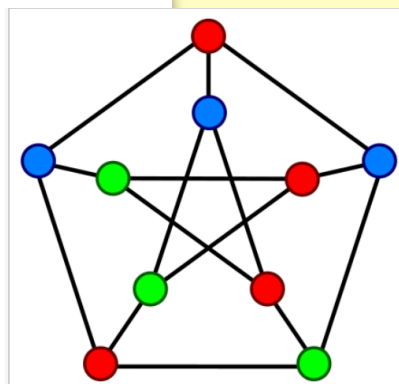
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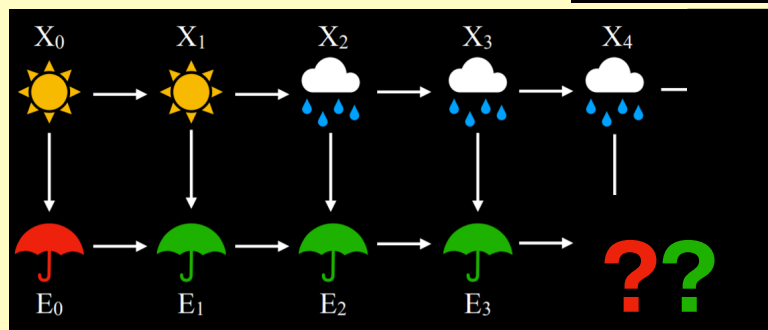


Logical variables **X** for domain objects

Hidden

Markov Models

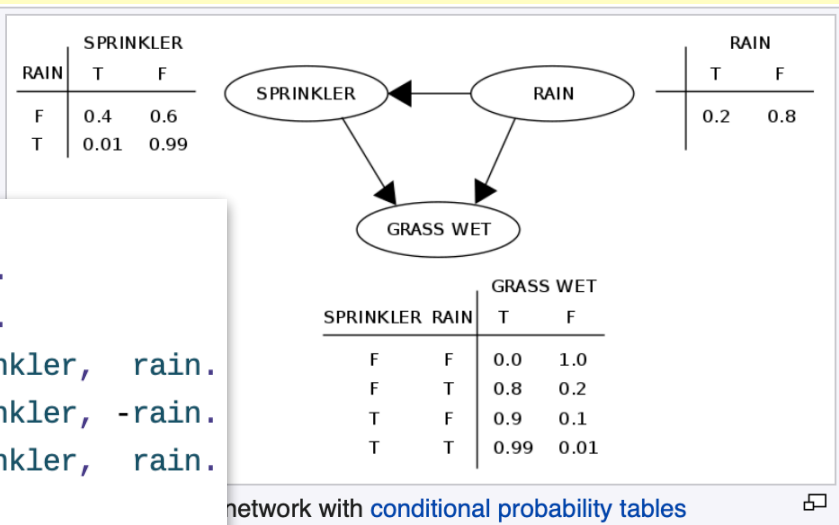
Observation (E _t)	
0.2	0.8
0.9	0.1



Probabilistic Logic Programming (Fusemate)

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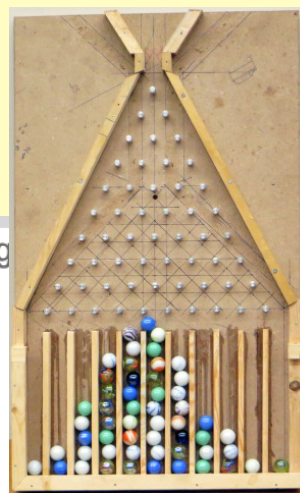
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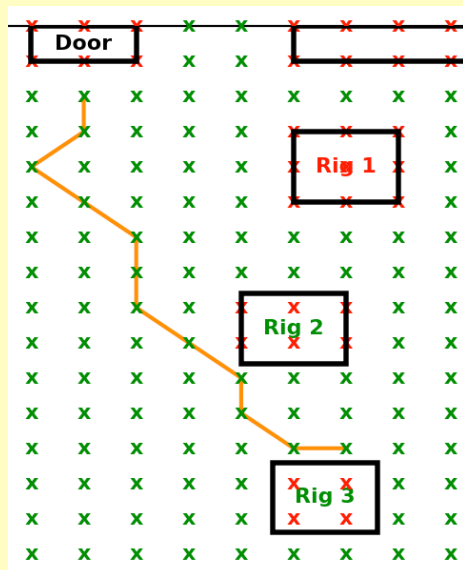
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0.0625 :: prob(0) @ 4
0.3750 :: prob(1) @ 4
0.43750 :: prob(2) @ 4
0.0625 :: prob(3) @ 4
0.0625 :: prob(4) @ 4
```

Algorithms



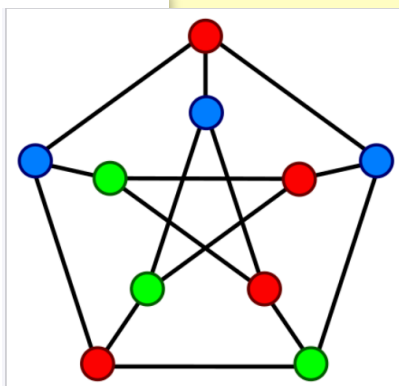
Probabilistic A*

NP-Complete Search Problems

```
color(X) in [r, g, b] :- node(X).
node(1). node(2). node(3). node(4).
noncol :- color(X)=r, color(Y)=r, edge(X,Y).
noncol :- color(X)=g, color(Y)=g, edge(X,Y).
noncol :- color(X)=b, color(Y)=b, edge(X,Y).
edge(1,2). edge(2,3). edge(3,1).

edge(4,1).
edge(4,2).
%edge(4,3).

%% \+ noncol is true iff there is a coloring
?- -noncol, color(1)=C1, color(2)=C2, color(3)=C3, color(4)=C4.
```

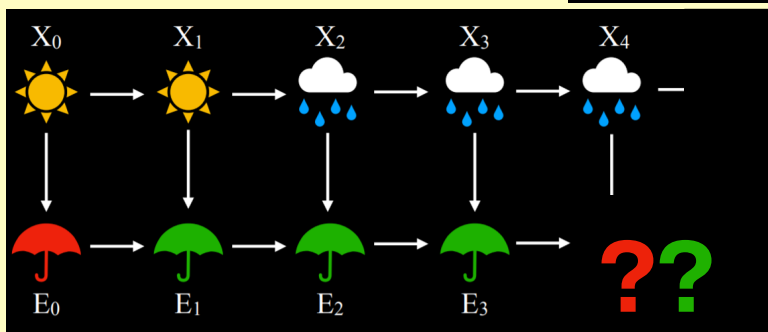


Logical variables **X** for domain objects

Hidden

Markov Models

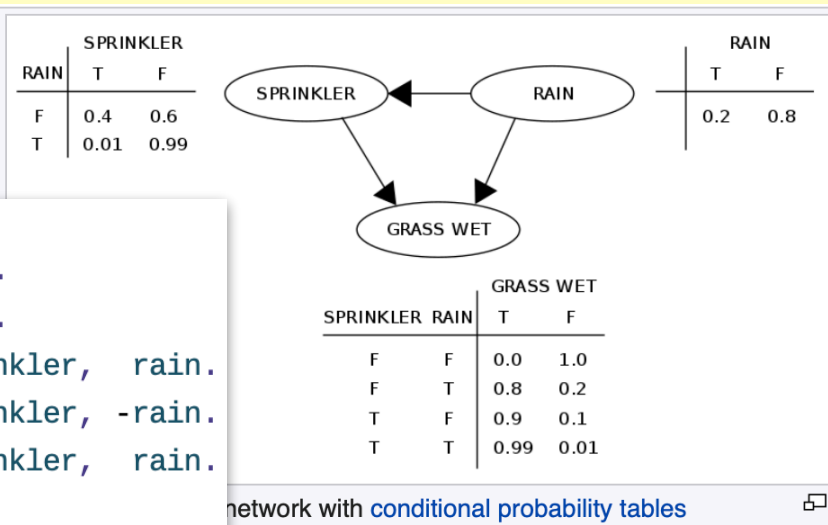
Observation (E _t)	
0.2	0.8
0.9	0.1



Probabilistic Logic Programming (Fusemate)

Bayes Network

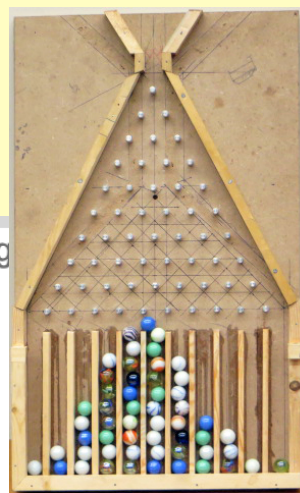
```
0.2 :: rain.
0.01 :: sprinkler :- rain.
0.4 :: sprinkler :- -rain.
0.99 :: grasswet :- sprinkler, rain.
0.9 :: grasswet :- sprinkler, -rain.
0.8 :: grasswet :- -sprinkler, rain.
?- rain | grasswet.
```



Time

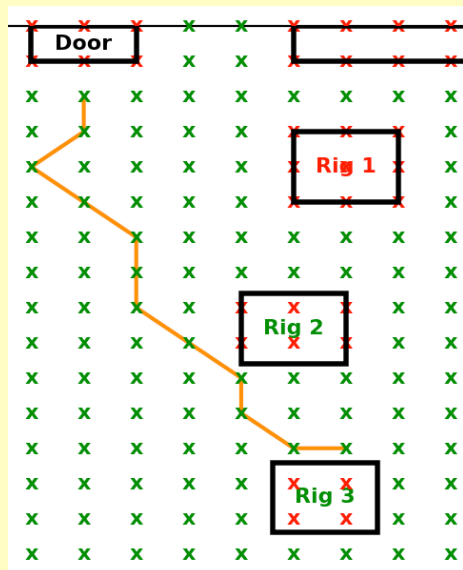
```
%% Some "random" blockage
block(1) @ 2.
block(2) @ 3.

prob(0).
(0.5 :: prob(K+1) + prob(K)) @ N+1 :-
    prob(K) @ N,
    \+ bl(K) @ N.
prob(K) @ N+1 :-
    prob(K) @ N,
    bl(K) @ N.
```



```
%% ?- prob(K) @ 4.
0.0625 :: prob(0) @ 4
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0.0625 :: prob(3) @ 4
0.0625 :: prob(4) @ 4
```

Algorithms



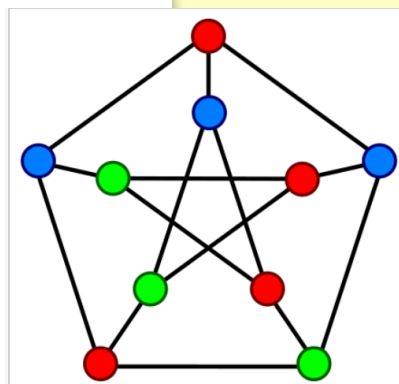
Probabilistic A*

NP-Complete Search Problems

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noncol :- color(X)=r, color(Y)=r, edge(X,Y).
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edge(1,2). edge(2,3). edge(3,1).

edge(4,1).
edge(4,2).
%edge(4,3).

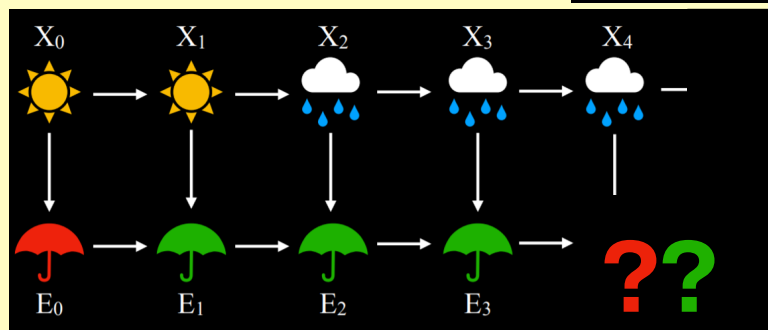
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```



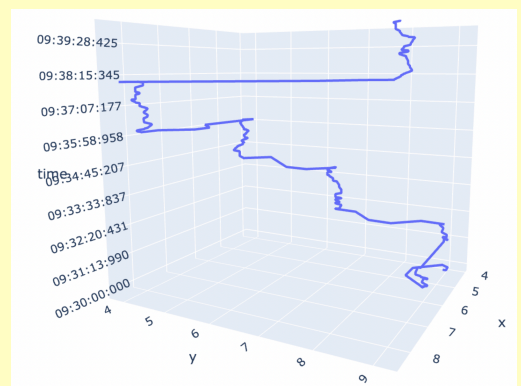
Logical variables **X** for domain objects

Hidden Markov Models

Observation (E _t)	
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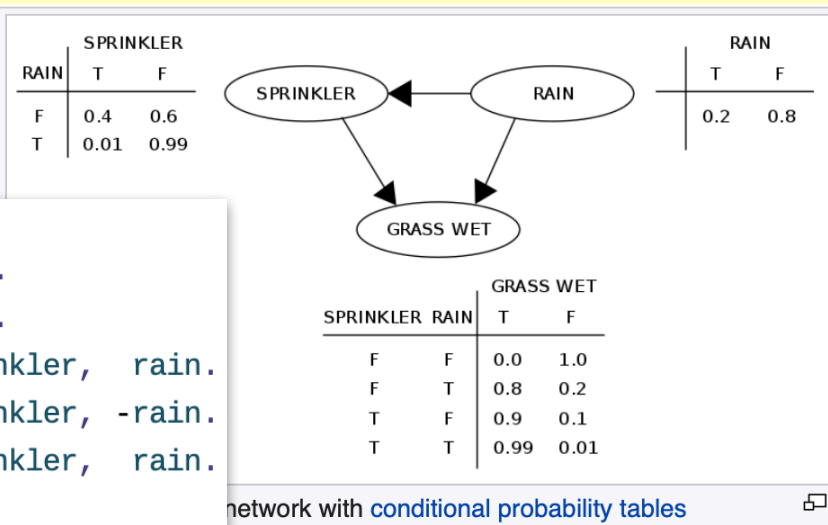
Simulation by Sampling



Probabilistic Logic Programming (Fusemate)

Bayes Network

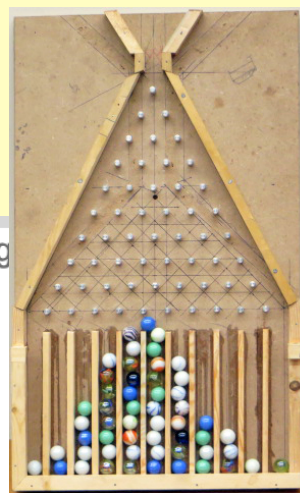
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0.8 :: grasswet :- -sprinkler, rain.
?- rain | grasswet.
```



Time

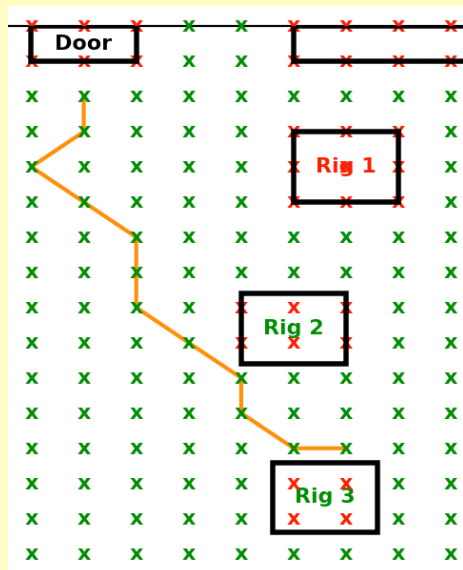
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prob(0).
(0.5 :: prob(K+1) + prob(K)) @ N+1 :-
    prob(K) @ N,
    \+ bl(K) @ N.
prob(K) @ N+1 :-
    prob(K) @ N,
    bl(K) @ N.
```



```
%% ?- prob(K) @ 4.
0.0625 :: prob(0) @ 4
0.3750 :: prob(1) @ 4
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0.0625 :: prob(3) @ 4
0.0625 :: prob(4) @ 4
```

Algorithms



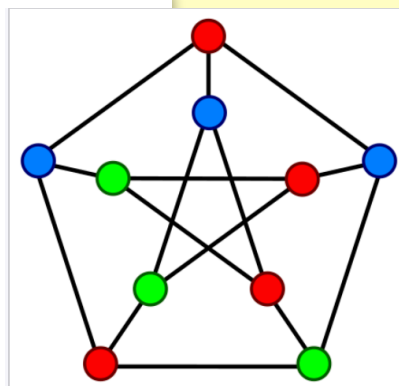
Probabilistic A*

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noncol :- color(X)=b, color(Y)=b, edge(X,Y).
edge(1,2). edge(2,3). edge(3,1).

edge(4,1).
edge(4,2).
%edge(4,3).

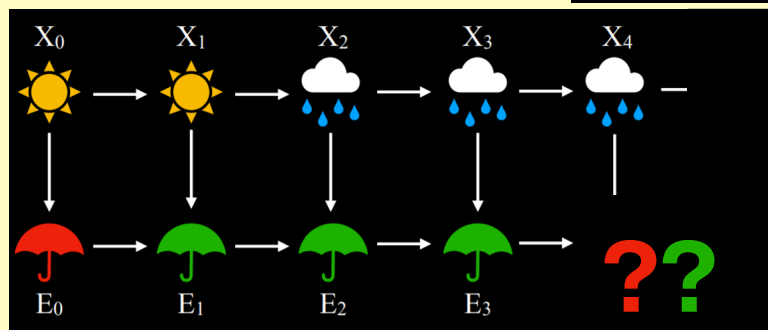
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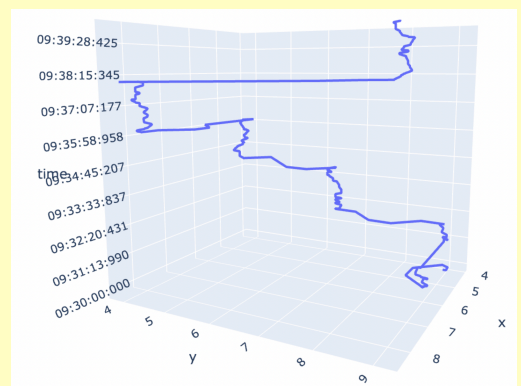
Logical variables **X** for domain objects

Hidden Markov Models

Observation (E _t)	
0.2	0.8
0.9	0.1



Simulation by Sampling



Expressivity: full history (non-Markovian); random variables are first-class citizens

Fusemate Probabilistic Logic Programming System

Implementation in Python

(From earlier versions in Scala)

Two-way interface Python \leftrightarrow Fusemate

Python data structures available in Fusemate

Logic program can be written as Python functions

Efficient probabilistic inference

Default negation via well-founded model

Rules cannot change past states

Two-phase inference algorithm

- Phase 1 “grounding”
 - Removal of first-order variables
 - > Bayes-net like program (may contain cycles)
- Phase 2 inference/sampling
 - Top-down variable elimination with caching of results

Strong Python integration

```
def weather_0():  
    return {'rainy': 0.5, 'sunny': 0.5}  
  
def weather_Tp1(weather_T):  
    return {'rainy': {'rainy': 0.8, 'sunny': 0.2},  
            'sunny': {'rainy': 0.2, 'sunny': 0.8}}\  
    [weather_T]  
  
def obs_T(weather_T):  
    return {'rainy': {'shop': 0.8, 'clean': 0.2},  
            'sunny': {'shop': 0.2, 'walk': 0.8}}\  
    [weather_T]
```

Fusemate Probabilistic Logic Programming System

Implementation in Python

(From earlier versions in Scala)

Two-way interface Python \leftrightarrow Fusemate

Python data structures available in Fusemate

Logic program can be written as Python functions

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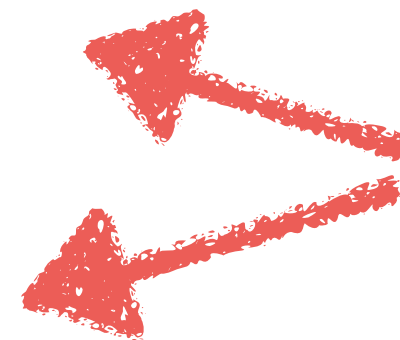
Two-phase inference algorithm

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- Phase 2 inference/sampling

Top-down variable elimination with caching of results

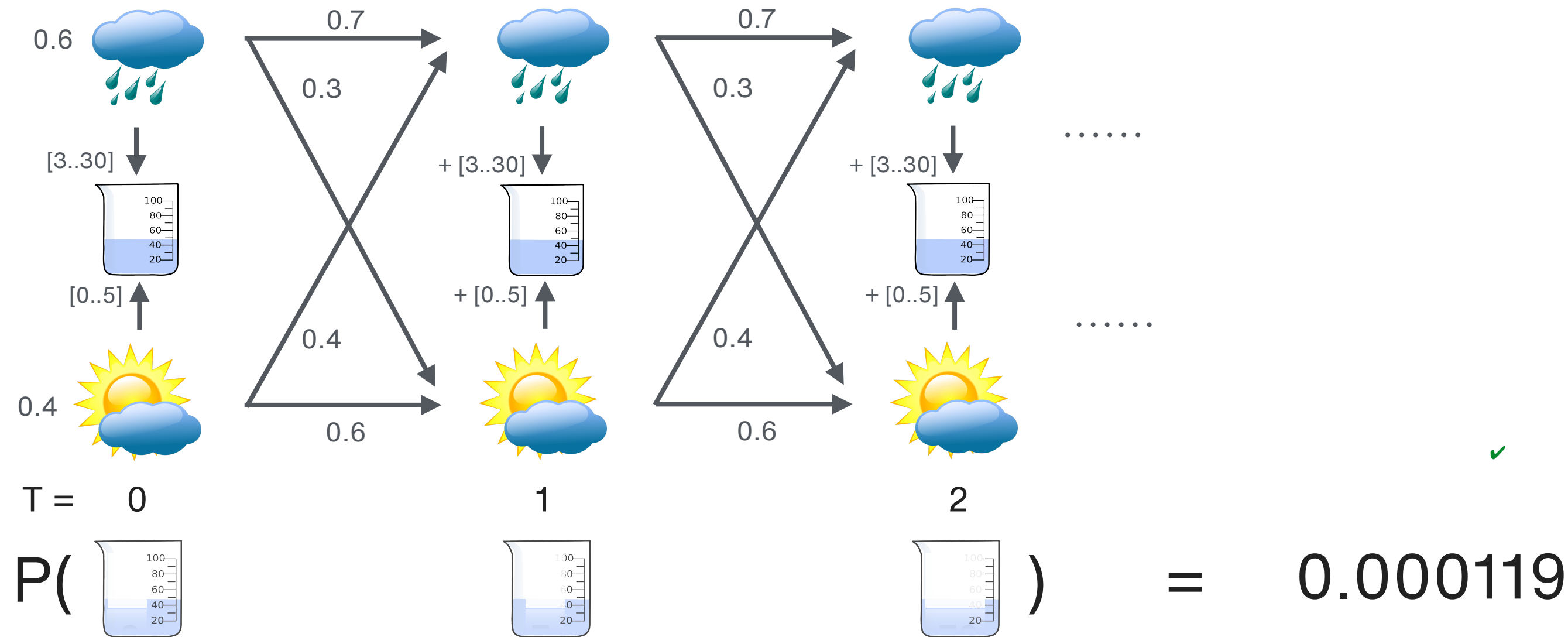
Strong Python integration

```
def weather_0():  
    return {'rainy': 0.5, 'sunny': 0.5}  
  
def weather_Tp1(weather_T):  
    return {'rainy': {'rainy': 0.8, 'sunny': 0.2},  
            'sunny': {'rainy': 0.2, 'sunny': 0.8}}\  
    [weather_T]  
  
def obs_T(weather_T):  
    return {'rainy': {'shop': 0.8, 'clean': 0.2},  
            'sunny': {'shop': 0.2, 'walk': 0.8}}\  
    [weather_T]
```

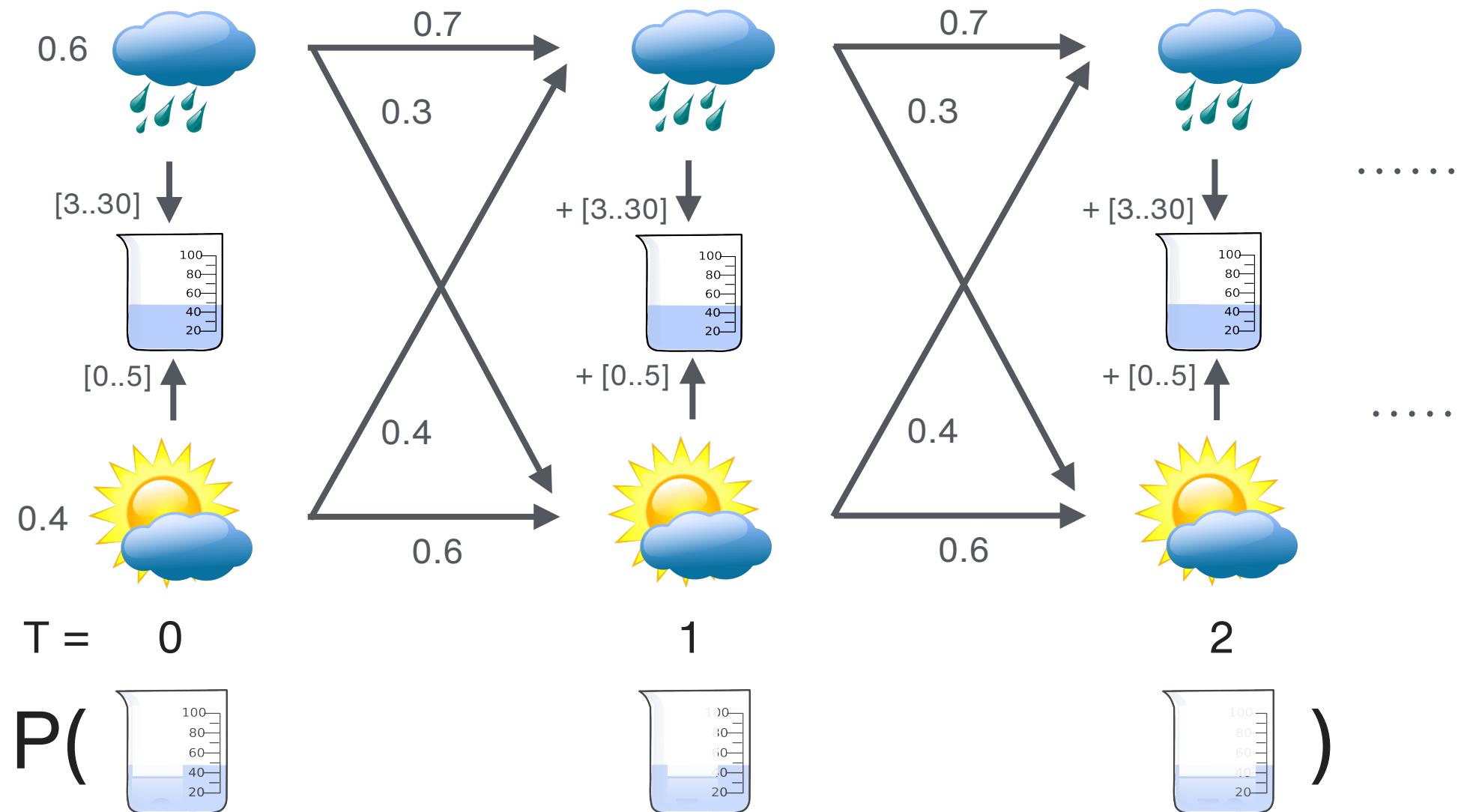


Contribution:
“Inconsistency Pruning”
for better efficiency

Fusemate Inconsistency Pruning



Fusemate Inconsistency Pruning



state ~ [[rainy, 0.6], [sunny, 0.4]] @ 0.

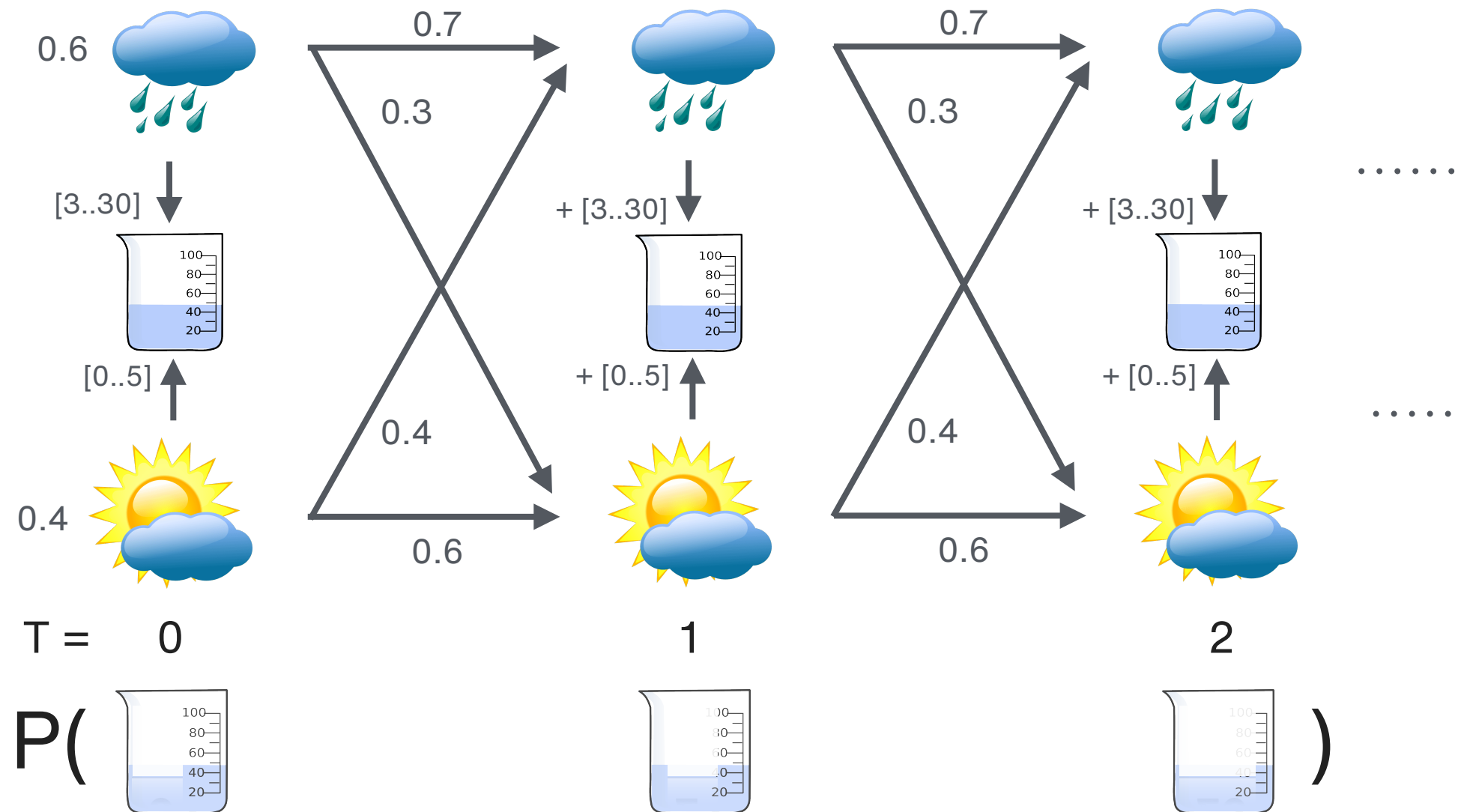
state \sim [[rainy, 0.7], [sunny, 0.3]] @ T+1 :-
state=rainy @ T.

obs ~ [R+3..R+30] @ T :-

state=rainy @ T, T > 0, obs=R @ T-1.

?- obs=0 @ 0, obs=4 @ 1, obs=20 @ 2.

Fusemate Inconsistency Pruning



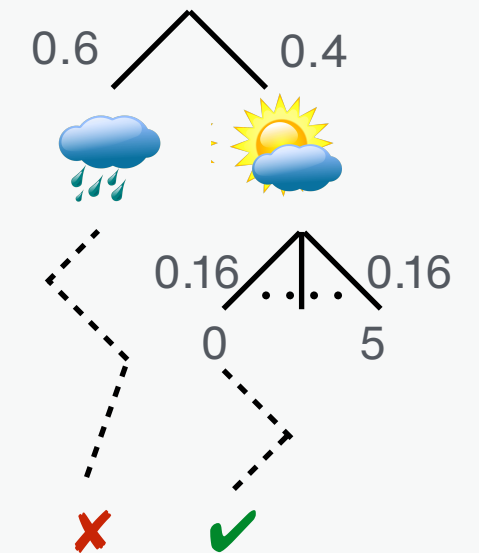
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state=rainy @ T.

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obs ~ [R+3..R+30] @ T :-
    state=rainy @ T, T > 0, obs=R @ T-1.
```

?- obs=0 @ 0, obs=4 @ 1, obs=20 @ 2.

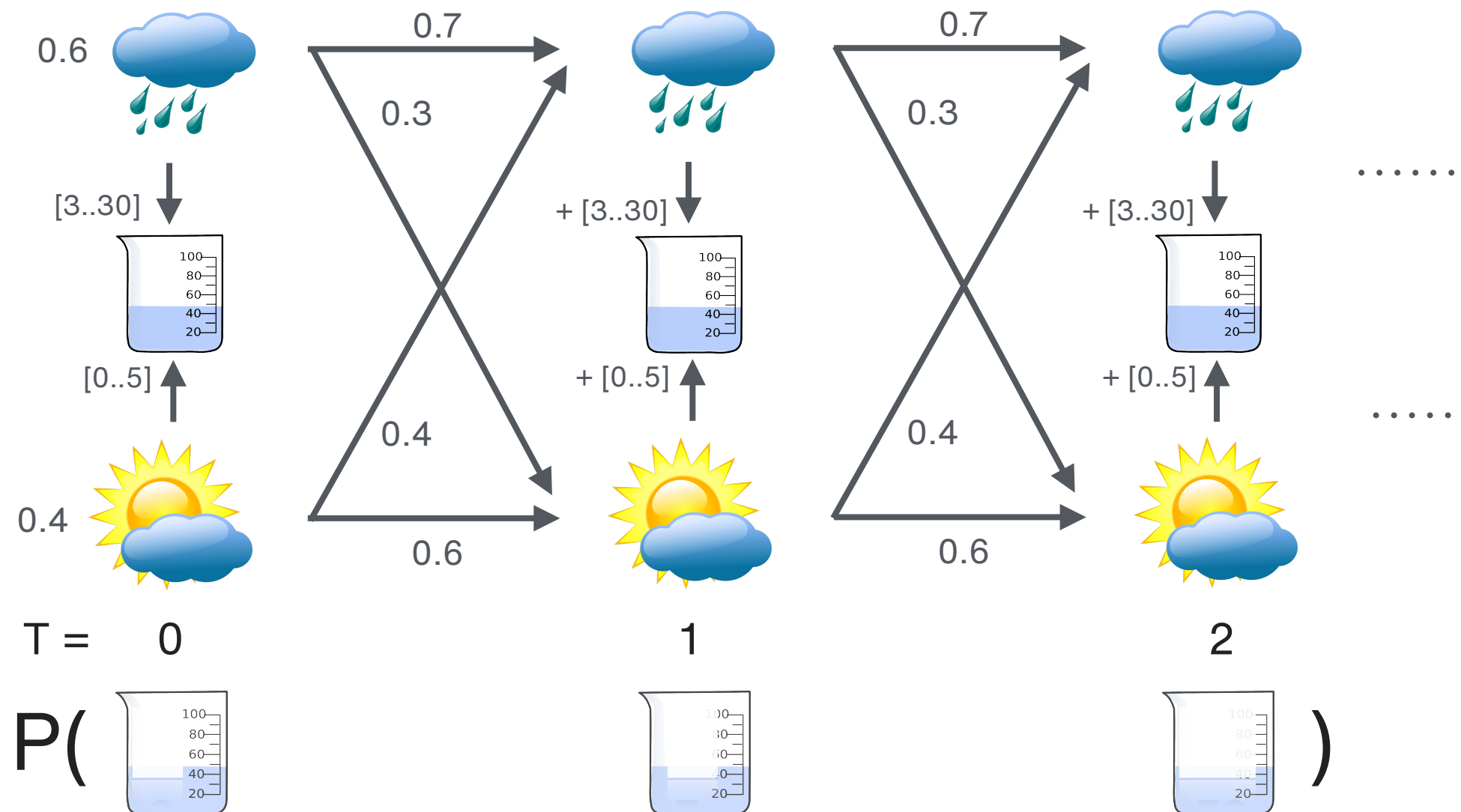
Distribution Semantics



$$P(\text{query}) = \sum_{\checkmark} P(\checkmark)$$

= 0.000119

Fusemate Inconsistency Pruning



state ~ [[rainy, 0.6], [sunny, 0.4]] @ 0.

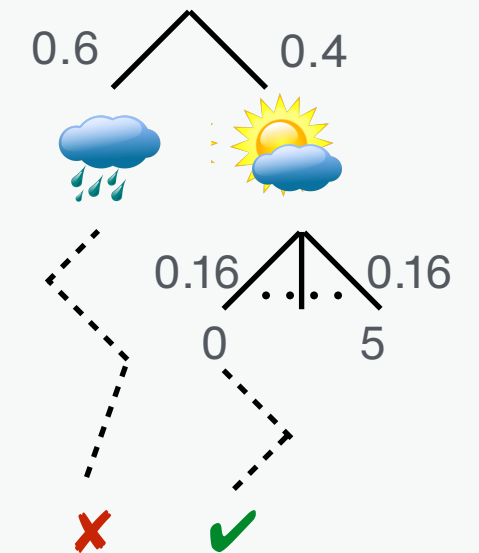
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state=rainy @ T.

obs ~ [R+3..R+30] @ T :-

state=rainy @ T, T > 0, obs=R @ T-1.

?- obs=0 @ 0, obs=4 @ 1, obs=20 @ 2.

Distribution Semantics



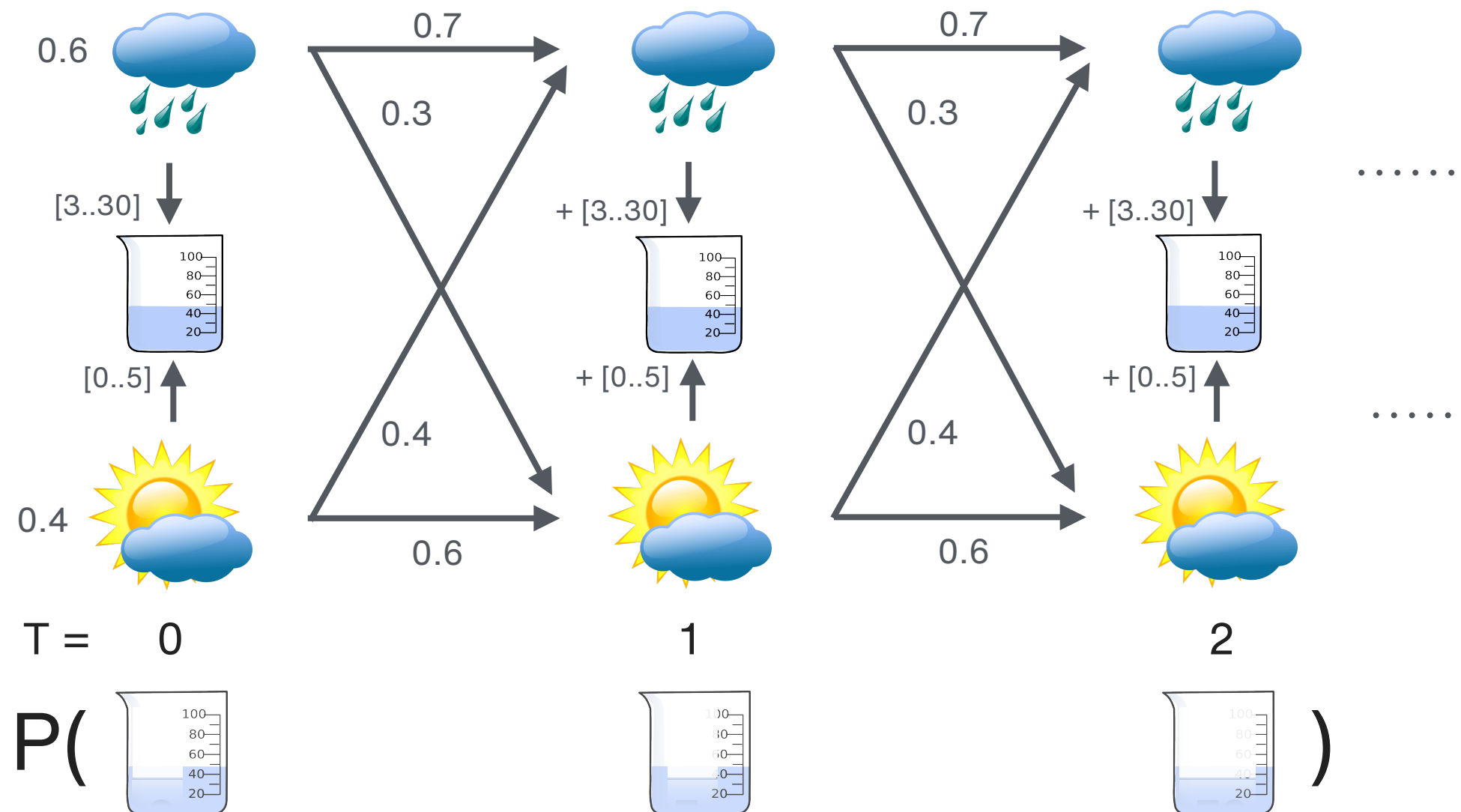
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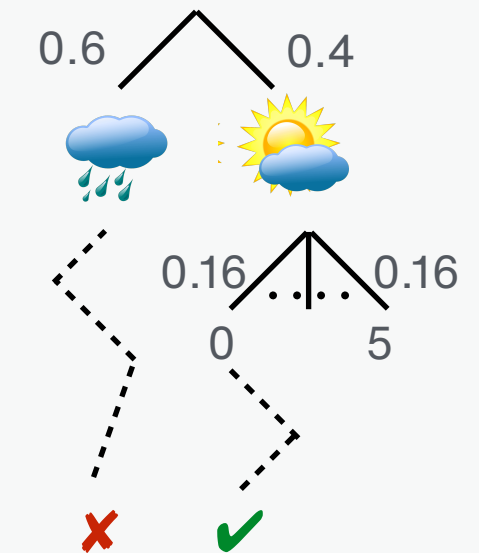
Computing query success probabilities

- (1) Program grounding (\approx Bayes net)
- (2) Query probability (marginal probability by var. elim.)

Fusemate Inconsistency Pruning



Distribution Semantics



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state ~ [[rainy, 0.6], [sunny, 0.4]] @ 0.

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state=rainy @ T.

obs ~ [R+3..R+30] @ T :-

state=rainy @ T, $T > 0$, obs=R @ T-1.

?- obs=0 @ 0, obs=4 @ 1, obs=20 @ 2.

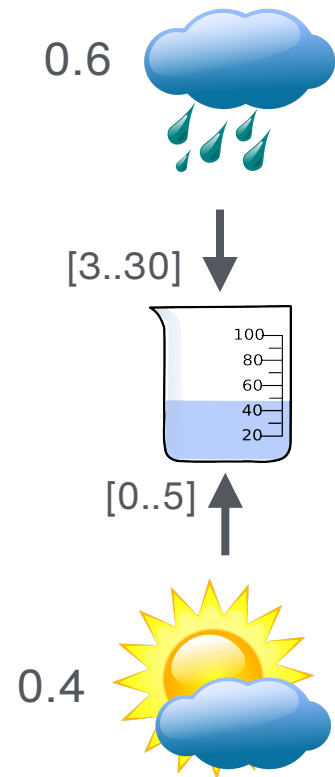
Computing query success probabilities

- (1) Program grounding (\approx Bayes net)
- (2) Query probability (marginal probability by var. elim.)

Naive (1): too many rules (quadratic in this case)

Solution: “Inconsistency Pruning”

Efficiency by Inconsistency Pruning



(Already grounded) program rules $T = 0$

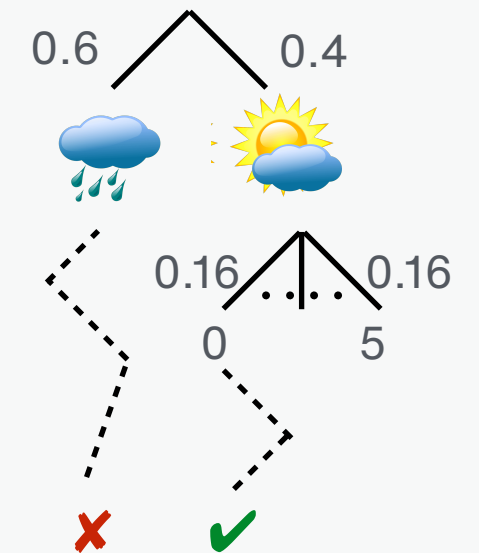
$\text{state} \sim [[\text{rainy}, 0.6], [\text{sunny}, 0.4]] @ 0.$

$\text{obs} \sim [3..30] @ 0 :- \text{state}=\text{rainy} @ 0.$

$\text{obs} \sim [0..5] @ 0 :- \text{state}=\text{sunny} @ 0.$

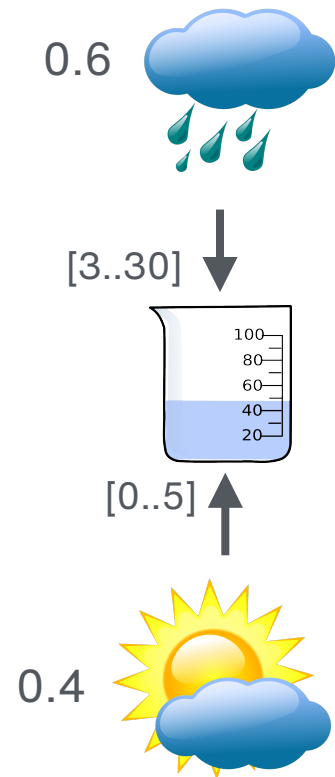
$?- \text{obs}=0 @ 0, \text{obs}=2 @ 1, \text{obs}=20 @ 2.$

Distribution Semantics



$$P(\text{query}) = \sum P(\checkmark)$$

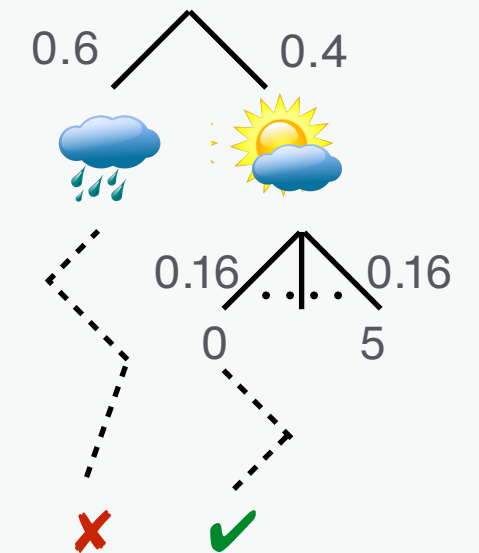
Efficiency by Inconsistency Pruning



In increasing time order:

- Ground out program over current domain
- Query regression, inconsistency pruning
- Extend current domain with \cup heads

Distribution Semantics



(Already grounded) program rules $T = 0$

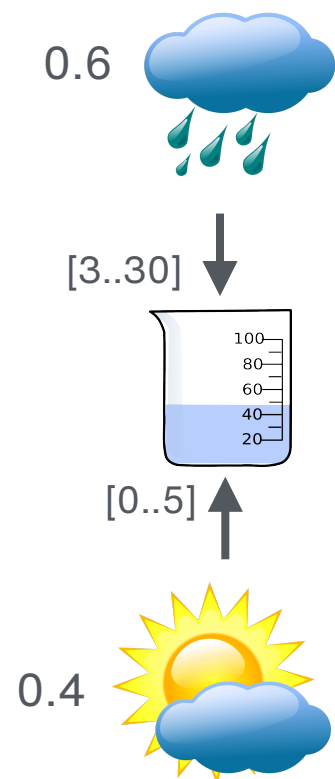
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obs \sim [3..30] @ 0 :- state=rainy @ 0.

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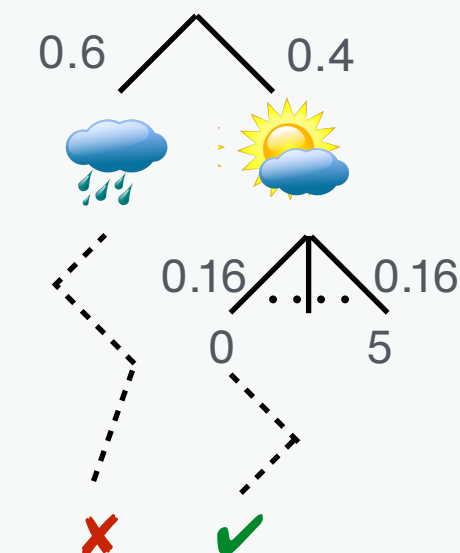
Efficiency by Inconsistency Pruning



In increasing time order:

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Distribution Semantics



$$P(\text{query}) = \sum P(\checkmark)$$

(Already grounded) program rules $T = 0$

state \sim [[rainy, 0.6], [sunny, 0.4]] @ 0.

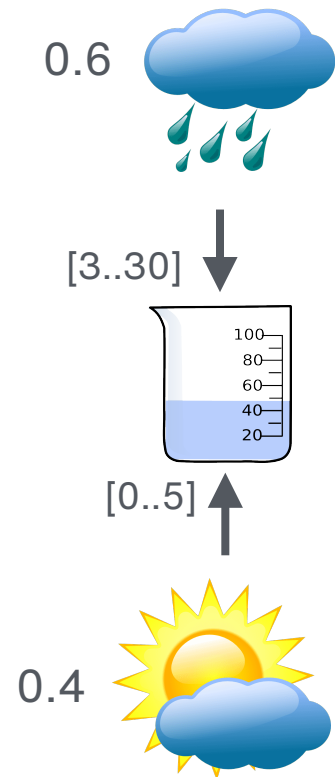
obs \sim [3..30] @ 0 :- state=rainy @ 0.

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Strengthen query by regression

?- obs=0 @ 0, obs=2 @ 1, obs=20 @ 2, state=sunny @ 0.

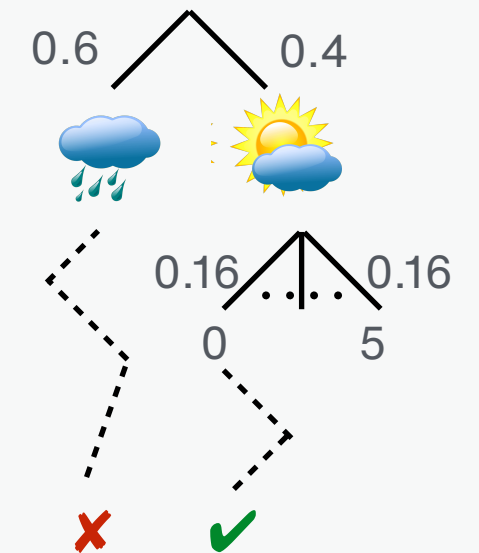
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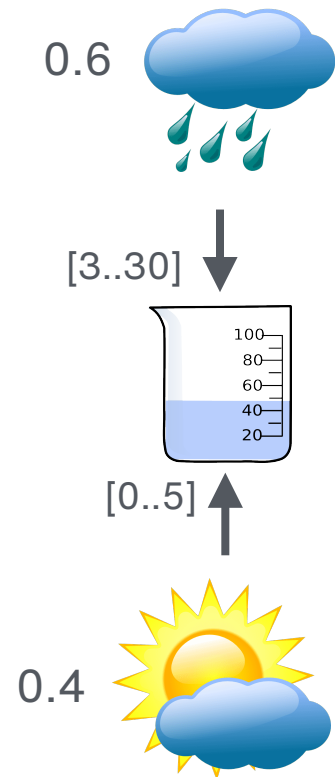
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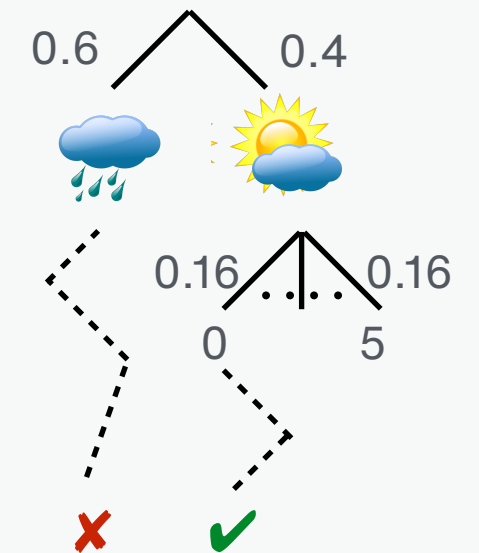
Efficiency by Inconsistency Pruning



In increasing time order:

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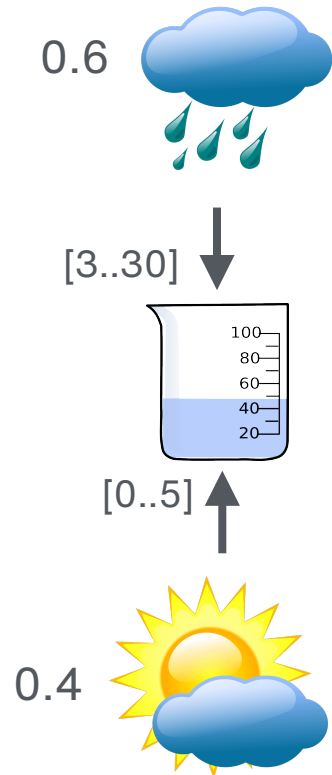
~~obs \sim [3..30] @ 0 :- state=rainy @ 0.~~ IP pruning

obs \sim [0..5] @ 0 :- state=sunny @ 0.

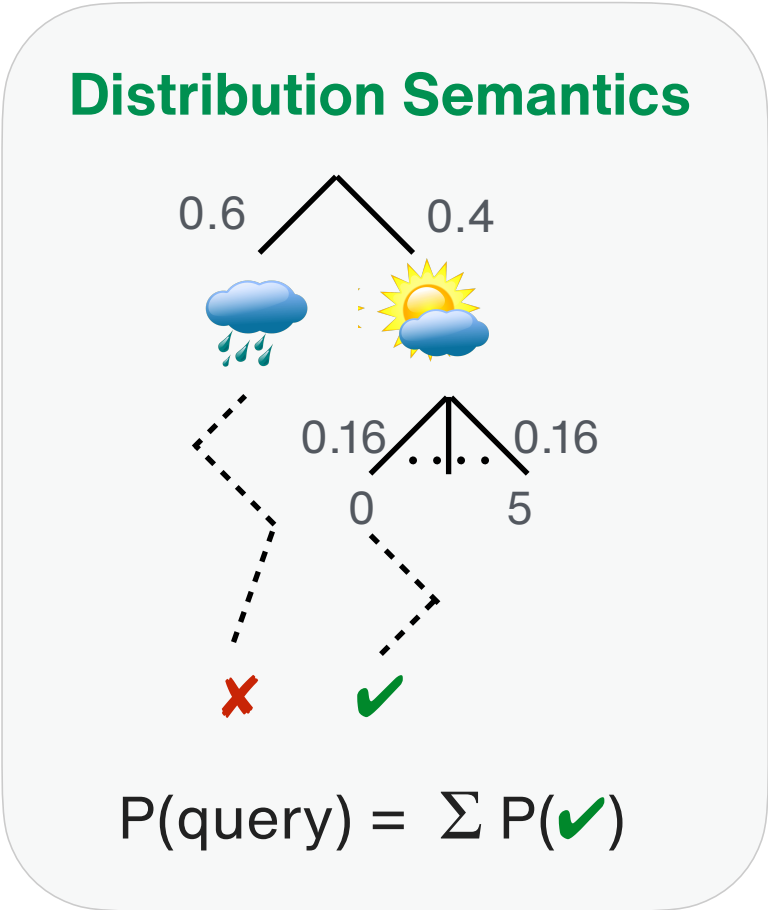
Strengthen query by regression

?- obs=0 @ 0, obs=2 @ 1, obs=20 @ 2, state=sunny @ 0.

Efficiency by Inconsistency Pruning



- In increasing time order:
- Ground out program over current domain
 - Query regression, inconsistency pruning
 - Extend current domain with \cup heads



(Already grounded) program rules $T = 0$



Domain after $T = 0$

state ~ [[rainy, 0.6], [sunny, 0.4]] @ 0.

~~obs ~ [3..30] @ 0 :- state=rainy @ 0.~~ IP pruning

obs ~ [0..5] @ 0 :- state=sunny @ 0.

state = rainy @ 0.

state = sunny @ 0.

obs = 0 @ 0.

obs = 1 @ 0.

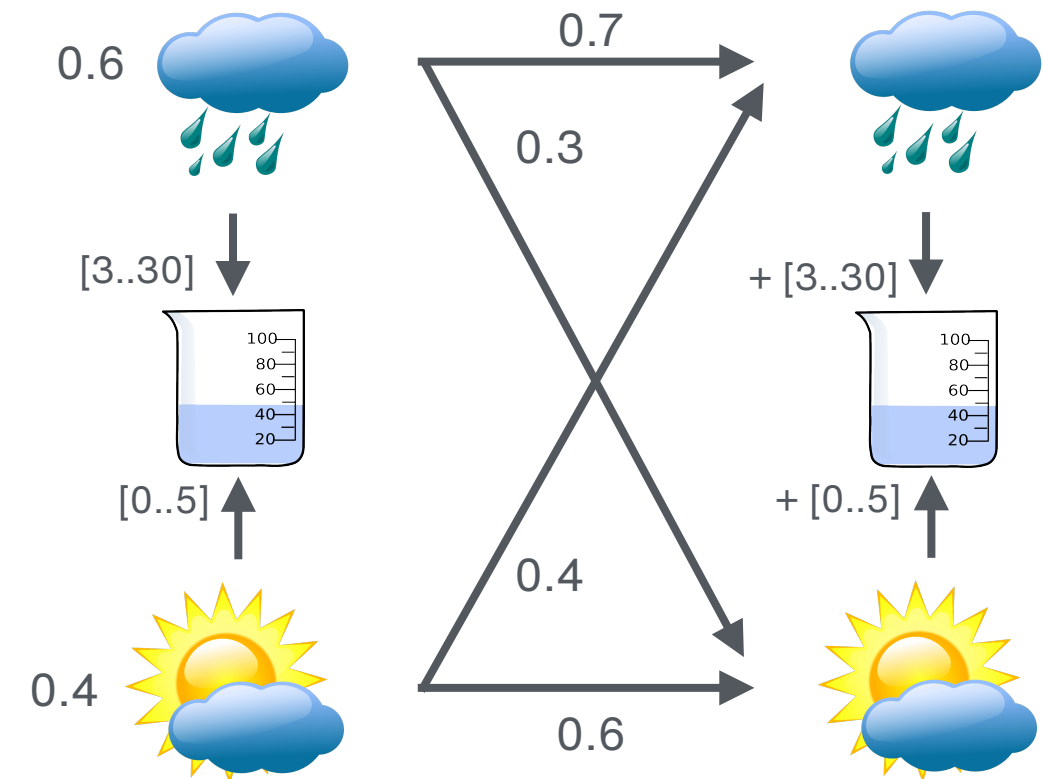
:

obs = 5 @ 0.

Strengthen query by regression

?- obs=0 @ 0, obs=2 @ 1, obs=20 @ 2, state=sunny @ 0.

Efficiency by Inconsistency Pruning



- In increasing stratification order:

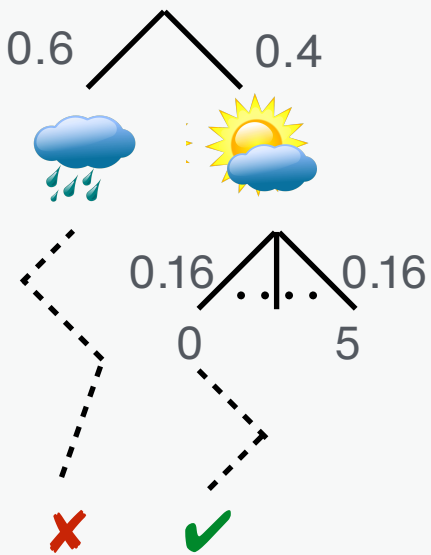
 - Ground out program over current domain
 - Query regression, inconsistency pruning
 - Extend current domain with U heads

Domain T = 1

obs = 0 @ 0.
obs = 1 @ 0.
:
obs = 5 @ 0.
state = rainy @ 1.
state = sunny @ 1.

?- obs=0 @ 0, obs=4 @ 1, obs=20 @ 2, state=sunny @ 0.

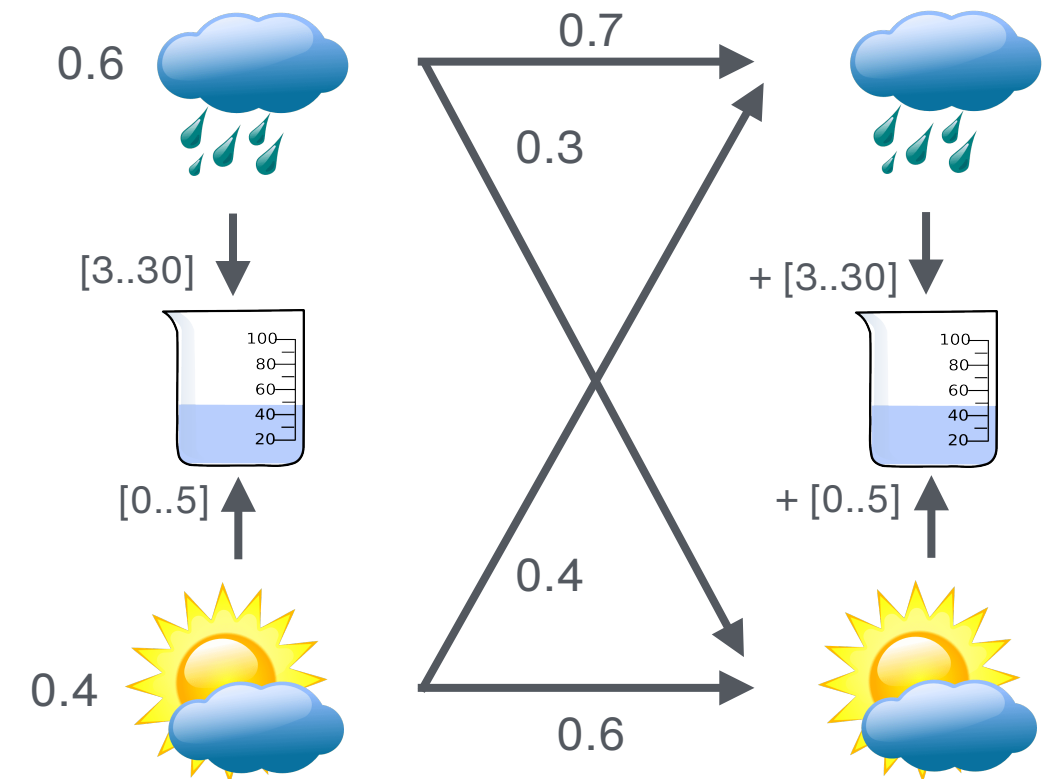
Distribution Semantics



$P(\text{query}) = \sum P(\checkmark)$

obs ~ [R+3..R+30] @ T :-
state=rainy @ T,
T > 0,
obs=R @ T-1.

Efficiency by Inconsistency Pruning



- In increasing stratification order:

 - Ground out program over current domain
 - Query regression, inconsistency pruning
 - Extend current domain with \cup heads

Domain $T = 1 \longrightarrow$

```

obs = 0 @ 0.
obs = 1 @ 0.
:
obs = 5 @ 0.
state = rainy @ 1.
state = sunny @ 1.

```

Grounded program rules $T = 1$

```

obs ~ [3..30] @ 1 :- state=rainy @ 1, obs=0 @ 0.
obs ~ [4..31] @ 1 :- state=rainy @ 1, obs=1 @ 0.
:
obs ~ [0..5] @ 1 :- state=sunny @ 1, obs=0 @ 0.
obs ~ [1..6] @ 1 :- state=sunny @ 1, obs=1 @ 0.
:

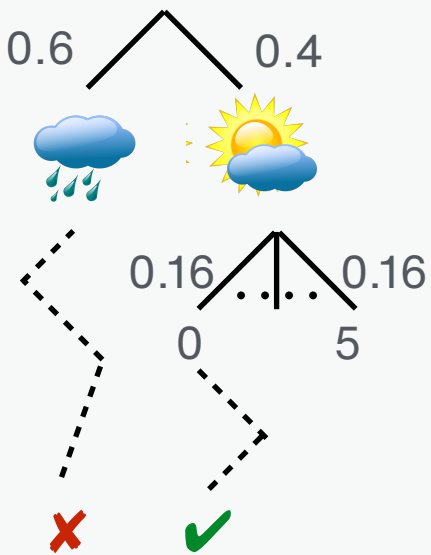
```

```

?- obs=0 @ 0, obs=4 @ 1, obs=20 @ 2, state=sunny @ 0.

```

Distribution Semantics



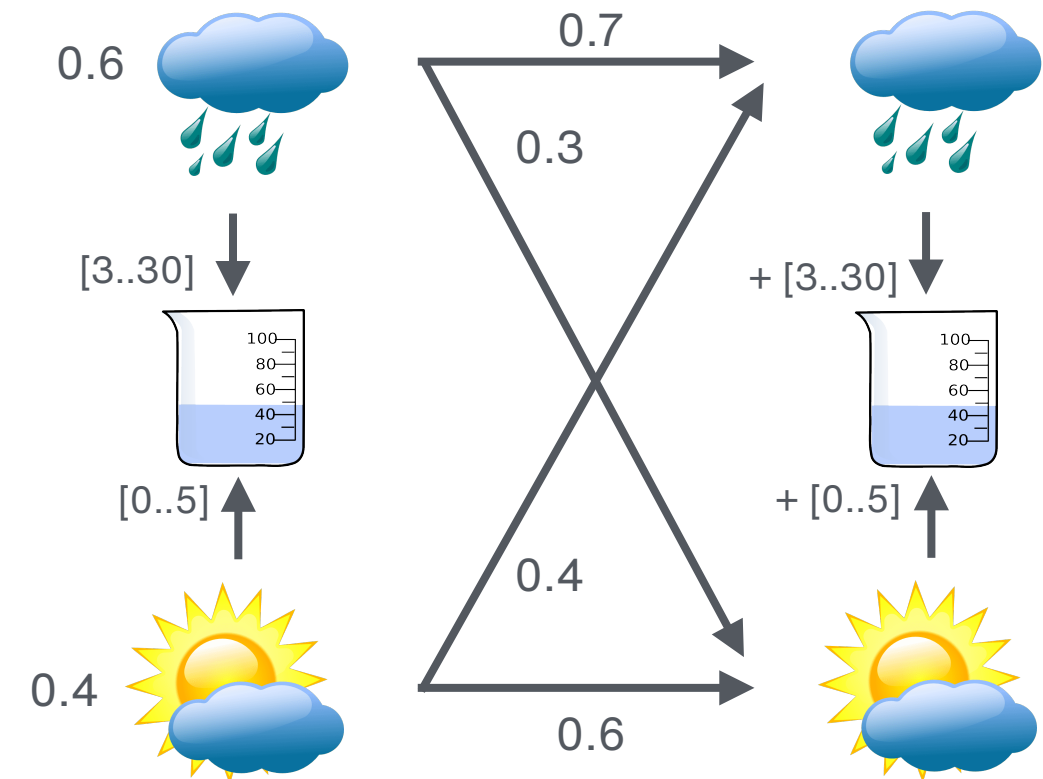
$$P(\text{query}) = \sum P(\checkmark)$$

```

obs ~ [R+3..R+30] @ T :-
    state=rainy @ T,
    T > 0,
    obs=R @ T-1.

```

Efficiency by Inconsistency Pruning



- In increasing stratification order:

 - Ground out program over current domain
 - Query regression, inconsistency pruning
 - Extend current domain with \cup heads

Domain $T = 1 \longrightarrow$

```

obs = 0 @ 0.
obs = 1 @ 0.
:
obs = 5 @ 0.
state = rainy @ 1.
state = sunny @ 1.

```

Grounded program rules $T = 1$

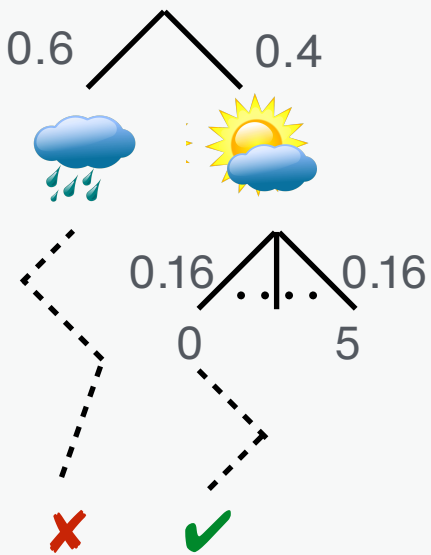
```

obs ~ [3..30] @ 1 :- state=rainy @ 1, obs=0 @ 0.
obs ~ [4..31] @ 1 :- state=rainy @ 1, obs=1 @ 0.
:
obs ~ [0..5] @ 1 :- state=sunny @ 1, obs=0 @ 0.
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:

```

?- obs=0 @ 0, obs=4 @ 1, obs=20 @ 2, state=sunny @ 0.

Distribution Semantics



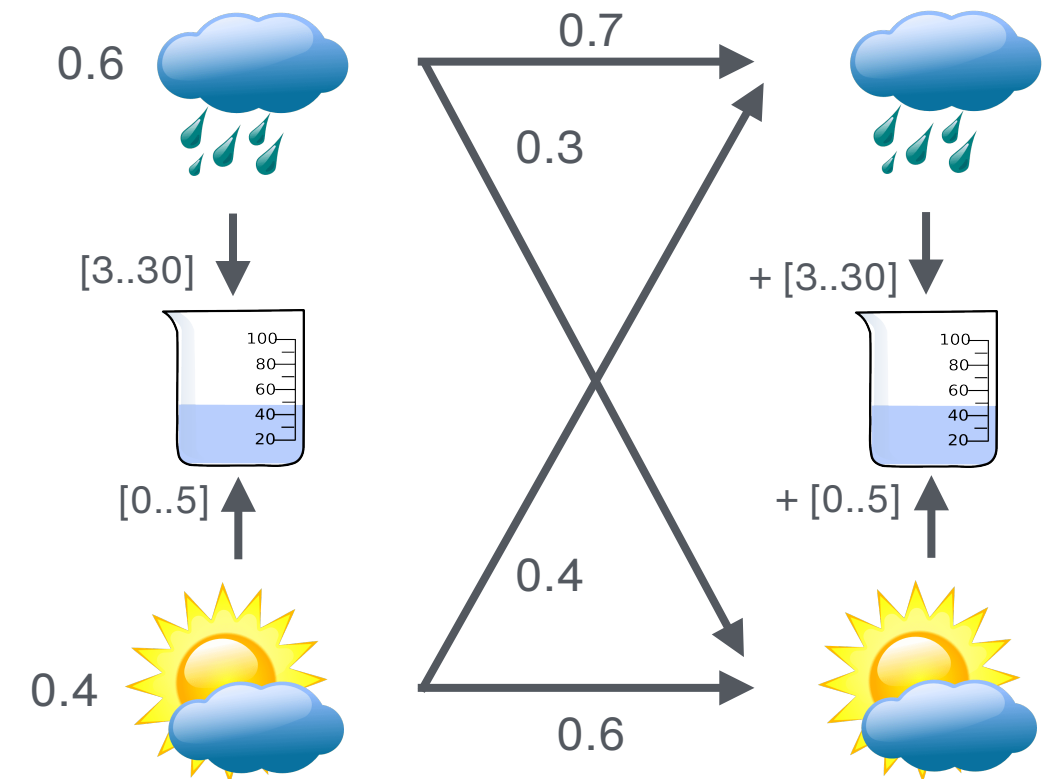
$$P(\text{query}) = \sum P(\checkmark)$$

```

obs ~ [R+3..R+30] @ T :-
    state=rainy @ T,
    T > 0,
    obs=R @ T-1.

```

Efficiency by Inconsistency Pruning



- In increasing stratification order:

 - Ground out program over current domain
 - Query regression, inconsistency pruning
 - Extend current domain with \cup heads

Domain $T = 1 \quad \longrightarrow$

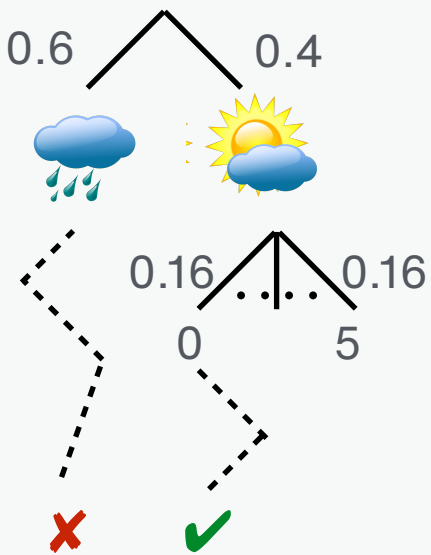
$obs = 0 @ 0.$
 $obs = 1 @ 0.$
 $:$
 $obs = 5 @ 0.$
 $state = rainy @ 1.$
 $state = sunny @ 1.$

Grounded program rules $T = 1$

$obs \sim [3..30] @ 1 :- state=rainy @ 1, obs=0 @ 0.$
 $obs \sim [4..31] @ 1 :- state=rainy @ 1, obs=1 @ 0.$
 $:$
 $obs \sim [0..5] @ 1 :- state=sunny @ 1, obs=0 @ 0.$
 $obs \sim [1..6] @ 1 :- state=sunny @ 1, obs=1 @ 0.$
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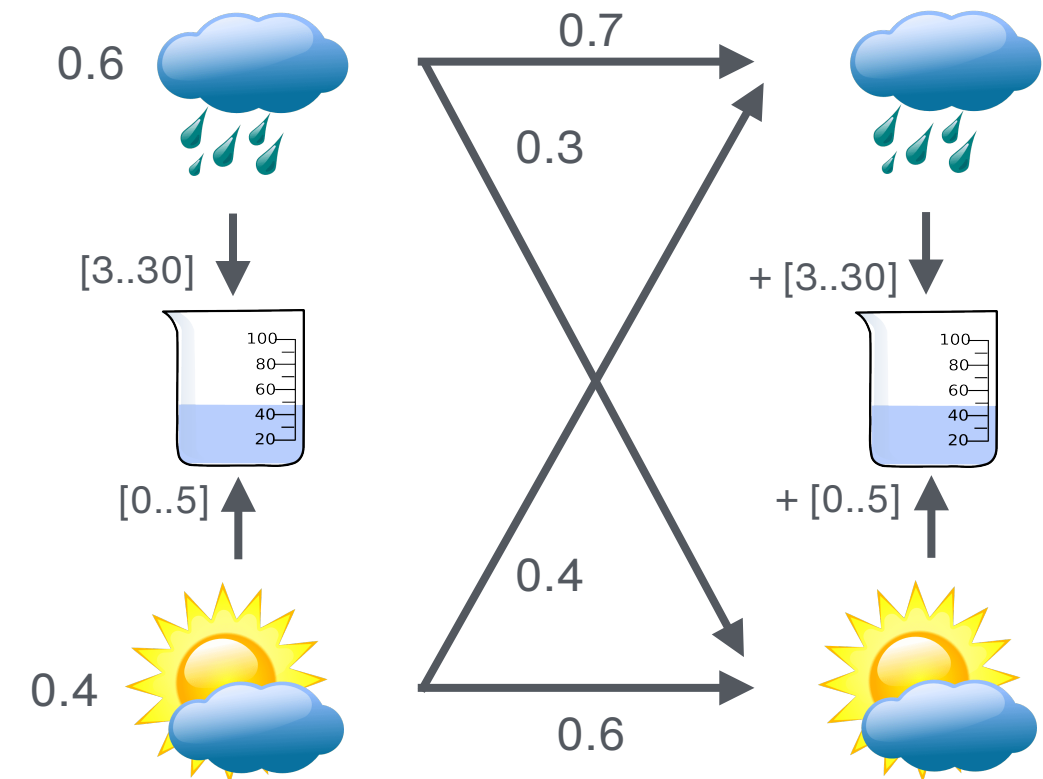
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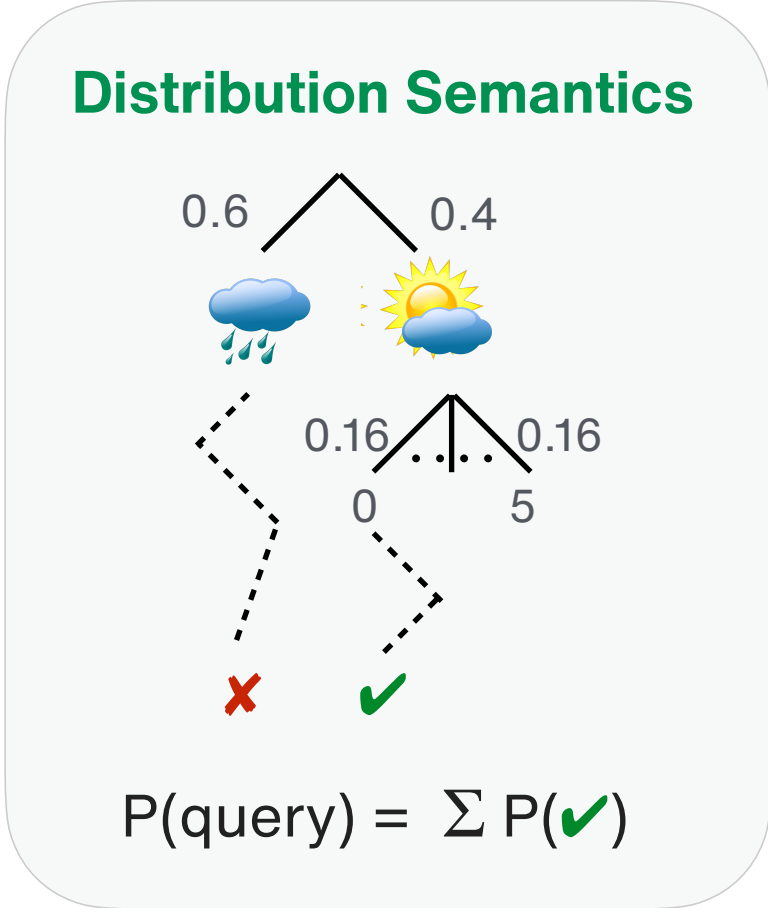
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Domain $T = 1$

→

Grounded program rules $T = 1$

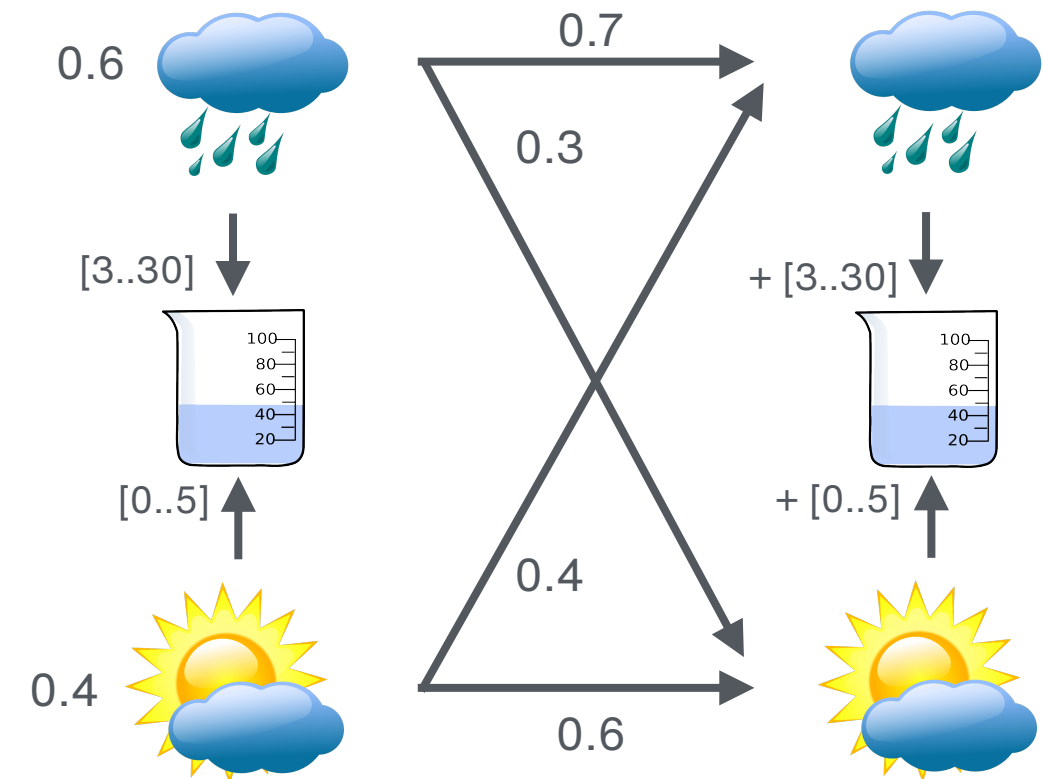
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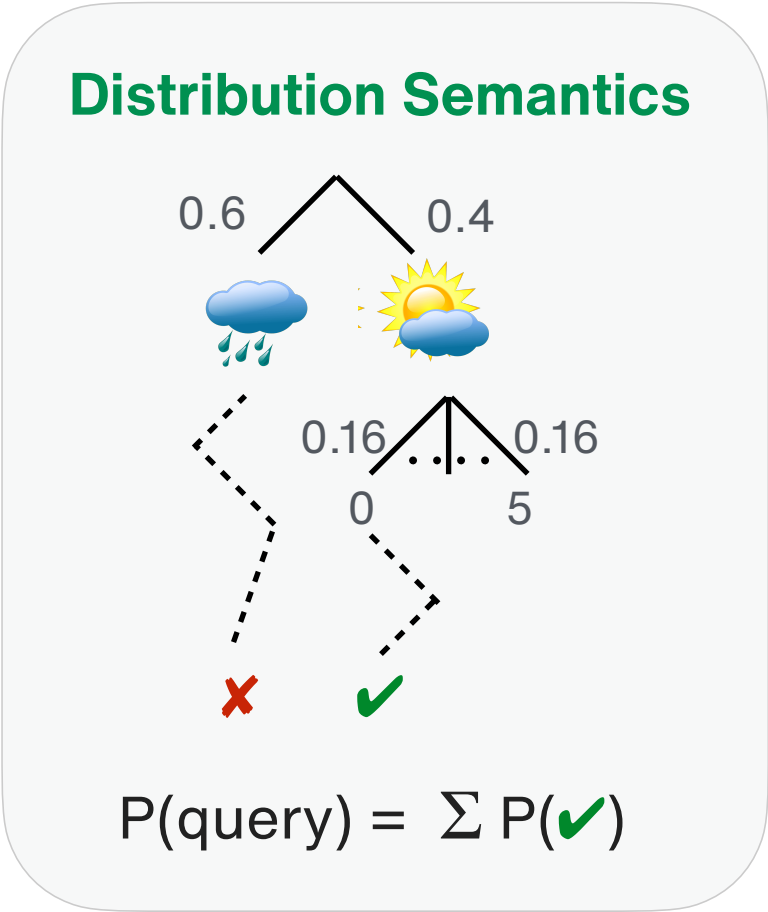
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- In increasing stratification order:

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Domain $T = 1$ \longrightarrow **Grounded program rules $T = 1$**

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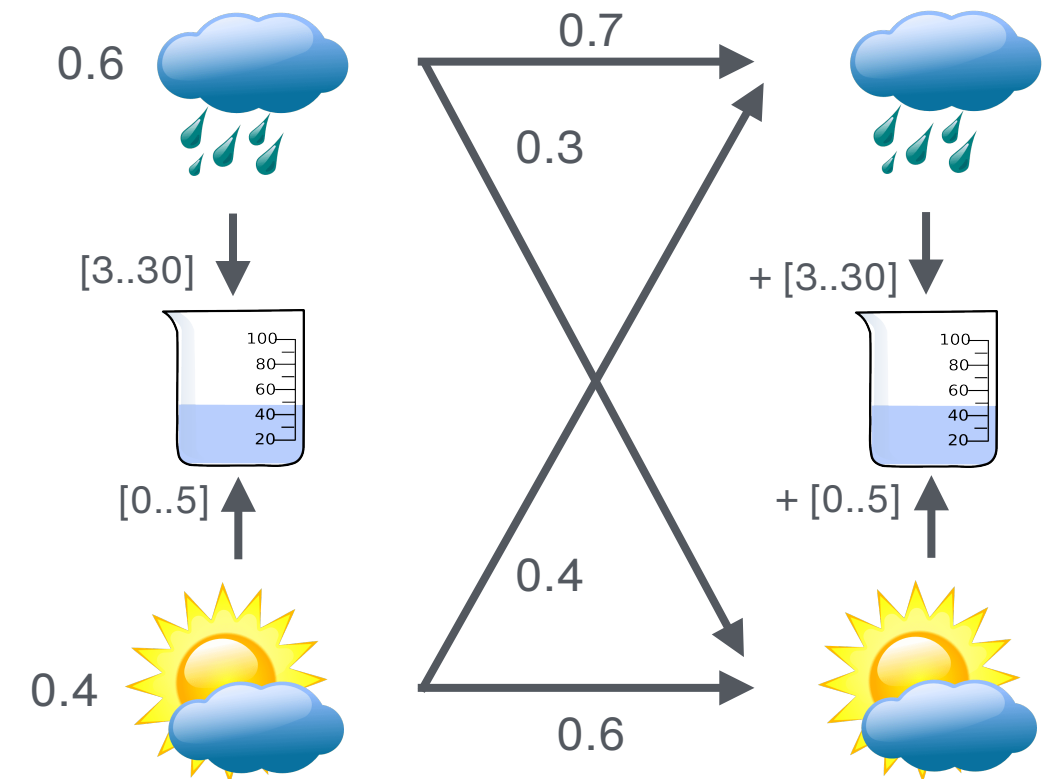
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Inconsistency pruning: 62 -> 2 rules

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Efficiency by Inconsistency Pruning



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Experimental Evaluation 1 - Hidden Markov Model

Runtime Results Fusemate vs ProbLog

Rainy/sunny example from above

%% Queries for N=3

%% Sunny

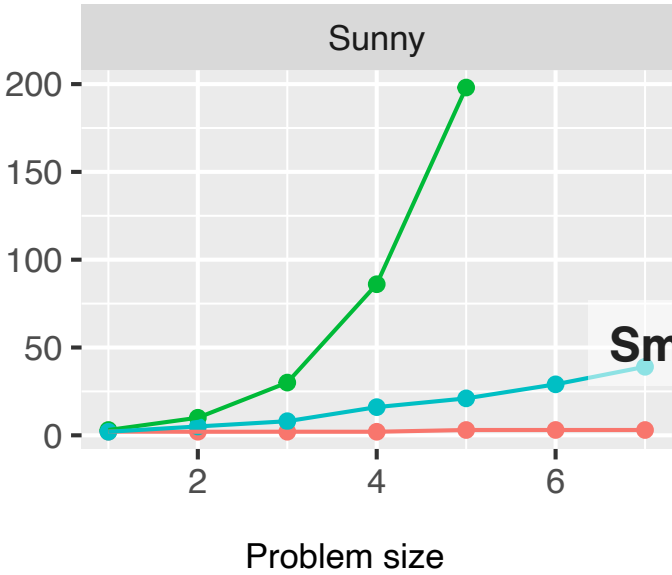
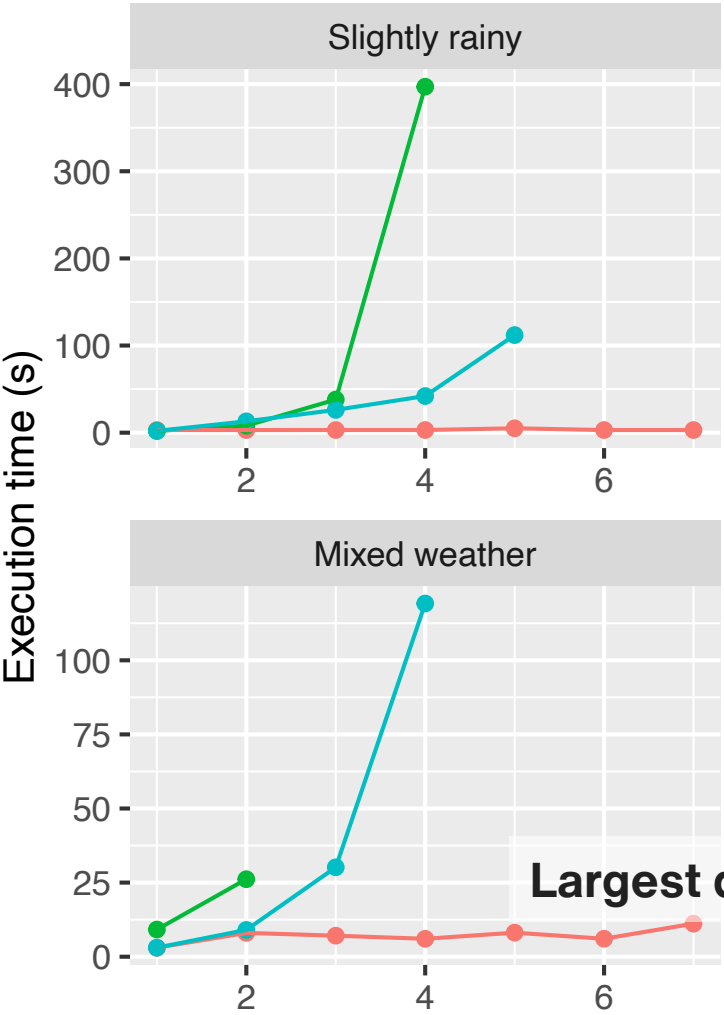
?-state=X @ 3 | obs=0 @ 1, obs=0 @ 2, obs=0 @ 3.

%% Rainy

?-state=X @ 3 | obs=4 @ 1, obs=8 @ 2, obs=12 @ 3

%% Mixed

state=X @ 3 | obs=0 @ 1, obs=4 @ 2, obs=24 @ 3.



Smallest domain

Largest domain

- Fusemate w/o Guidance
- Fusemate w/ Guidance
- ProbLog

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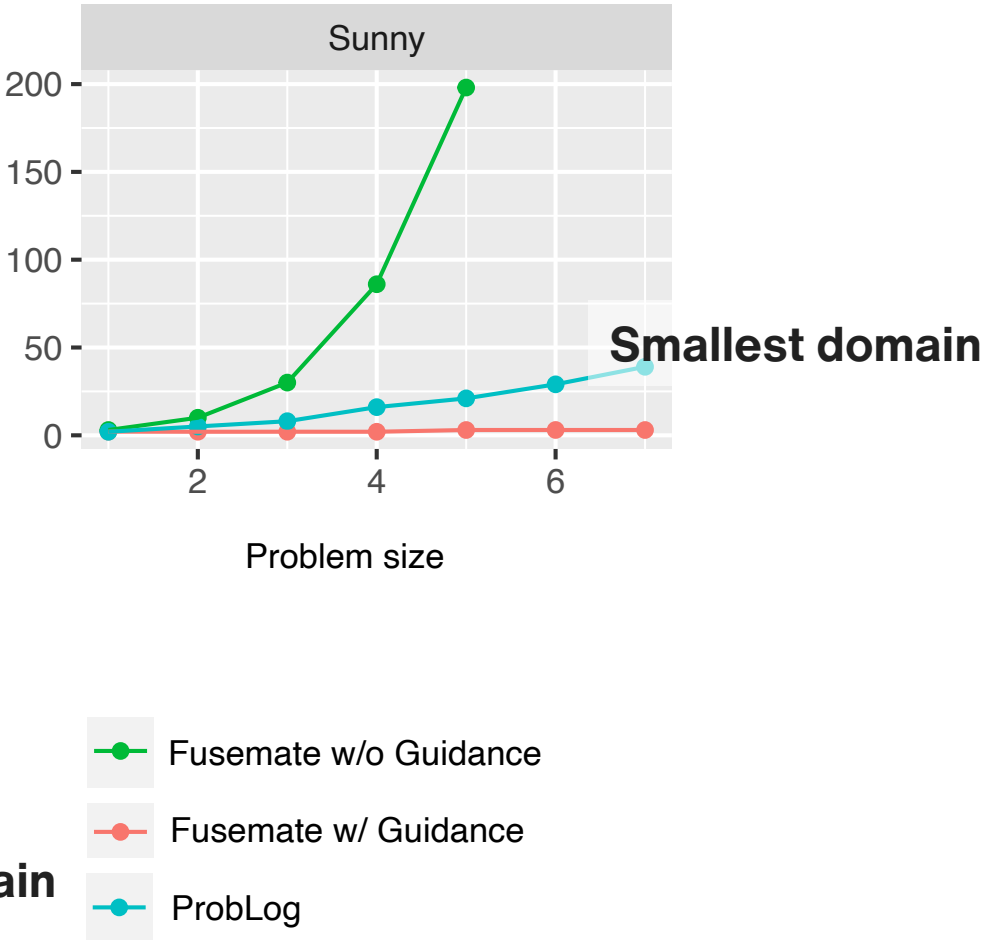
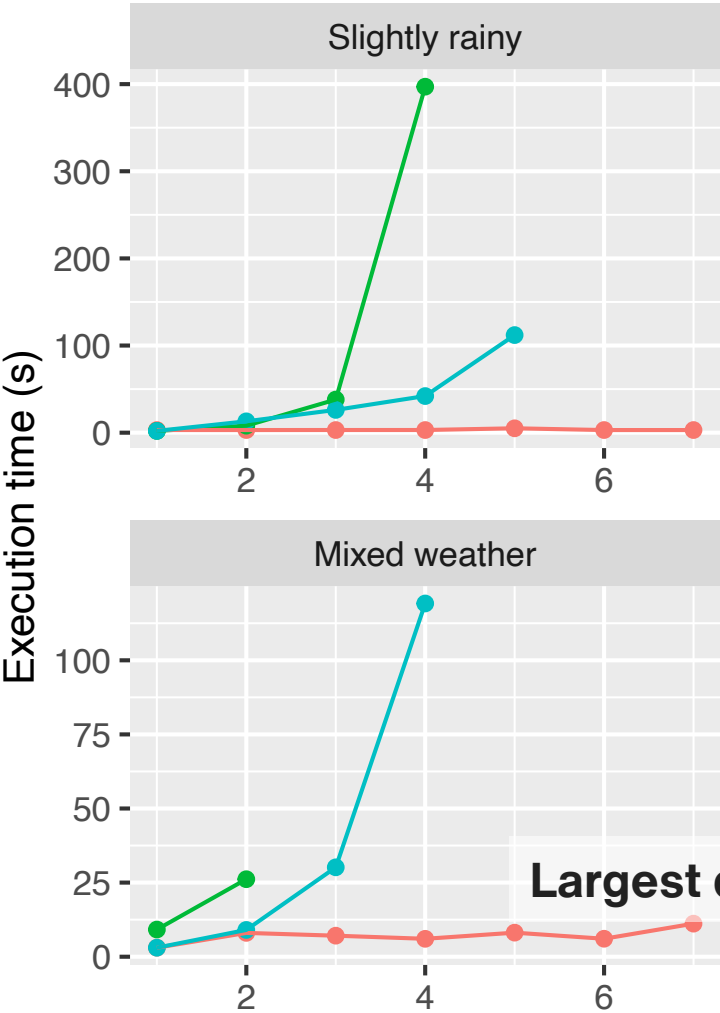
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Grounding vs Inference - Mixed Weather

N	Fusemate #ground rules		ProbLog		#ground rules
	query-guided	unguided	total time	grounding time	
2	2200	6500	9.0	8.3	53
3	2270	12900	30	19	276
4	2300	21400	119	33	499
5	2400	32000		50	682
6	2470	45000		65	839
7	2500	60000		95	1068

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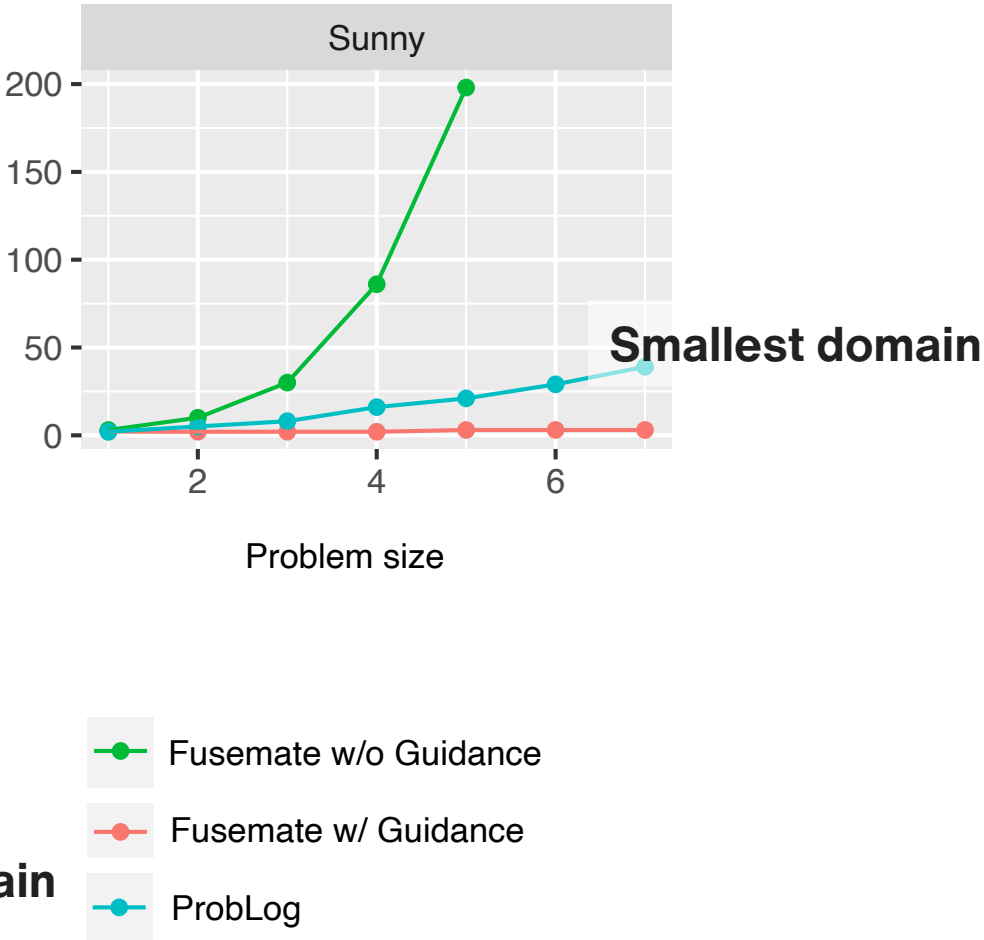
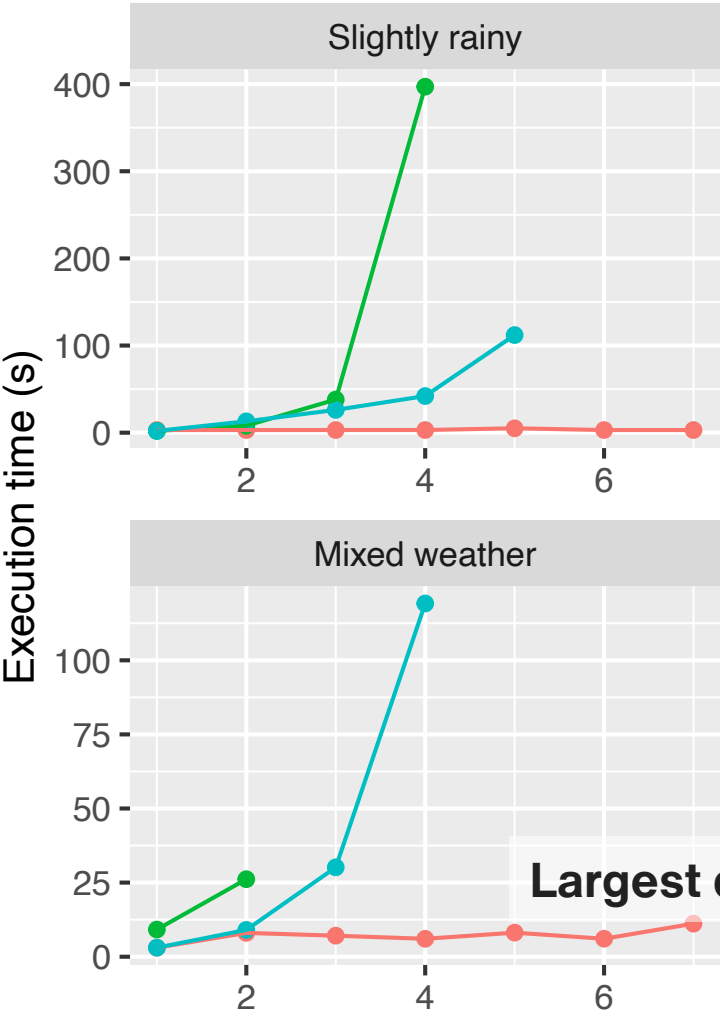
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Fusemate:
Improved grounding pays off
Inference engine implements UNA
ProbLog:
Grounding OK?
Bottleneck inference component?

Experimental Evaluation 2 - Markov Model

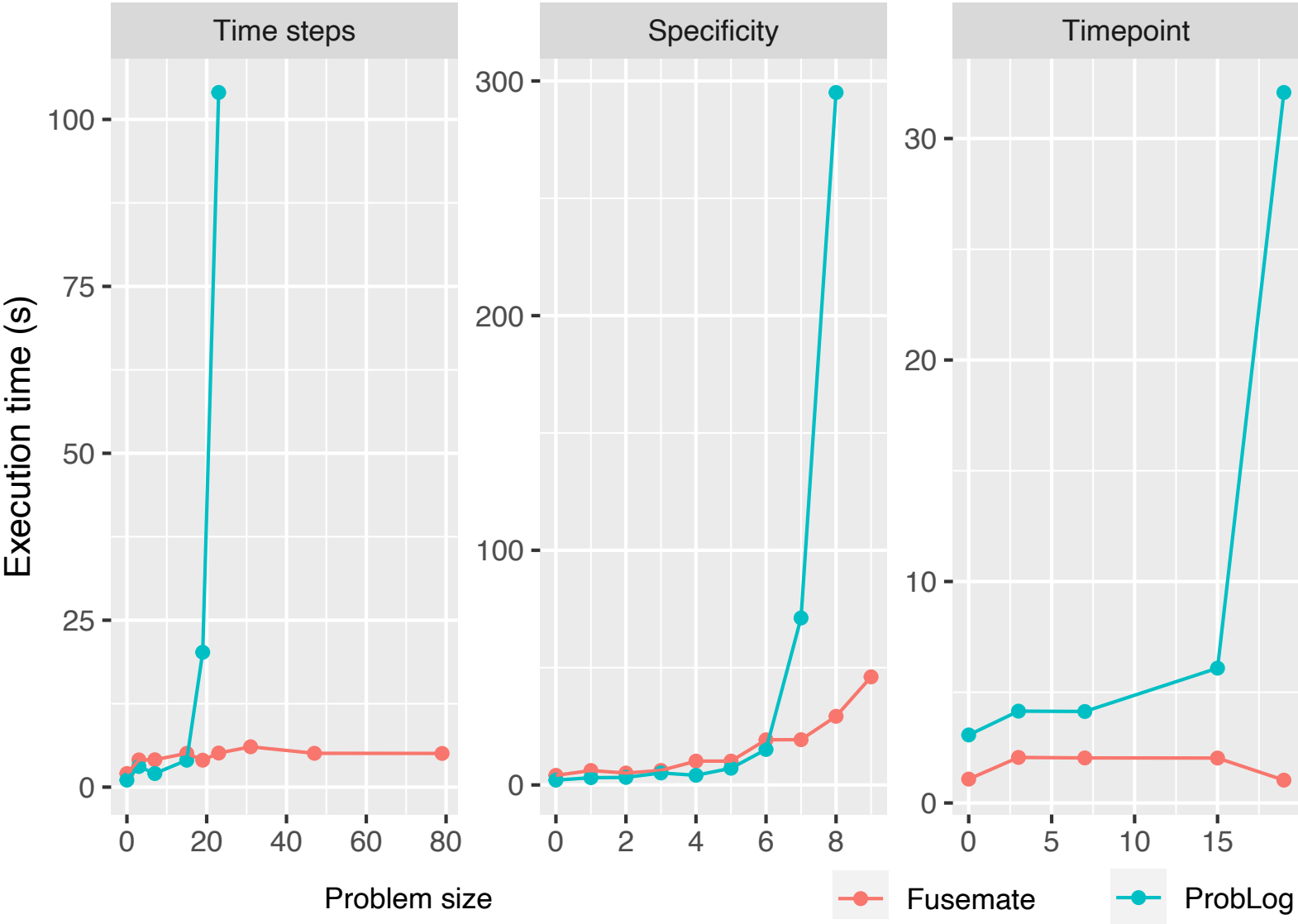
Runtime Results Fusemate vs ProbLog

```
%% Markov Model
in ~ [a, b, c] @ 0.
in ~ [[a, 0.9],[b, 0.05],
      [c, 0.05]] @ T+1 :- in=a @ T.
in ~ [[a, 0.7],[c, 0.3]] @ T+1 :- in=b @ T.
in ~ [[a, 0.8],[c, 0.2]] @ T+1 :- in=c @ T.

%% Time steps N = 20
?- in=a@0, in=a@1, ..., in=a@20.

%% Specificity, N = 7
?- in=a@0, in=a@1, in=L2@2, ..., in=L8 @ 8.

%% Timepoint, N = 20
?- in=a@23.
```



(ProbLog code from ProbLog tutorial web page)

Learning (Largely TBD in Fusemate)

Probability parameters learning

MLE, EM

Learning the structure of logic programs

Inductive Logic Programming (1970s)

Probabilistic Version [Riguzzi 2015]

Logic programs from tabular data

Probabilistic version of CART

Probabilistic decision lists [2017]

FOLD-RM [Gupta et al, ICLP 2023]

CON-FOLD [McGinness and B, ICLP 2024]

= FOLD-RM with confidence values

Very short explanations



	PassengerId	Survived	Pclass	Title	Sex	Age	SibSp	Parch	
0	1	False	3	Mr	male	22	1	0	
1	2	True	1	Mrs	female	38	1	0	
2	3	True	3	Miss	female	26	0	0	STON/C
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survived(X) :- not perished(X).
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Part 1

- Probabilistic
- Logic
- Programming
- Fusemate Implementation

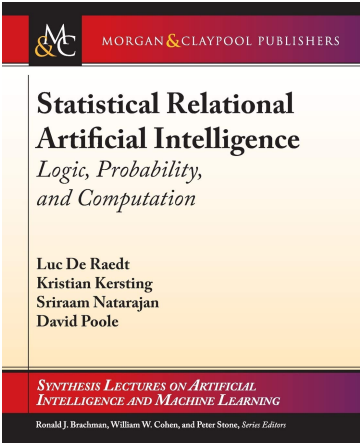
Part 2

- **LLMs + Logic (Programming)**
- **Neural Networks + Logic (Programming)**

Statistics/NN/LLM+ Logic Combinations

StarAI =
RelationalAI/Logic +
Learning + Statistics (1980s)

fusemate



NeSy =
Neural Networks + Symbolic Reasoning

Neural-Symbolic Learning and Reasoning:
A Survey and Interpretation

Tarek R. Besold et al
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TAREK-R.BESOLD@CITY.AC.UK

NeSy + StarAI ?

From Statistical Relational to Neural Symbolic
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DeepProbLog - see below

LLMs + Logic

Augmented Language Models: a Survey

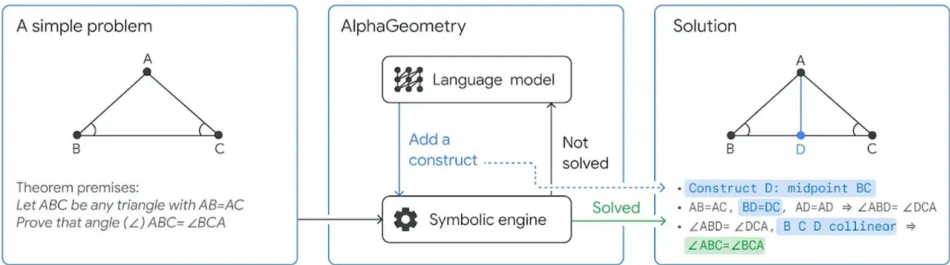
Grégoire Mialon* et al gmialon@meta.com

See below

Position: LLMs Can’t Plan,
But Can Help Planning in LLM-Modulo Frameworks

Subbarao Kambhampati¹ Karthik Valmeekam¹ Lin Guan¹ Mudit Verma¹ Kaya Stechly¹
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AlphaZero -> AlphaGeometry, AlphaProof

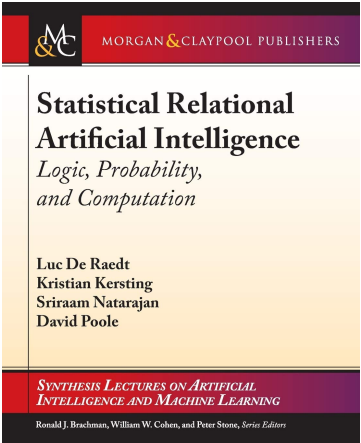


Lachlan’s PhD - “AlphaPhysics”

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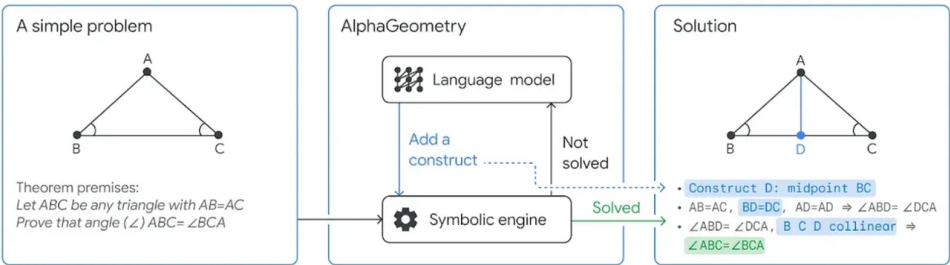
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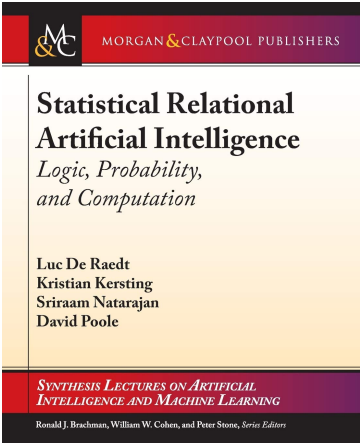


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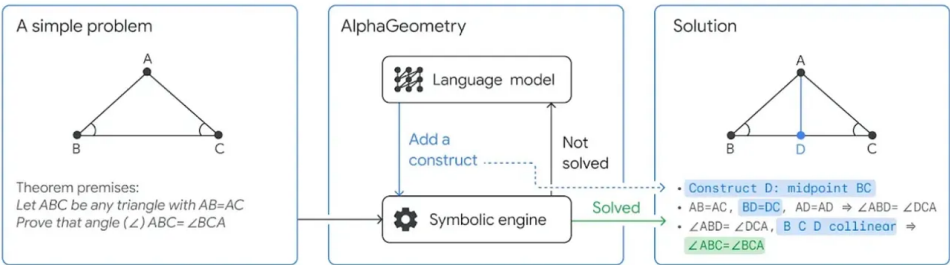
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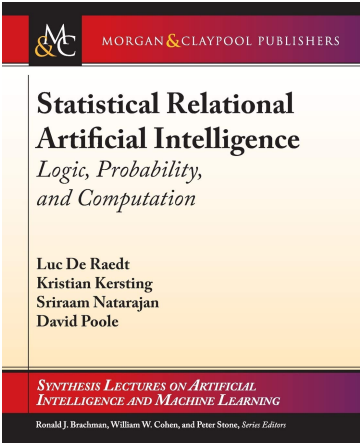


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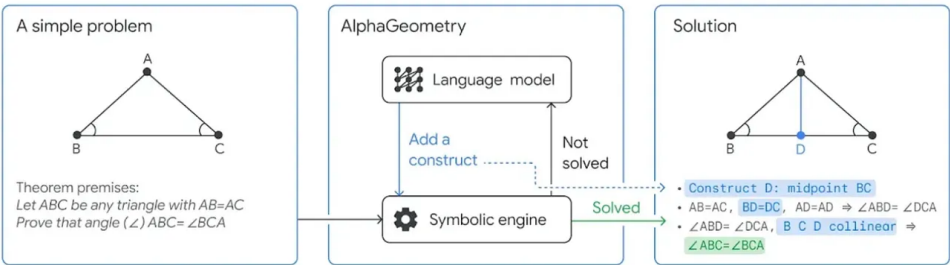
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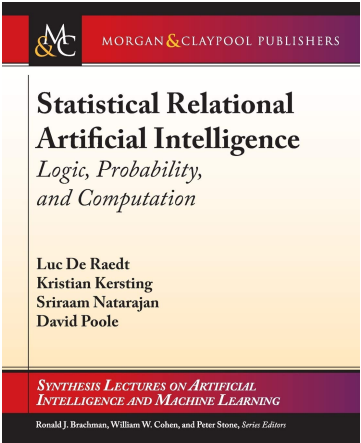


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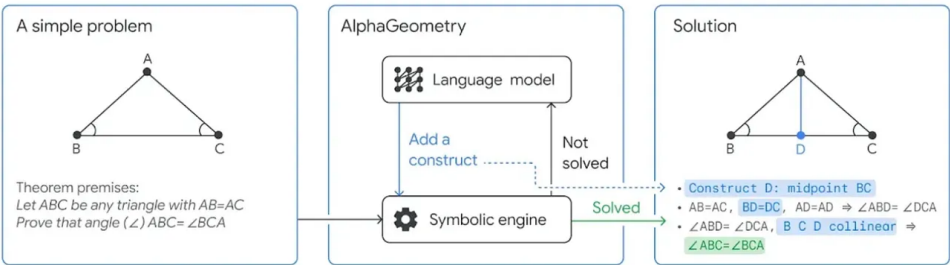
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LLM + Logic: LLMs Are Logic Reasoners?

Task LLM with Reasoning

ProntoQa [Saparov and He, 2023]

Synthetic Data

Varying redundancy (distractors)

Varying length of reasoning chains

Each composite number is not liquid. Every composite number is a fraction. Every composite number is a number. Negative numbers are not large. Every fraction is large. Each fraction is a real number. Fractions are integers. Integers are temperate. Each number is slow. Each even number is loud. Even numbers are natural numbers. Alex is an even number. Alex is a composite number.

True or false: Alex is large.

Prompt Engineering

In-prompt training one/view shot

Chain-of-thought “explain your reasoning”

Instruct LLM to use strategies

(backward/forward/SOS - own work)

Self-critique

Explainability?

LLM explanation can be nonsense

Correctness and Scalability?

More complex logic, e.g. quantifiers

Planning task, see Subbarao Kambhampati

Reasoning at all?

Or lookup?

LLM + Logic: Hierarchical Combination

Reliable Natural Language Understanding with Large Language Models and Answer Set Programming [Rajasekharan et al, ICLP 2023]

Example 3.1:

Question: Alan noticed that his toy car rolls **further** on a wood floor than on a thick carpet. This suggests that:

(world1: wood floor, world2: thick carpet)

(A) The carpet has **more resistance** (Solution)

(B) The floor has more resistance

Approach

- (1) LLM w/ fine tuning translates problem into logic programming query
- (2) Logic programming system answers query modulo background knowledge

<code>qplus(friction, heat).</code>	<code>qminus(friction, speed).</code>
<code>qplus(speed, distance).</code>	<code>qminus(distance, loudness).</code>
<code>positive(X, Y) :- qplus(X, Y).</code>	<code>negative(X, Y) :- qminus(X, Y).</code>
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<code>opposite_w(world1, world2).</code>	<code>opposite_v(higher, lower).</code>
<code>opposite_w(world2, world1).</code>	<code>opposite_v(lower, higher).</code>
<code>conc(P, V, W) :- obs(P, Vr, Wr), property(P),</code>	
<code> opposite_w(W, Wr), opposite_v(V, Vr).</code>	

`property(friction). property(heat). property(speed).`

Autocorrecting Translation Errors

Automated Theorem Provers Help Improve Large Language Model Reasoning [McGinness, B., LPAR 2024]

Each integer is not fruity.
Negative numbers are brown.
Wren is an integer.

LLM (wrong):

```
! [X] : (fruity(X) => integer(X))
integer(wren)
! [X] : integer(X)
brown(negative)
```

Auto-corrected:

```
! [X] : (fruity(X) => ~ integer(X))
integer(wren)
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Translation errors?

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Neural Networks + Symbolic Reasoning

DeepProbLog

Neural probabilistic logic programming in DeepProbLog
[Manhaeve et al, AIJ, 2021]

Inference

Query - does the following hold true?

addition(3, 5, 8)

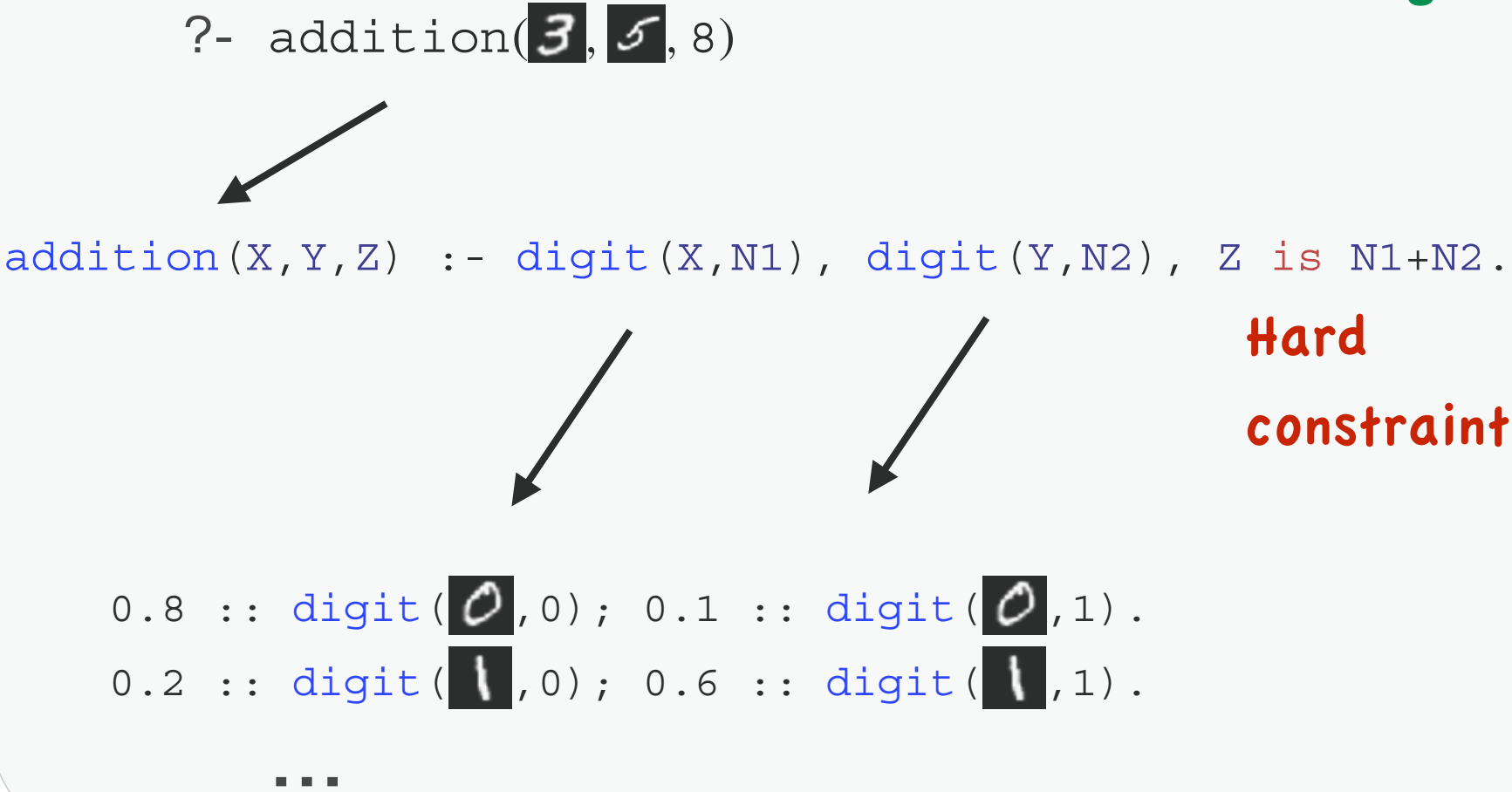
addition([3, 8], [2, 5], 63)

Use backward chaining with
NN classifier for probabilistic facts
Returns query probability

Learning

End-to-end differentiable
-> back propagation modulo background knowledge
Here: learns digit image classifier from addition examples

Backward Chaining



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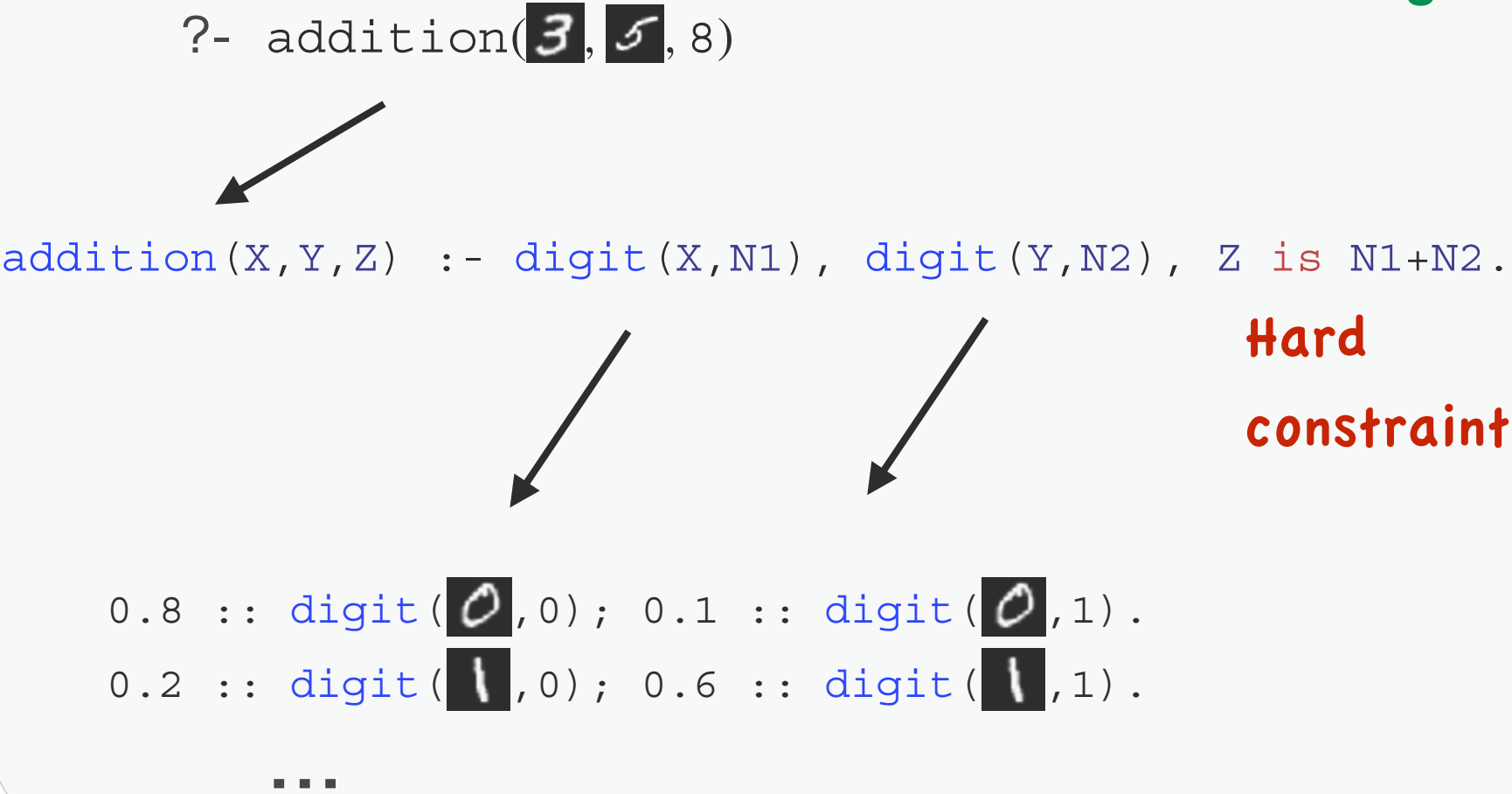
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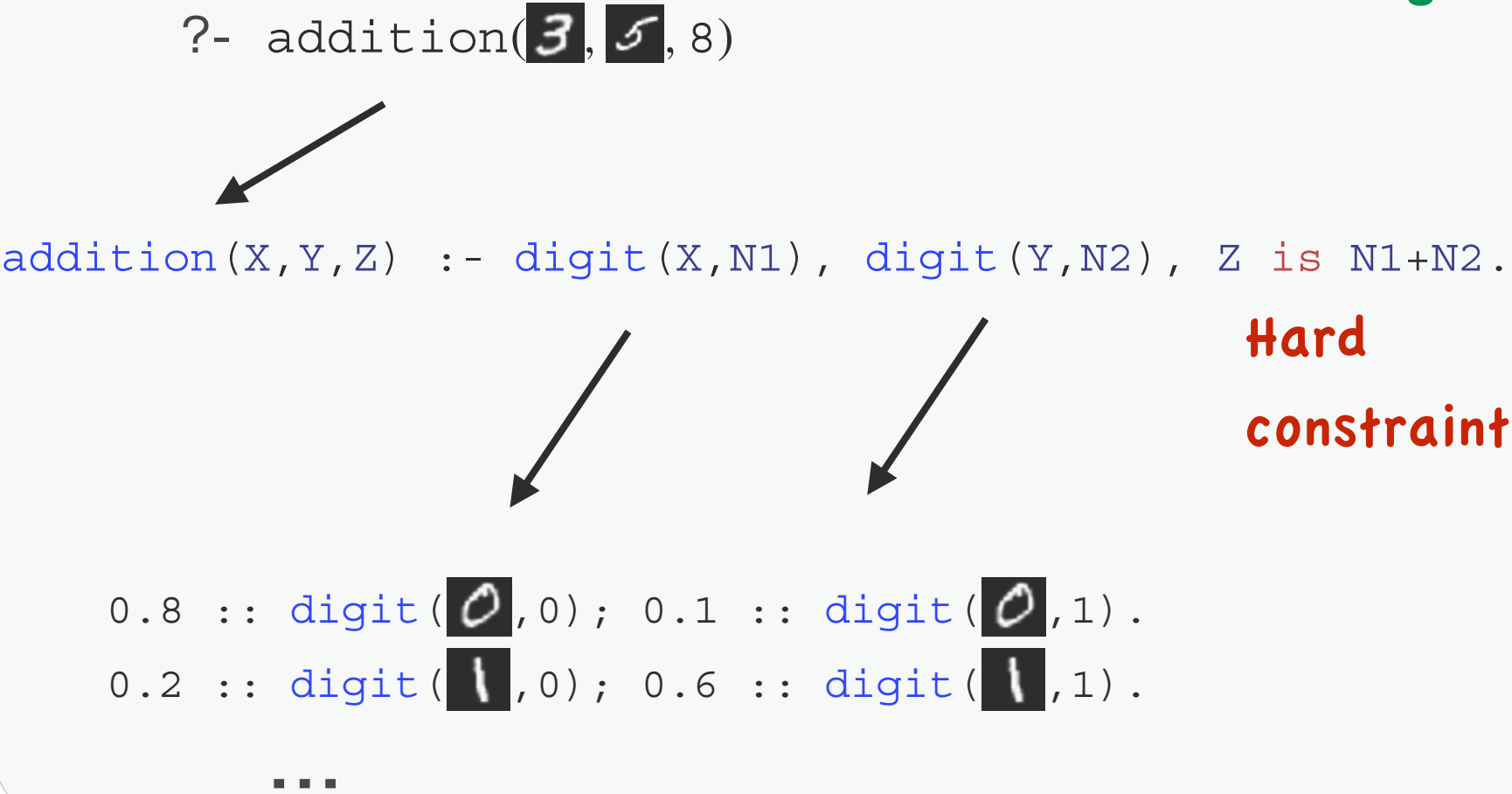
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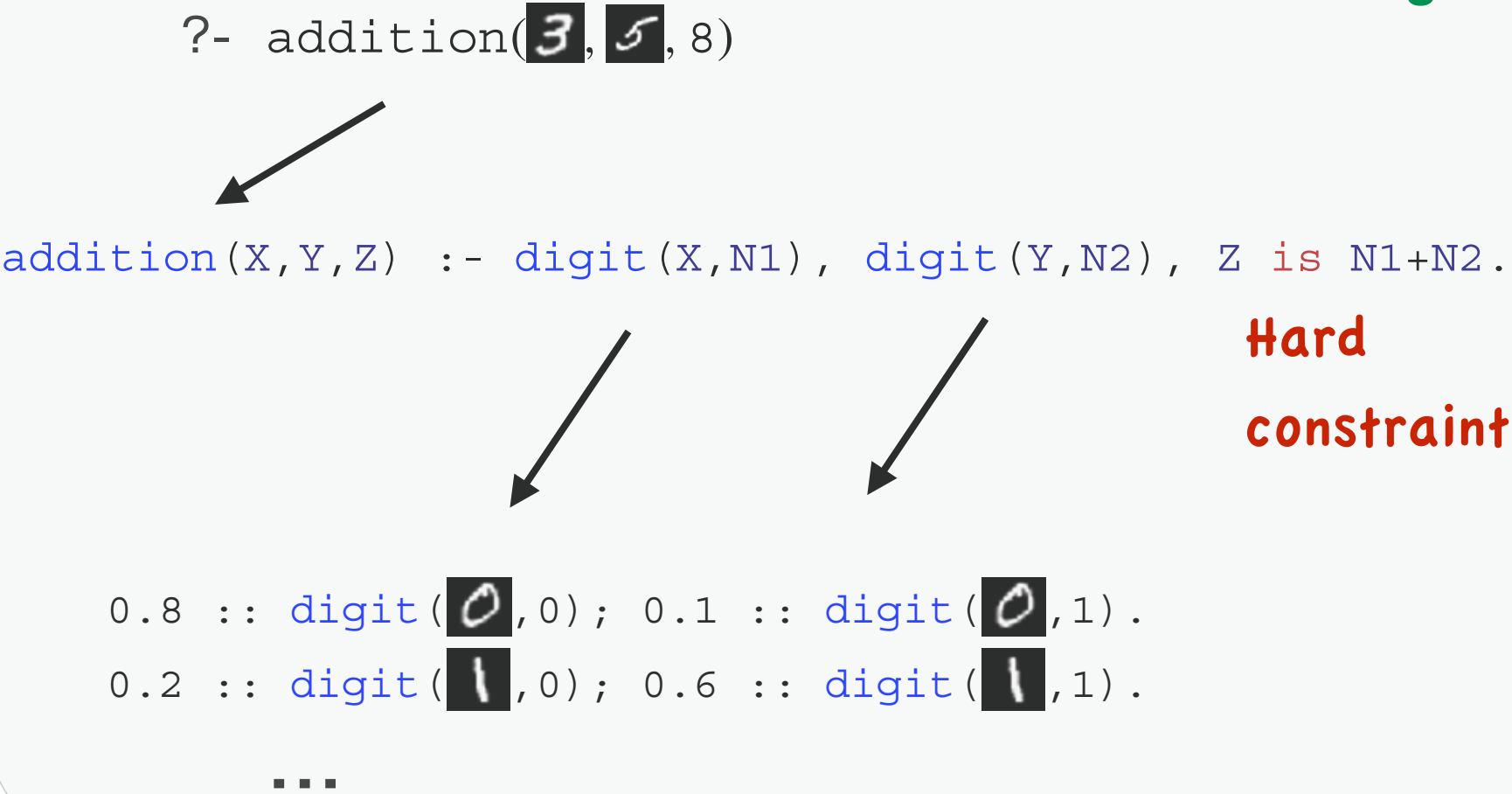
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?- addition(3, 5, 8)

addition(X, Y, Z) :- digit(X, N1), digit(Y, N2), Z is N1+N2.

Hard
constraint

0.8 :: digit(0, 0); 0.1 :: digit(0, 1).

0.2 :: digit(1, 0); 0.6 :: digit(1, 1).

...

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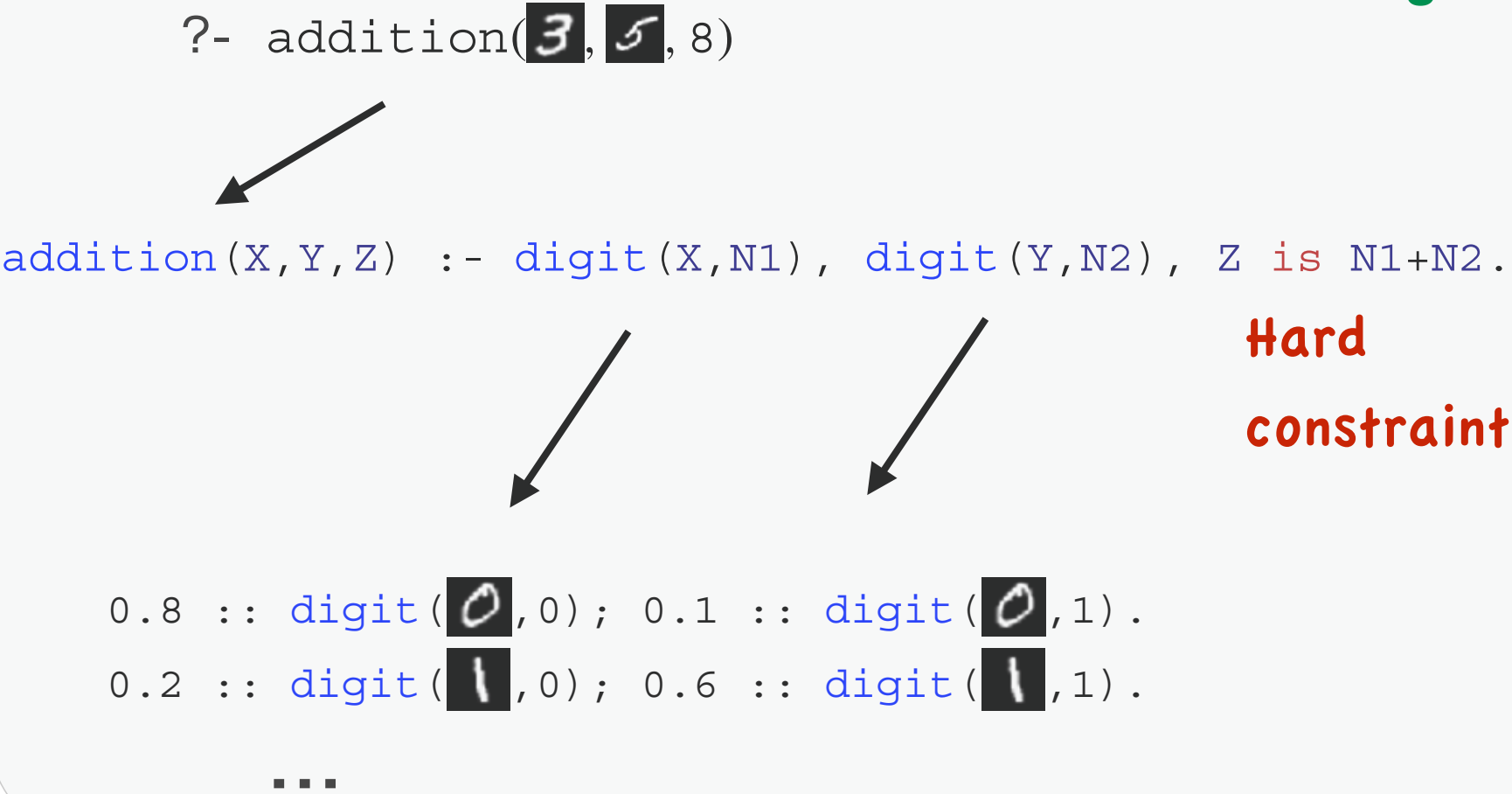
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“Strong” coupling
Counterpart LLM modulo?

Neural Networks + Smbolic Reasoning

Many More Architectures

- *Differentiable Theorem Proving* [Rocktäschel]

```
parentOf(HOMER, BART).  
grandfatherOf(X, Y) :- fatherOf(X, Z), parentOf(Z, Y).  
grandfatherOf(ABE, Q)? {Q/LISA}, {Q/BART}
```

Reasoning in embedding space:

Example: unify $\mathbf{v}_{\text{grandfatherOf}}(\mathbf{X}, \mathbf{v}_{\text{BART}})$ with $\mathbf{v}_{\text{grandpaOf}}(\mathbf{v}_{\text{ABE}}, \mathbf{v}_{\text{BART}})$

$$\Psi = \{\mathbf{X}/\mathbf{v}_{\text{ABE}}\}, \quad \tau = \min(e^{-\|\mathbf{v}_{\text{grandfatherOf}} - \mathbf{v}_{\text{grandpaOf}}\|_2}, e^{-\|\mathbf{v}_{\text{BART}} - \mathbf{v}_{\text{BART}}\|_2})$$

- *Semantic Probabilistic Layers for Neuro-Symbolic Learning* [Ahmed et al NeurIPS, 2022]
Logic constraints at the output layer, e.g. exclusivity constraints for classification
- *FFNSL: Feed-Forward Neural-Symbolic Learner* [Cunnington, Law, Lobo, Russo 2023]
- *Encodings of logic within NNs*
- *Logic Tensor Networks*
- *Neural Datalog over time*

Conclusions

Fusemate

- Probabilistic Logic Programming system
- Good
 - Expressivity, good Python interface, reasonably optimized for intended use case (HMM-ish)
- Needs work
 - Documentation, efficiency

LMM + Logic

- Current focus of research and D61 applications for “Explainability”
 - ML/LLM -> generate solution candidates
 - Probabilistic logic -> validate/complete solution candidates